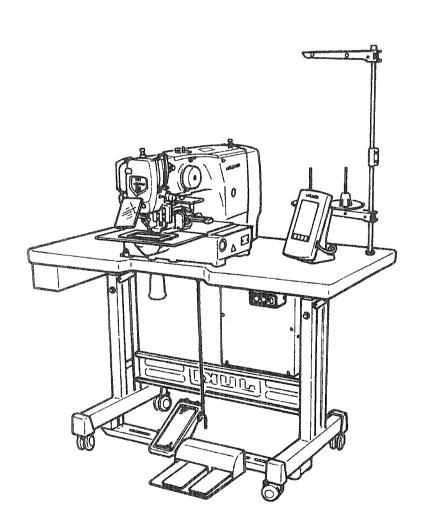


Computer-controlled, Cycle Machine With Input Function

AMS-210E

ENGINEER'S MANUAL



PREFACE

This Engineer's Manual is written for the technical personnel who are responsible for the service and maintenance of the machine.

The Instruction Manual for these machines intended for the maintenance personnel and operators at an apparel factory contains operating instruction in derail. And this manual describes "Standard Adjustment", "Adjustment Procedures", "Results of Improper Adjustment", and other important information which are not covered in the Instruction Manual.

It is advisable to use the Input Instruction Manual, relevant Instruction Manual and Parts List together with this Engineer's Manual when carrying out the maintenance of these machines.

In addition, for the motor for the sewing machine with thread trimmer, refer to the separate Instruction Manual or This manual gives the "Standard Adjustment" on the former page under which the most basic adjustment value is described, and on the latter page "Results if Improper Adjustment" under which stitching errors and troubles arising from mechanical failures and "Hoe to adjust" are described.

CONTENTS

-	. Specifications	2889	Section 2
2.	Configuration		a
	(1) Names of main unit		6=
	(2) IP-400 operation panel		2
	(3) CP-20 operation panel	8000	3
_			
3.	Standard adjustment		E-2
	(1) Main Shart connection/disconnection		
	(2) Removal of main shaft motor and coupling		
	(3) Crank rod connection/disconnection	9000	<i>[</i>
	(4) Crank balancer positioning	= 0 to 0 40	<i>⋑</i>
	(5) Adjustment of intermediate presser cam	 	. I
	(6) Adjustment of intermediate presser bar	n = = = = = = = = = = = = = = = = = = =	3
	(7) Intermediate presser variable connection /disconnection		J
	(8) Intermediate presser variable adjustments	1	5
	(9) Intermediate presser drivie arm	7	-
	(10) Lower shaft backlash adjustment and connection/disconnection	1	9
	(11) Oscillator gear positioning	2	1
	(12) Adjustment of hook oil amount	2	1
	(13) Shuttle connection / disconnection and all wints wints.	. 2	3
	(13) Shuttle connection / disconnection and oil wick piping	. 2	3
	(14) Adjusting the height of the needle bar	. 2	5
	(15) Hook adjustment	. 2	7
	(16) Thread trimmer presser lifter cam connection/disconnection	. 2	9
	(17) Thread trimmer and presser origin sensor adjustment	. 29	9
	(18) Adjusting the thread trimmer sensor	. 3	Samuel P.
	(19) Adjustment of the moving knife and counter knife position	. 3:	3
	(20) Floating amount of the thread tension disk	. 3:	3
	(21) Second thread tension connection / disconnection	. 34	5
	(22) AT unit connection / disconnection	. 37	7
	(23) Wiper adjustment	. 3	9
	(24) Adjusting the pre-load of the X-Y table	. 4	
	(25) Adjustment of the tension of the X timing belt	. 43	3
	(26) Adjustment to positions of X-motor and Y-motor (Backlash adjustment to gear)	. 43	3
	(27) Adjusting of the presser lower arm (Motor type only)	ΛE	-
	(28) Adjustment when the presser plate sheet is replaced (Motor type only)	45	5
	(29) Height of the slider and pasting of the presser plate sheet		
	(Pneumatic type only)	47	7
	(30) Adjusting the speed of the work clamp feet (Pneumatic type only)	AC	3
	(31) Making the origin setting gauge	51	1
	(32) Adjusting the X origin sensor	51]
	(33) Adjusting the Y origin sensor	E2	9
	(34) Adjustment of the bobbin winder driving wheel position	55	
	(33) Adjusting the bobbin winder amount	55	
	(36) Adjustment of the shuttle upper spring and lower thread holder position	57	7
	(37) Shuttle felt	57	,
	(38) Snape of the shuttle race ring	50	4
	(39) Adjustment of thread take-up spring	50)
	(40) Needle thread clamp device connection/disconnection	61	
	(41) Adjusting the needle thread clamp sensor	60	,
	(42) Adjusting the needle thread clamp notch	ge GE	

4.	Memory switch	
	(1) Start and change(2) Function list	
	(2) FUIICUOII IISt	3 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8
5.	Supplemental remarks of each function number and	
9 8	explanation of each function	. 92
	(1) Feeding frame operational sequence setup	92
	(2) Fixed refuge position setup	
	(3) Bank function setup	
	(4) Port I/O setup	
	(5) Simplified program setup	
	(6) Version display	126
	(7) Keylock setup	127
	(8) Communication screens of the maintenance personnel level (Program rewrite)	128
	(9) Information screen at the maintenance personnel level	
	(10) Test sewing function	
6.	Test mode	139
€P B	(1) Start (CP-20)	
	(2) Display output test (CP-20)	141
	(3) Method of confirmation according to each test program No. (CP-20)	142
	(4) For IP-400	
7.	Printed wiring board and dip switch	165
	(1) Various printed wiring boards	165
	(2) Dipswitch setting	173
8.	Table of exchanging gauge parts according to sewing specifications and	4 T) A
	needle size used	1/4
O	Option list	175
9 .	VPLIVII II 3 L. R. D. R. D. R. D. R. D. R. D. R. D. D. R. D.	u u 🥪
10	. Maintenance	181
	(1) Replacing the fuse	
	(2) Changing the voltage specification	
	(3) Greasing • lock-tight parts	
	(4) Parts to which grease • lock-tight is applied	
	(5) Replenishing the designated places with grease	
11	. Error code list	194
8 40		~~ 4
12	Troubles and corrective measures	
	(1) Mechanical parts	
	(2) Sewing conditions	
	(3) Electrical components	213
-1-0	Circuit diagrams	221
1 0	(1) Block diagram A	
	(2) Power supply circuit diagram A	
	(3) Power supply circuit diagram B	
	(4) Power supply circuit diagram C	
	(5) Servo motor circuit diagram	
	(6) Sensor-pedal circuit diagram	226
	(6) Sensor-pedal circuit diagram(7) MAIN•PANFI board circuit diagram	
	(7) MAIN-PANEL board circuit diagram	227
	(7) MAIN•PANEL board circuit diagram(8) Motor•solenoid circuit diagram	227 228
	(7) MAIN-PANEL board circuit diagram	227 228 229

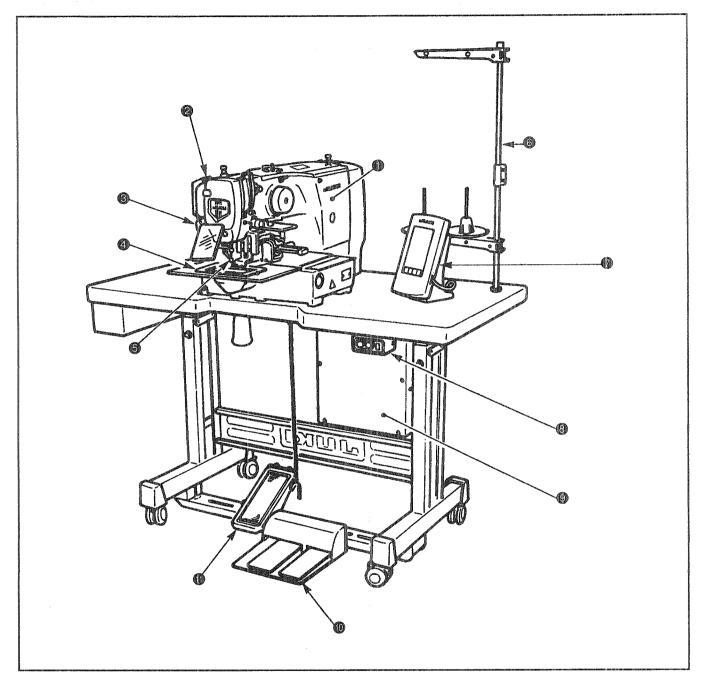
1. Specifications

No.	Model name				
TO THE COMPANY OF THE PARKS	Item	AMS-210EHS	AMS-210ESS	AMS-210EHL	AMS-210ESL
1	Sewing area	X-Direction	(right, left) 130mm; Y-	Direction (forward, back	ward) 60mm
2	Max. sewing speed			ng pitch is 3mm or less)	
3 Stitch length 0.1 to 12.7mm (Min. resolution : 0.				resolution : 0.05mm)	
4	Feed rnotion of feeding frame	in	termittent feed (2-shat	t drive by stepping moto	or)
5	Needle bar stroke			2mm	
6	Needle		S type: DP x 5 # 14	H type: DP x 17 # 18	
7	Method to lift feeding frame	Pulse			ir
8	Feeding frame shape	Right and	left united	Right and left separated	
9	Lift of feeding frame	Standard 25mm	n, Max. 30mm	Max. 3	
10	Intermediate presser stroke			m (0 to 10mm)	
11	Lift of intermediate presse	r			
12	Intermediate presser DOWN position variable	Standard 0 to 3.5mm (Max. 0 to 7.0mm)			
13	Needle thread clamp device	H type	S type	H type	S type
14	Needle thread tension	<u> </u>		ension control mechani	
15	Hook		2-fold semi-rot		3111)
16	Lubrication	Plane part: gre		volume lubrication (tar	ok type)
17	Lubricating oil			60 VG32) (Lubrication s	
18	Grease				,
19	Memory of pattern data	Penetration No. 2 lithium grease, 2. Templex N2, 3. Juki Grease A, 4. Juki Grease B (Caution)1. EEP-ROM, Smart media EEP-ROM: Max. 200 patterns (Max. 20,000 stitches/pattern) Smart media: Max. 200 patterns (Max. 50,000 stitches/pattern)			
20	Temporary stop facility	Smart media : Max. 999 patterns (Max. 50,000 stitches/pattern) Used to stop machine operation during a stitching cycle.			vole
21	Enlarging/Reducing function	Allows a pattern to be enlarged or reduced on the X axis Y axis independently when sewing a pattern. Scale: 1% to 400% times (0.1% steps)			
22	Enlarging/Reducing method	Pattern enlargement / reduction can be done by increasing / decreasing either stitch length or the number of stitches. (Only increase/decrease of stitch length when pattern button is selected and CP-20 is used)			
23	Sewing speed limitations				und 01 2010 d30d)
24	Pattern selector facility	200 to 2,700 rpm (Scale : 100 rpm steps) Pattern No. selection method (EEP-ROM : 1 to 200, Smart media : 1 to 999) (CP-20 is the scroll type.)			
25	No. of sheets counter			9,999) (IP-400 only)	
26	Sewing counter (Bobbin thread counter)		Up/Down meth		
27	Mernory back-up	In case of a power interruption, the pattern being used will automatically be stored in memory.			
28	2nd origin setting facility	Using jog keys, a 2nd origin (needle position after asewing cycle) can be set in the desired position within the sewing area. The set 2nd origin is also stored in memory. (IP-400 only)			
29	Sewing machine motor	Servomotor 550W			
30	External dimensions	1,200mm (W) x710mm (L) x 1.200mm (H) (Excluding thread stand)			
31	Weight (gross weight)	Machine head : 69kg, Control box : 16.5kg			
32	Power consumption	500VA			
33	Working temperature/humidity	Temperature: 5-35°C, Humidity: 35-85% (no condensation)			
34	Supply voltage/frequency		Rated voltage ±		anon)
35	Air pressure used		rialed voltage 1		AD- Mari Occide
36	Air consumption			Standard: 0.35 to 0.48	
37	Needle highest position stop facility	After the completion	if sewing, the needle	1.8dm³ /mi can be brought up to its	

(Caution) Grease type, refer to (3) Greasing • lock-tite parts of [10] Maintenance

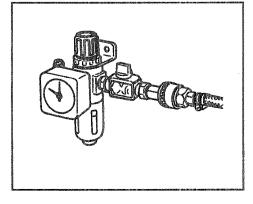
2. Configuration

(1) Names of main unit

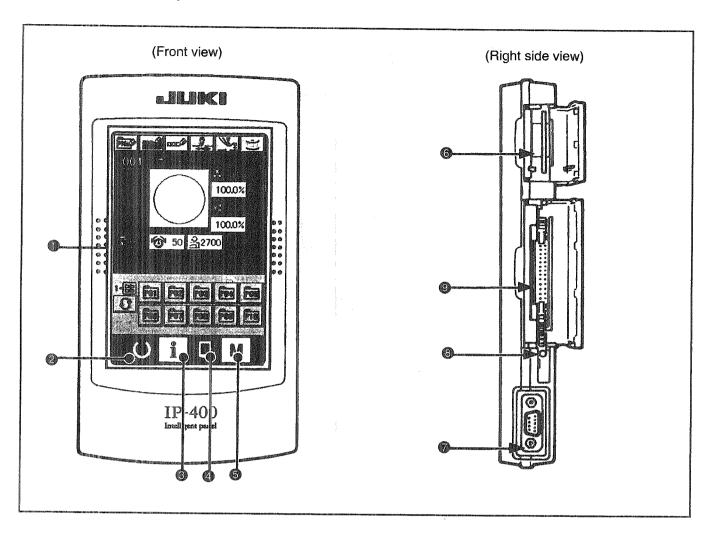


- Machine head
- Wiper switch
- Temporary stop switch
- Feeding frame
- 6 Intermediate presser
- Thread stand
- Operation panel (IP-400 or CP-20)
- O Power switch
- Control box
- Foot pedal
- Manual pedal (Excluding pneumatic type)

Air regulator (for pneumatic type only)



(2) IP-400 operation panel



- Touch panel LCD display section
- **e**
- READY key
- → Changeover of the data input screen and the sewing screen can be performed.

- **3**
- **INFORMATION** key
- ightarrow Changeover of the data input screen and the information screen can be performed.



COMMUNICATION key

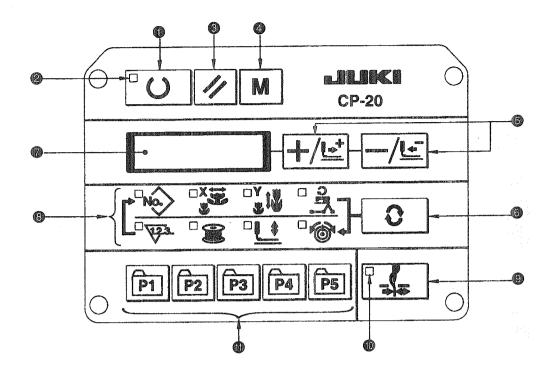
 \rightarrow Changeover of the data input screen and the communication screen can be performed.



MODE key

- → Changeover of the data input screen and the mode changeover screen which performs various detail settings can be performed.
- Smart media card slot (Close the cover for use.)
- Connector for RS-232C communication
- Variable resistor for color LCD → Screen contrast can be adjusted. Adjust it as you desire.
- © Connector for external input

(3) CP-20 operation panel



(f) "Ready" key

This key changes over the setting state from the panel to the sewing state where the sewing machine actually operates.

Sewing LED

This LED goes off at the time of setting state and lights up at the time of sewing state. Changeover can be performed with "Ready" key.

@ "Reset" key

This key is used for canceling error or returning the set value to the initial value.

@ "Mode" key

This key makes the setting mode of the memory switch.

"+ / Feed forward" key and "- / Feed backward" key

This key is used for changing pattern No. and X/Y scale, and feed forward/feed backward.

@ "Selection" key

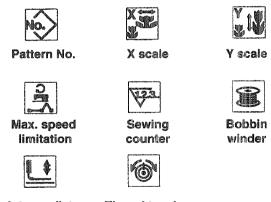
This key selects the item to be set. Item selection LED of the selected item and the set value are displayed.

Data indication LED

This LED indicates the set values of the selected items such as pattern No., X/Y scale, etc.

Item selection LED

LEDs of the selected items light up.



Intermediate presser height

Thread tension

Needle thread clamp ON/OFF key

This key selects effective/ineffective of needle thread clamp. When it is effective, needle thread clamp disply LED lights up.

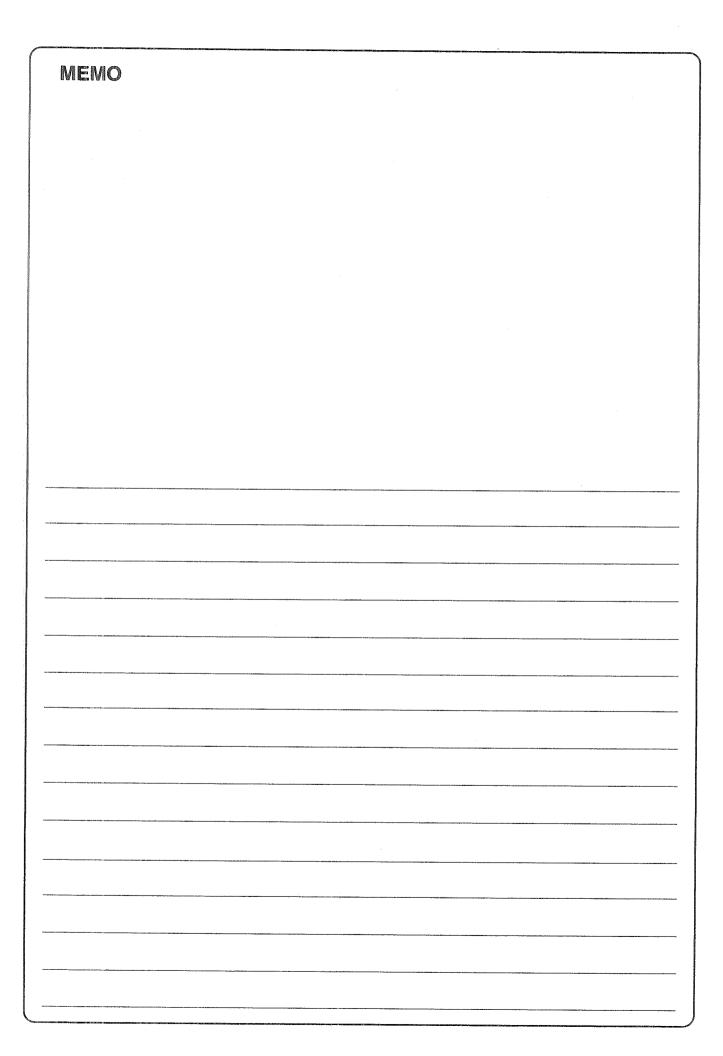
Needle thread clamp display LED

When this LED lights up, needle threas clamp operaters.

Pattern registration key

This key registers the pattern. When this key is pressed, the pattern registered here can sew immediately.

X/Y scale, sewing position. etc. can be changed and registered.



3. Standard adjustment

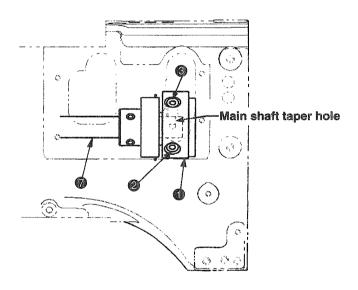
(1) Main shaft connection/disconnection

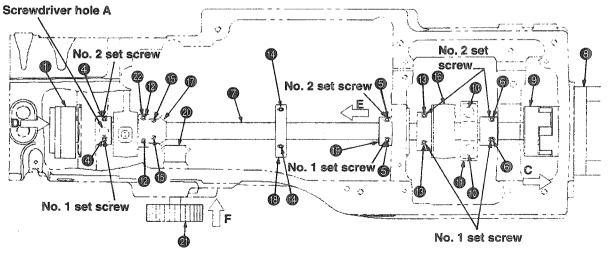
Procedures of disassembling

- 1. Loosen the set screw a securing the main shaft counterbalance and remove the taper screw so.
- 2. Loosen 2 set screws (4) (through the screwdriver hole A), 2 set screws (5), and 2 set screws (6).

 On this occasion, loosen No. 2 set screw first, and completely remove No. 1 set screw from the flat part of the main shaft (6).
- 3. Remove the main shaft motor **3**. Refer to "3.-(2) Removal of the main shaft motor and coupling".
- Loosen 2 set screws (1).
 On this occasion, be aware that the balancer (1) may rotate due to loosened set screws (1).
- 5. Loosen 2 set screws @.
- 6. Loosen 2 set screws **®**.

 On this occasion, completely remove No. 1 set screw of the set screws **®** from the flat part of the main shaft
- 7. Loosen 2 set screws @ and 2 set screws .
- 8. Pull out the main shaft n in the direction of Arrow C.





Procedures of assembling

- 1. Insert the main shaft into the crank rod , balancer , hand pulley gear A , bobbin winding drive wheel , and main shaft counterbalance in this order, and mount this assembly on the frame.
- 2. Tighten the taper screw (a) into the taper hole of the main shaft (b), and tighten the set screw (a) to secure the main shaft counterbalance (a).
- 3. Lightly press the main shaft counterbalance in the direction of Arrow D and the middle metal in the direction of Arrow E, and tighten 2 set screws .

 (Tighten No. 1 set screw so that it touches the flat part of the main shaft . Then, tighten No. 2 set screw.

Same procedure hereafter)

- 4. Tighten 2 set screws ♠ and 2 set screws ♠. (Make sure that No. 1 set screw touches the flat part of the main shaft ♠.)
- 5. Press the hand pulley in the direction of Arrow F to engage the hand pulley gear A with the hand pulley gear B and secure them with 2 set screws .
- 6. Mount the main shaft motor (3) and coupling (9). Refer to "3.-(2) Removal of main shaft motor and coupling".
- 7. Secure the eccentric cam of the intermediate presser with 2 set screws . Refer to "3.-(5) Adjustment of intermediate presser cam".
- 8. Secure the crank rod (with 2 set screws (Refer to "3.-(3) Crank rod connection/disconnection".

9. Secure the balancer with 2 set screws . Refer to "3.-(4) Crank balancer positioning".

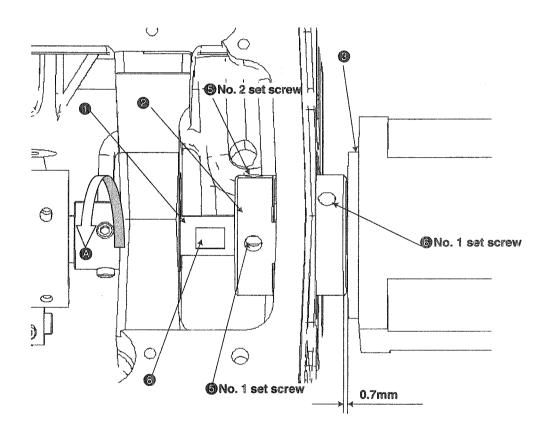
- 10. Secure the bobbin winding drive wheel (1) with 2 set screws (2). Refer to "3.-(34) Adjustment of the bobbin winder driveing wheel poition".
- * Make sure that no torque is applied by rotating the main shaft .

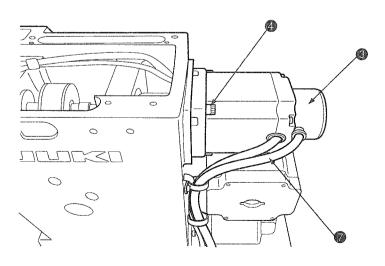
(2) Removal of main shaft motor and coupling

Procedures of disassembling

- For removal of the main shaft with the coupling, Loosen 2 set screws on the main shaft side of the coupling and remove 4 set screws securing the motor.
- 2. For removal of the coupling from the main shaft motor , loosen 2 set screws on the main shaft motor side.

(Caution) The screw (hole) that can be seen first is No. 1 set screw @ when the main shaft @ is turned in the forward direction @. For loosening, loosen No. 2 set screw first, and for tightening, tighten No. 1 set screw @ first.





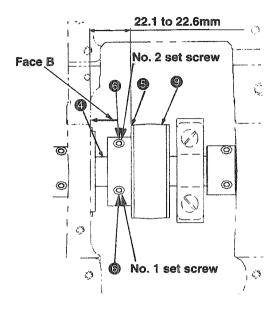
Procedures of assembling

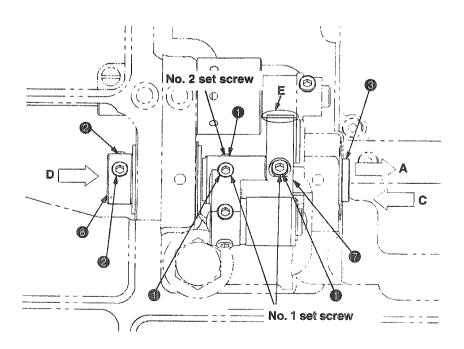
- 1. For mounting the main shaft motor with the coupling,
 - (1) Tighten 4 set screws ② that securing the motor, and tighten 2 set screws ③ on the main shaft side of the coupling ②.
 - (2) The cords of the main shaft motor should be positioned in the lateral direction.
- 2. For connecting the coupling to the main shaft motor,
 - (1) Provide a clearance of 0.7 mm between the coupling and main shaft motor .
 - (2) Apply No. 1 set screw 6 of the coupling 2 to the flat section 6 of the main shaft motor 6, the main shaft 6 and secure it.
- 3. For engaging the coupling,
 - (1) Position the set screw (3) (No. 1 set screw) on the main shaft motor side between 2 set screws (3) on the main shaft side, and engage the coupling.

(3) Crank rod connection/disconnection

Procedures of disassembling

- 1. Loosen 3 set screws and 2 set screws . On this occasion, loosen No. 2 set screws first, and completely disengage No. 1 set screws from the flat section of the oscillator shaft .
- 2. Pull out the oscillator shaft (3) in the direction of Arrow A.
- 3. Remove the main shaft @ according to "3.-(1) Main shaft connection/disconnection", and remove the crank rod unit @.





Procedures of assembling

- 1. Mount the main shaft @ according to "3.-(1) Main shaft connection/disconnection", and mount the crank rod unit @.
- 2. Adjust the clearance to 22.1 to 22.6 mm between the under cam 6 of the crank rod unit 9 and Face B (middle metal bearing mounting face) of the frame, and secure the cam with the set screw 6. (Apply No. 1 set screw to the flat section of the main shaft 4 and tighten it first, then tighten No. 2 set screw. Same procedure hereafter)
- 3. Pass the oscillator through the oscillator shaft and mount them on the frame.
- 4. Pass the thrust collar ③ through the oscillator shaft ⑥. Lightly press the oscillator shaft ⑥ in the direction of arrow C and the thrust collar ⑤ in the direction of Arrow D, and tighten 2 set screws ②. Make sure that No. 1 set screw touches the flat section of the oscillator shaft ⑥.)
- 5. Secure the oscillator according to "3.-(11) Oscillator gear positioning".
- (Caution) 1. Make sure that no torque is applied by rotating the main shaft .
 - 2. When the crank rod unit (a) is connected, disconnected, or positioned, or the oscillator (b) is positioned, be sure to grease two specified positions and the gear section (E) of the oscillator (a).
 - 3. After positioning the crank rod unit (under cam ()), be sure to perform "3.-(11) Oscillator gear positioning". Wrong positioning of the under cam () or oscillator () may cause frictional wear or lock-up.

(4) Crank balancer positioning

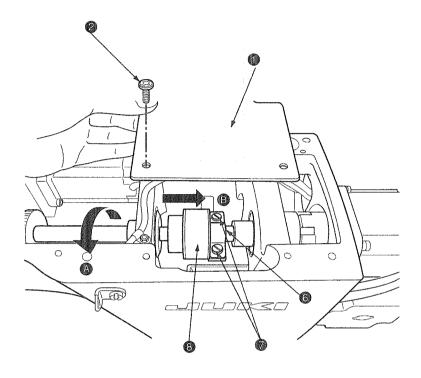
Standard Adjustment

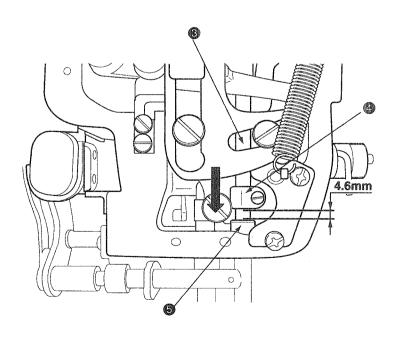
[Rotating direction]

When the needle bar 6 lowers and the clearance between the needle bar connecting 6 and needle bar lower bushing 6 is 4.6 mm, 2 set screws 6 of the crank balancer 6 becomes horizontal position.

[Axial direction]

Bring the main shaft eccentric cam (a) into contact with the crank balancer (b).





Adjustment Procedures

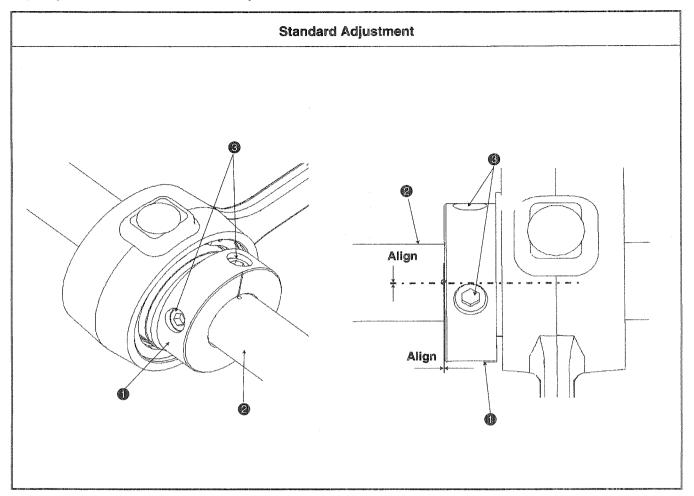
If the main shaft eccentric cam (3) is not secured, the main shaft eccentric cam (3) should be positioned first.

- 1. Loosen 2 set screws a securing the crank balancer a.
- 2. Remove 4 set screws , then remove the crank rod cover .
- 3. Turn the main shaft in the forward direction (a) so that the needle bar (b) lowers and the clearance between the needle bar connecting (a) and needle bar lower bushing (a) is 4.6 mm.
- 4. Secure the crank balancer (6) with 2 set screws (7) under the conditions that 2 set screws (7) securing the balancer (6) are horizontally positioned and the balancer (6) is moved in the direction of Arrow (8) to make it into contact with the main shaft eccentric cam (8). For tightening 2 set screws (7), tighten them alternately.

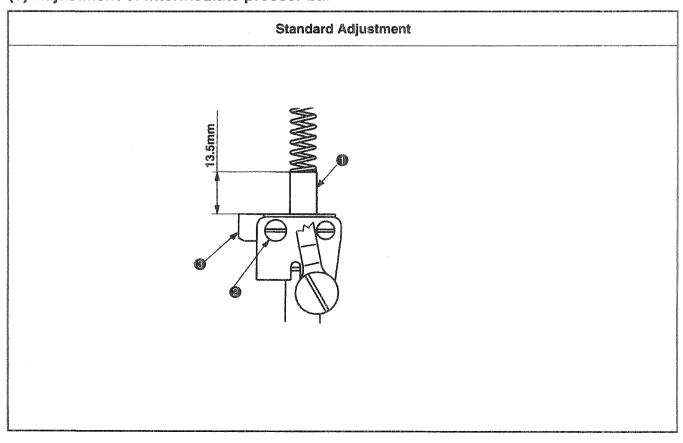
Results of Improper Adjustment

- o If the mounting angle of the crank balancer (6) is wrong, vibration during sewing will be intensified.
- If the sewing machine is used for a long time under the condition of wrong securing position, the life of main shaft bearing may be shortened.
- o If the crank balancer (a) is not moved in the direction of Arrow (b), it may interfere with the sewing machine frame.

(5) Adjustment of intermediate presser cam



(6) Adjustment of intermediate presser bar



Adjustment Procedures	stitch may occur.	
1. Align the edge of the intermediate presser cam with the center of the engraved point on the main shaft , align the engraved line on the intermediate presser cam with the engraved point on the main shaft , and tighten the set screw .		

Adjustment Procedures	Results of Improper Adjustment
1. Adjust the thrusting distance of the intermediate presser bar 13.5 mrn, and tighten the set screw after ensuring that the needle passes through the center of the intermediate pressure. (Caution) Be aware that the tightening pressure of the set screw should be from 2.16 to 2.75 N·m (22 to 28 kgf·cm).	o An excessive thrusting distance of the intermediate presser bar may damage the intermediate presser spring or cause poor presser lifting. o Excessive tightening pressure may deform the intermediate pressure bar or intermediate presser bar connecting resulting in malfunction.

(7) Intermediate presser variable connection/disconnection

Procedures of disassembling

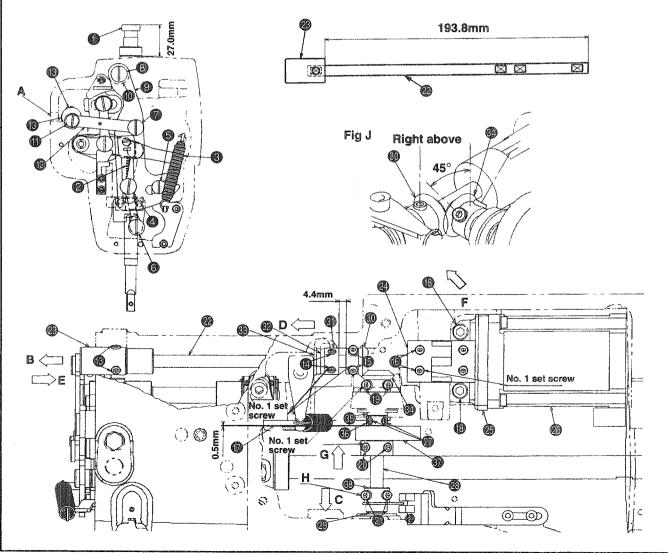
- 1. Remove the presser adjusting screw . Then, remove the intermediate presser spring and the guide shaft.
- 2. Remove the intermediate presser auxiliary spring .
- 3. Remove the step screws (a), (5), and (6).
- Remove the step screw .
- 5. Remove the step screw (a), and then the intermediate presser variable plate (a) and the variable plate spacer (a).
- 6. Remove the step screw (1), and then the intermediate presser variable link (2).

 (At that time, insert a hexagonal wrench through the arm screw hole A and apply it to the setscrew (3) as a means of turn stop for the intermediate presser variable arm (2).)
- 7. Loosen two each of the setscrews (a), (b), and (b).

 At that time, the second screw should be loosened first. The first screw of the setscrew should be removed, completely separate from the flat part of the intermediate presser variable shaft (a).
- 8. After the intermediate presser variable arm and the intermediate presser variable shaft have been pulled out in the direction of the Arrow B, loosen the setscrew and pull out the intermediate presser variable shaft from the intermediate presser variable arm.

At that time, both of the setscrews (8) should be separated completely from the flat parts (2 positions) of the intermediate presser variable shaft (2).

- 9. Loosen the two setscrews (1) and remove the intermediate presser coupling (2), the intermediate presser motor mounting plate (2), and the intermediate presser motor (3).
- 10. Loosen two each of the setscrews (1), (2), (2) and (2). At that time, the second screws of the setscrews (1) and (2) should be loosened first. The first screw of the setscrew should be removed, completely separate from the flat part of the intermediate presser lifting shaft (2).
- 11. Remove the E ring @ and pull out the intermediate presser lifting shaft @ in the direction of the Arrow C.



Procedures of assembling

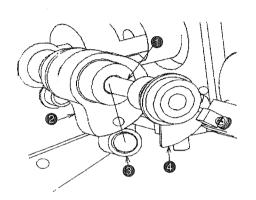
- 1. Fix the intermediate presser variable shaft ② to the intermediate presser variable arm ③ by means of the two setscrews ⑥ so that the length of the shaft section becomes 193.8mm.

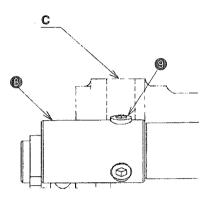
 (Both setscrews ⑥ should be adjusted level to the intermediate presser variable shaft ②.)
- 2. Insert the washer ③, thrust bearing ②, thrust collar ⑤, and the drive bevel gear ⑥ in the intermediate presser variable shaft ② in this order, and mount this assembly on the frame.
- 3. Pressing the intermediate presser variable arm @ in the direction of the Arrow E, secure a proper thrust by pressing the thrust collar @ in the direction of the Arrow D and tighten the two setscrews @. (Tighten the first screw first so that it is fixed level to the intermediate presser variable shaft @. Then, tighten the second screw. To be done in the same manner hereafter.)
- (Caution) If there is rattle in the variable shaft of the intermediate presser @ in the forward and backward directions, this can be a cause of intermediate presser step-out. Be careful when you try to fix the thrust collar .
- 4. Adjust the distance to 4.4mm between the thrust collar **3** and the drive bevel gear **3**. Tighten the first screw of the setscrew **3**.
 - (Tentatively tightened till the completion of intermediate presser sensor adjustments)
- 5. Fix the intermediate presser motor ® to the intermediate presser motor mounting plate ® and mount the intermediate presser coupling ® on the motor shaft. Since then, press the intermediate presser motor assembly in the direction of the Arrow F and tentatively fix it to the frame by means of the two setscrews ®. Adjust the positioning of the intermediate presser motor assembly where the intermediate presser coupling ®) can be turned without any resistance, and tighten the two setscrews ®.
- 6. Insert the sensor slit (a), intermediate presser lifting cam (a), thrust collar (b), and the wave washer (b) in the intermediate presser lifting shaft (a) in this order, and pass this assembly through the frame. Mount the E ring (a) on the intermediate presser lifting shaft (a).
- 7. Pressing the intermediate presser lifting shaft ② in the direction of the Arrow C, press the thrust collar ③ in the direction of the Arrow G and tighten the two setscrews ②.
- 8. Fix the intermediate presser lifting cam by means of the two setscrews so that the clearance becomes 0.5mm between both end planes of the intermediate presser lifting cam and the intermediate presser lifting link .
- 9. Turn the intermediate presser variable shaft @ and the intermediate presser lifting shaft @ so that the trailing bevel gear @ and the drive bevel gear @ are positioned as shown in Fig. J. Since then, fix them by means of the two setscrews @ while the trailing bevel gear @ is pressed in the direction of the Arrow G (in order to reduce the backlash to zero).
- 10. Press the sensor slit (3) in the direction of the Arrow C and turn the setscrew (3) so that its H comes in the section toward the setscrew (3) of the intermediate presser lifting cam (3). Then, fix H of the setscrew (3) tentatively.
- 11. According to adjustments of intermediate presser variable as described in 3-(8), make adjustments of intermediate presser variable and fasten the setscrews of the drive bevel gear ② and the sensor slit ③.
- 12. Using the step screw (1), mount the intermediate presser variable link (2) on the intermediate presser variable arm (3).
- 13. Using the step screw (a), mount the intermediate presser variable plate (a) and the variable plate spacer (a).
- 14. Mount the step screws (a), (5), and (6).
- 15. Using the step screw , mount the intermediate presser variable link on the intermediate presser variable plate .
- 16. Mount the intermediate presser auxiliary spring .
- 17. Mount the intermediate presser spring ② and the guide shaft from above the frame. Then, mount the presser adjusting screw ③.
 - (27.0mm from the upper plane of the arm to that of the presser adjusting screw)

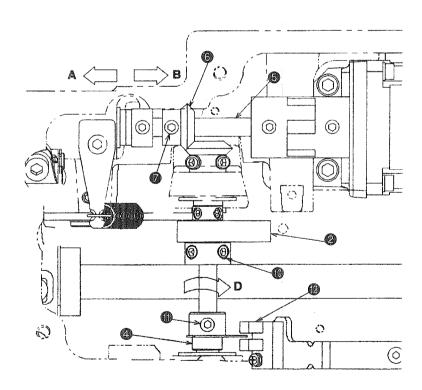
(8) Intermediate presser variable adjustments

Standard Adjustment

Start the Test Mode I10 (IP-400) or CP-8 (CP-20) and press twice after the completion of origin retrieval. At that time, there shall be coincidence between the center of the arm's left-side hole C and the second screw of the intermediate presser variable arm .







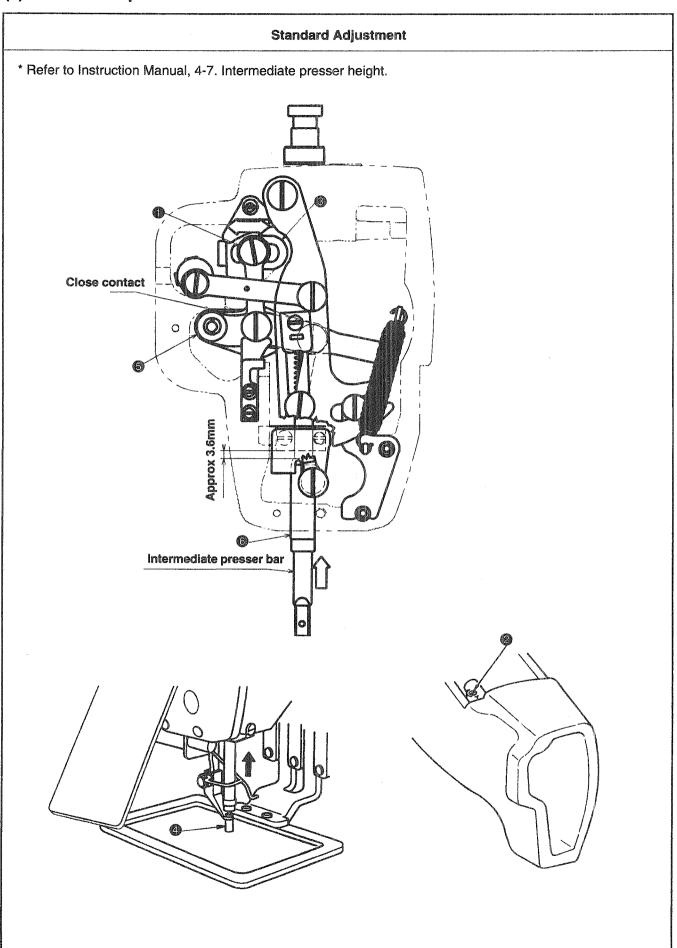
Adjustment Procedures

- 1. Start the Test Mode I10 (IP-400) or CP-8 (CP-20).
- 2. Tread on the start pedal for origin retrieval, and make adjustments by turning the sensor slit so that the lines combining the center of the intermediate presser lifting shaft , the standard hole of the intermediate presser lifting cam , and the center of the cam follower become almost a straight line.
- 3. Press of the panel three times. Loosen the first screw of the drive bevel gear of the intermediate presser variable shaft and move it in the direction of the Arrow A.
- 4. Using the [+] key or the [-] key, turn the intermediate presser variable shaft (a) until the second screw (a) of the intermediate presser variable arm (a) settles in the center of the arm's left-side hole C. (Insert a hexagonal wrench to adjust positioning so that the arm comes in the center of backlash deflection.)
- 5. Turn the intermediate presser lifting shaft so that the second screw of the intermediate presser lifting cam comes just above. Press the drive bevel gear fo the intermediate presser variable shaft in the direction of the Arrow B to fix it.
- 6. After the completion of second origin retrieval, press of the panel twice to secure the [timing adjustment position]. In this case, confirm that the second screw of the intermediate presser variable arm of is positioned in the center of the arm's left-side hole C or below it. (If the screw seems to have been positioned above the center, return to Step 4 and repeat the above-mentioned adjustments.)
- 7. If the second screw (a) of the intermediate presser variable arm (a) is not positioned in the center (or lower), loosen the setscrew (a) of the sensor slit (a) and turn this sensor slit (a) in the direction of the Arrow A for fine adjustments.
- 8. Make origin retrieval and confirm that the the cam follower so is located in the parallel section of the intermediate presser lifting cam
 a. When the condition has been found normal, fasten the setscrew of the drive bevel gear of and the setscrew of the sensor slit regularly.
- (Caution) For the prevention of the sensor @ from destruction, make origin retrieval after confirming that the slit of the sensor slit @ is positioned in the center of the sensor @.

Results of Improper Adjustment

- o There will be a displacement between the variable value of the intermediate presser lower position and the panel setup value.
- o If there is no cam follower (a) in the parallel section of the intermediate presser lifting cam (a) at the time of origin retrieval, stepping out may occur in the intermediate presser motor, thus causing defective stitches, generation of sound from the face plate section, and destruction of parts.
- o If adjustments of backlash are insufficient for the drive bevel gear , stepping out may occur in the intermediate presser motor, thus causing defective stitches, generation of sound from the face plate section, and destruction of parts.

(9) Intermediate presser drive arm



Adjustment Procedures

- 1. Turn ON the power supply and set the height of the intermediate presser (a) to 0mm. Turn OFF the power supply in the state that the intermediate presser (a) has been lowered.
- 2. Loosen the intermediate presser stroke adjusting screw ①.
- 3. Turn the pulley and move the needle bar to the lower dead point. When the intermediate presser is lifted and the intermediate presser stroke adjusting screw is moved to the right or left, confirm that the intermediate presser adjusting arm is positioned not to move vertically and that the intermediate presser positioning link is keeps a close contact with the arm. In this state, tighten the setscrew of the intermediate presser drive arm.

(The clearance is approximately 3.6mm between the intermediate presser needle bar connection and the intermediate presser bar metal (6).)

- 4. After the setscrew has been tightened, confirm that there is no backlash in the intermediate presser adjusting arm in the forward and backward directions.
- 5. Finally, make adjustments of the intermediate presser stroke. (Refer to Instruction Manual III. MAINTENANCE OF SAWING MACHINE, 1-4. Adjusting the vertical stroke of the intermediate presser.)

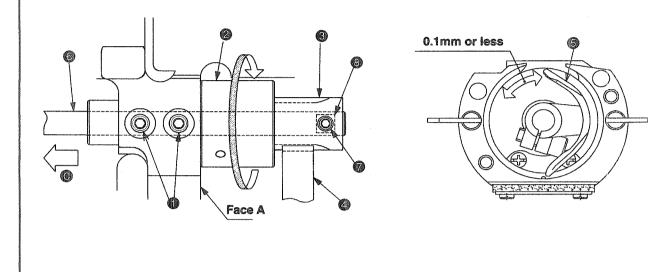
Results of Improper Adjustment

- o If there is no clearance, there will be interference between the intermediate presser bar metal and the intermediate presser needle bar connection during sewing machine operation, and this will generate abnormal sound as a result.
- o If there is too much clearance, there will be interference between the intermediate presser adjusting arm (a) and the arm during sewing machine operation, thus generating abnormal sound as a result.
- o If there is too much or too less clearance, the lower dead-point height of the intermediate presser
 may be changed as a result of intermediate presser stroke adjustments.

(10) Lower shaft backlash adjustment and connection/disconnection

Standard Adjustment

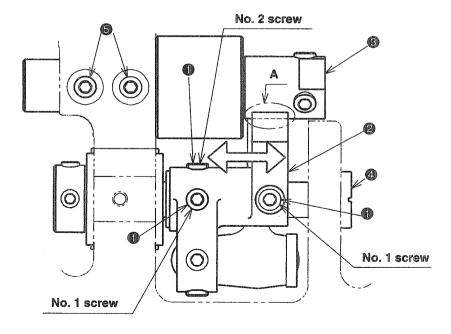
- 1. Size of lower shaft backlash is 0.1mm at the tip of the driver **6**. The shaft is required to rotate smoothly.
- 2. Define the stop position of the lower shaft 6 so that the set screw settles almost in the center of the flat section 6 of the lower shaft 6.



(11) Oscillator gear positioning

Standard Adjustment

1. When the oscillator is lightly swung by a finger in the direction of the arrow, the oscillator ② is fixed in the center position of swinging.



Adjustment Procedures

- 1. Lower shaft backlash
 - 1) Loosen the two set screws (1).
 - 2) Turn the lower shaft rear metal ② in the direction of the arrow and adjust the backlash, keeping the metal to contact closely with Face A. Size of backlash is 0.1mm at the tip of the driver ⑤. The shaft is required to rotate smoothly.
 - 3) Tighten the two set screws 1.

(Caution) When eliminate the backlash, the direction of rotation should always be kept in the direction of the arrow.

- 2. Lower shaft connection/disconnection
 - 1) Loosen the two set screws .
 - The lower shaft are can be taken out if it is pulled in the direction of the arrow.
 - 3) When mounting the lower shaft (a), insert it in the lower shaft rear metal (a) and the lower shaft gear (a). Apply one of the set screws (b) to the flat section (a) of the lower shaft (b) and tighten it approximately in the center. Tighten the remaining set screw (a).
- * Connection and disconnection of the lower shaft become easy if the above-mentioned backlash has been relieved in advance. In this case, backlash adjustment must be done after the lower shaft has been installed.

Results of Improper Adjustment

- o If the backlash is excessive, the hook noise will be increased.
- o If backlash is too small, the lower shaft gear ③ or the oscillator ④ will give rise to frictional wear. In addition, this can be a cause of crank rod lock-up.
- o If the front or rear position of the lower shaft rear metal (2) is displaced at the time of backlash adjustment, this can also be a cause of the lock-up of oscillator (3) or the crank rod.

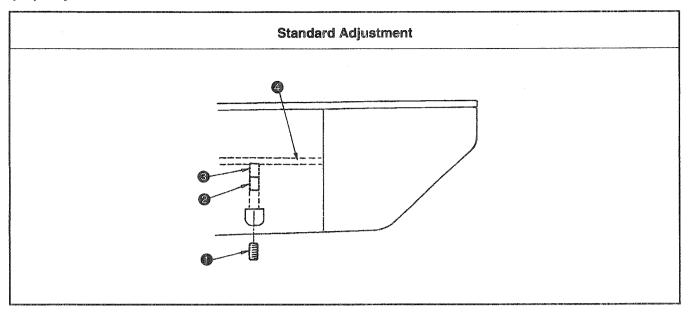
Adjustment Procedures

- 1. Loosen the two set screws 6 and increase the backlash of the lower shaft gear 6.
- (Caution) 1. If the lower shaft gear (3) has insufficient backlash, the oscillator (2) does not swing correctly. In such a case, refer to [(10) Lower shaft backlash adjustment and connection/disconnection] and provide a sufficient backlash.
- 2. The three set screws should have been loosened in advance. In this case, the second screw of the set screws should be loosened first. Then, the first one can be loosened.
- 3. Lightly swing the whole body of the oscillator ② with a finger in the direction of the arrow. Decide the positioning of the oscillator ② so that it stays in the center of swinging.
- 4. Loosen the three set screws and then fix them so that the oscillator is not displaced from the center of swinging. (Tighten the first screw first so that it comes in contact flatly with the oscillator shaft . Then, tighten the second one.)
- 5. Make backlash adjustment for the lower shaft gear ②, according to [(10) Lower shaft backlash adjustment and connection/ disconnection].
- (Cautions) 1. In the case of disassembly and adjustment, greaseup treatment is always needed for the specified places (2 positions) and the gear area A of the oscillator ②.
 - When the crank rod (under-cam) is removed, actions for under-cam positioning must be taken, without fail. Refer to [(3) Crank rod connection/ disconnection].

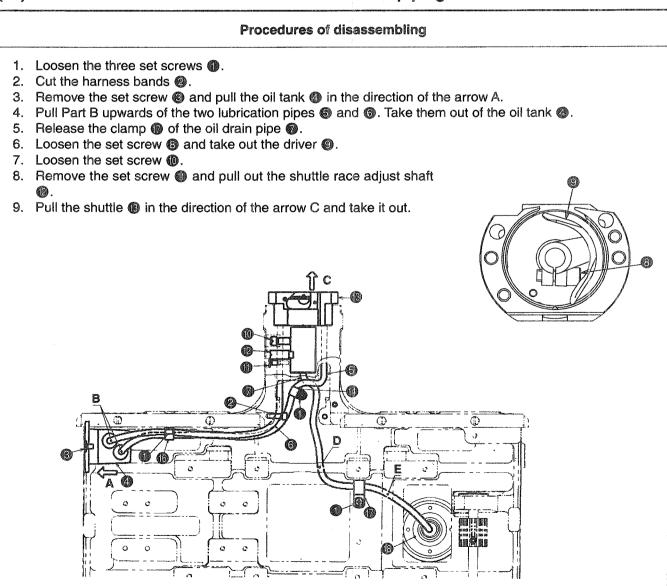
Results of Improper Adjustment

o If the position for fixing the oscillator (2) is inadequate, this can also be a cause of the frictional wear or lock-up of the oscillator pin, crank rod lid, undercam, and the crank rod.

(12) Adjustment of hook oil amount



(13) Shuttle connection / disconnection and oil wick piping



Adjustment Procedures	Results of Improper Adjustment
 Loosen the set screw and remove it. When the adjusting screw is tightened, the quantity of oil can be regulated for the lubrication pipe left. After adjustments, tighten the set screw to fix it. 	o If the amount of hook lubricant is reduced too much, this can be a cause of frictional wear of the hook race plane or lock-up.
 (Cautions) 1. In the state of standard shipping, the hook lubrication reducer (3) is positioned so that it is lightly tightened and then return-loosened by 4 turns. 2. When reducing the oil amount, the screw should not be tightened up fully. Tighten the hook lubrication reducer (3) and then return it by two turns. In this position, wait for half a day to see how it goes. Too much reduction can be a cause of hook wear. 	

Procedures of assembling

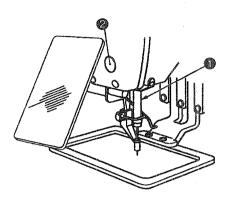
- 1. Pass the two lubrication pipes 6 and 6 and the oil drain pipe 1 through the frame, and mount the shuttle 6.
- 2. Pass the lubrication pipe (a) along the upper side of the oil drain pipe (a). Hold the lubrication pipe (b) with the pipe holder (b) and fix it with the set screw (d).

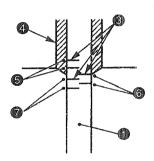
 At that time, make sure not to let the lubrication pipe (b) and the oil drain pipe (c) come in contact with the thread cutter connector rod and the lower shaft.
- 3. Fix the lubrication pipe (a) to the bed by means of the harness band (a).
- 4. Fix the two lubrication pipes 6 and 6 with the cord clamps 6 and the set screws 6.

 At that time, make sure not to permit the lubrication pipes 6 and 6 to come in contact with the needle thread clamp connector link.
- 5. Insert the two lubrication pipes 6 and 6 in the oil tank 4 and fix this oil tank 4 to the frame with the set screws 6.
- 6. Fix the needle thread clamp sensor cord and the oil drain pipe with the cord clamp . At that time, pass the oil drain pipe through the head holes in two positions D and E.
- 7. Insert the oil drain pipe on in the oil reservoir .
- 8. Fix the shuttle (a) and mount the driver (a) with the set screw (b). Refer to [(15) Hook adjustment].
- * Harness bands @ : Part No. EA9500B0100

(14) Adjusting the height of the needle bar

Standard Adjustment



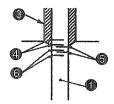


- 6 : Marker line for DP x 5
- (with needle count higher than #22)
- Marker line for DP x 17 (with needle count lower than #22)

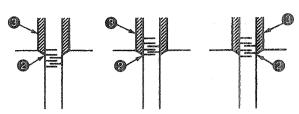
Adjustment Procedures	Results of Improper Adjustmen
Turn ON the power once, and turn OFF the power again after making the intermediate presser in the lowered state. I. Bring the needle bar (1) down to the lowest position, loosen the needle bar connection screw (2) and align the upper engraved line (3) on the needle bar with the bottom end of the needle bar lower bushing (4). Change the adjusting position according to needle sizes.	
Caution) Be sure that torque is even after adjustment.	

(15) Hook adjustment

Standard Adjustment



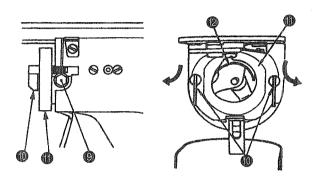
- @: Marker line for DP x 5 needle
- 6: Marker line for DP x 17 needle (with needle count higher than #22)
- 6: Marker line for DP x 17 needle (with needle count lower than #22)

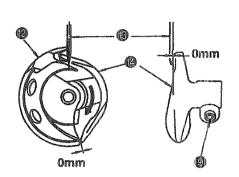


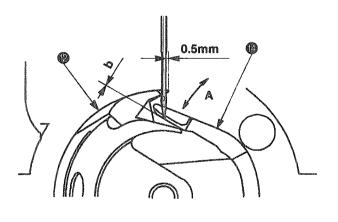
When a DP x 5

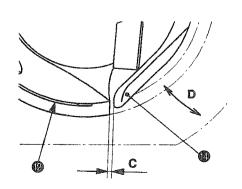
DP x 17 needle needle is used (of which needle count is lower

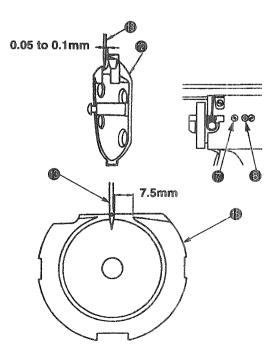
DP x 17 needle (of which needle count is higher than #22) is used. than #22) is used.











Adjustment Procedures

Results of Improper Adjustment

- * Turn ON the power once, and turn OFF the power again after making the intermediate presser in the lowered state.
- Turn hand wheel by hand to ascend the needle bar .
 Adjust so that lower marker line on the ascending needle bar aligns with the bottom end of the needle bar bushing lower .
- 2. Loosen setscrew (a) in the driver. Drawing bobbin case opening lover hook (b) toward you, open it to the right and left until bobbin case opening lover (b) comes off.

(Caution) At this time be careful not to let inner hook @ come off and fall.

- 3. Refer to 5. below and make tentative adjustments of timing for the inner hook **@**.
- 4. Turn the pulley by hand and make adjustments for the needle location block of the driver by bending it in the direction of Arrow A so that the clearance b attains 0mm to 0.5mm between the needle tip and the lowest end of the needle location block of the driver when the needle tip of the inner hook is protruded by 0.5mm from the right end of the needle .
- 5. Make an adjustment so that the blade point of the inner hook @ is aligned with the center of the needle ®, and that the clearance between the front end of the driver @ and the needle ® is 0 mm because the front end of the driver @ receives the needle to prevent needle bending. Then, tighten the set screw @ securing the driver.
- 6. Make adjustments so that the clearance (C) in the revolving direction attains 0.3mm to 0.6mm between the inner hook @ and the driver @ by bending the inner hook holder block (reverse side of the needle location block) of the driver @ in the direction of the arrow (D).

(Caution) Make sure not to damage the shuttle (race plane while making adjustment of the driver ().

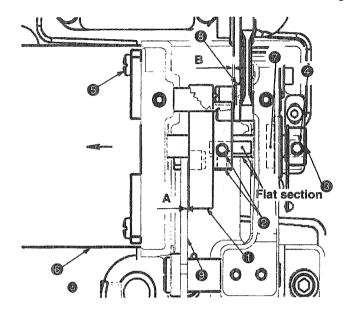
- 7. Loosen the set screw securing the shuttle s, and adjust the front-rear position of the shuttle by rotating the shuttle adjusting shaft so that the clearance between the needle s and the blade point of the inner hook becomes 0.05 to 0.1 mm.
- 8. After adjusting the front-rear position of the shuttle (6), set the clearance between the needle (6) and the shuttle (6) to 7.5 mm by adjusting the rotating direction, and tighten the set screw (6) securing the shuttle.

(16) Thread trimmer presser lifter cam connection/disconnection

Procedures of disassembling

- 1. Loosen 2 set screws @ securing the presser lifter and thread trimmer cam (hereafter called "cam") .
- 2. Loosen the two set screws @ and remove the sensor slit @.
- 3. Remove the four set screws and take out the presser lifting motor in the direction of the arrow. In some cases, the bearing and the motor shaft seem to be tightly coupled. Pull out the motor shaft in the direction of the arrow straightforward in order not to hurt the bearing .

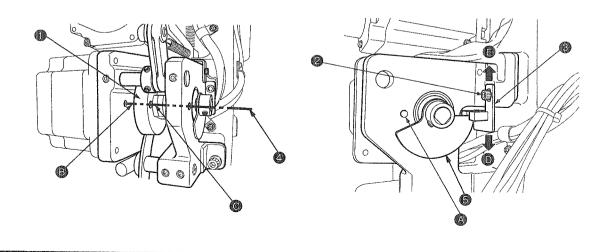
 At that time, the cam may come down. Handle it with care, not to damage it.



(17) Thread trimmer and presser origin sensor adjustment

Standard Adjustment

When origin retrieval (at start switch on) is conducted in the test mode 107 (IP-400) or CP-6 (CP-20), the standard holes of the sewing machine frame (and and are aligned with the standard hole of the thread trimmer and presser lifter cam .



Procedures of assembling

- 1. Apply a proper amount of grease (Juki Grease A) to the grooved cam block of the cam (1), the peripheral cam block, and the rollers of the presser bar lifter link (3) and the thread trimmer link (2). Refer to "10.-(4) Parts to which grease lock-tight is applied o TENSION RELEASE & THREAD TRIMMER MECHANISM COMPONENTS."
- 2. While the cam (1) is being inserted in the shaft of the presser lifting motor (3), mount the assembly on the sewing machine frame and tighten the four set screws (5). The insertion of the cam should be done gently in order not to hurt the bearing (6).
- 3. Clearance B toward the presser bar lifter link ③ and Clearance A toward the thread trimmer link ⑤ should be equally distributed. For this purpose, adjust the position of the cam ⑥ and fix it with the use of the two set screws ②. (Apply the screws to the flat section at both ends of the shaft.)

* If it is difficult to examine Clearance B, Clearance A should be adjusted to 0.5mm ~ 0.7mm during assembly.

4. Mount the sensor slit with the two set screws so that the end plane of the motor shaft can approximately coincide with that of the sensor slit (Join the flat section for installation.)

* Confirm that the slit plate of the sensor slit 3 does not interfere with the presser bar lifter sensor.

5. Refer to "3.-(17) Thread trimmer and presser origin sensor adjustment" and make sensor adjustments.

1. Start the test mode I07 (IP-400) or CP-6 (CP-20). o If the standard holes are not 2. Tread on the pedal for the retrieval of the thread trimmer and presser aligned, the thread trimming bar lifter (cam) origin. timing error occurs and defective 3. Make sure that the standard holes (and () of the thread trimming thread trimming and unthreading motor stand are aligned with the standard hole of the thread trimat the beginning of sewing may mer and presser lifter cam 1 using a bar 4. be caused. 4. If the standard hole of the thread trimmer and presser lifter cam is too high (direction), loosen the set screw and move the sensor mounting plate @ upward (@ direction) and secure it. If the standard hole @ of the thread trimmer and presser lifter cam (is too low (direction), loosen the set screw (and move the sensor mounting plate @ downward (@ direction) and secure it. After securing the sensor mounting plate (3), conduct origin retrieval by pressing the pedal to make sure that the standard holes are aligned. 5. Repeat the above steps 2 to 4 until the coincidence is confirmed.

Results of Improper Adjustment

Adjustment Procedures

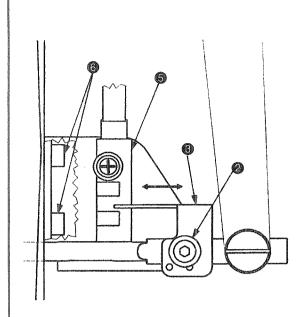
(Caution) Tighten the set screw @ after confirming that there is no

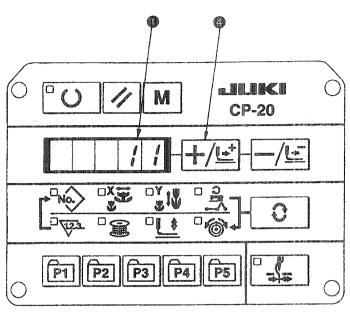
interference between the sensor slit plate (3) and the sen-

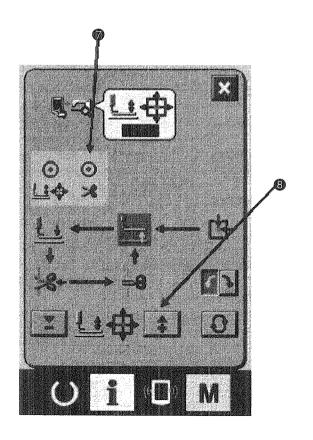
(18) Adjusting the thread trimmer sensor

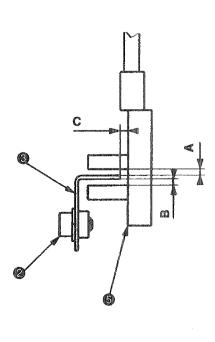
Standard Adjustment

After completion of origin retrieval (at start switch on) in the test mode I07 (IP-400) or CP-6 (CP-20), press the + key 6 to 8 times, and the thread trimmer sensor is turned off (IP-400: The contents on the operation panel change from " to " to " CP-20: The display of 10th digit on the operation panel changes from "1" to "0".)









Adjustment Procedures

- 1. Start the test mode I07 (IP-400) or CP-6 (CP-20).
- Tread on the pedal to perform origin retrieval for the thread trimmer cam.
 (Confirm that the origin is in the correct position. Then, proceed to the procedures shown below. Refer to "(17) Thread trimmer and presser origin sensor adjustment.")
- 3. Press the + key (3) (IP-400) or (4) (CP-20). Make sure that the contents (7) (IP-400) on the operation panel change from (6) " to " or that the value (1) (CP-20) on the operation panel changes from "11" to "01" after pressing the + key 6 to 8 times.
- 4. If the change occurs by pressing the + key other than 6-8 times, or the change does not occur, loosen the set screw ② and adjust the sensor slit ③ finely in the arrow direction.
- 5. After the sensor slit (3) has been fixed, tread on the pedal and make origin retrieval for the thread trimmer cam. Examine the sensor changeover position in the steps 3. and 4. above.
- 6. Repeat the steps 2. ~ 5. above until the coincidence is secured.

(Caution) During adjustments, check the clearances A, B, and C of the sensor slit @ and the sensor ⑤. If the clearances seem to be insufficient, use the set screws @ and ⑥ to correct the gradient. While taking this action, continue to work on the steps above.

Results of Improper Adjustment

- o If the thread trimmer sensor changeover takes place outside the range, the moving knife may interfere with the needle. This will be a cause of injury or the breakage of parts.
- o If the thread trimmer sensor changeover does not take place, Error 305 occurs and the sewing machine fails to start operating.
- o If the sensor slit (3) has no clearance against the sensor (5), this can be a cause of destruction in the sensor slit (3) or the sensor (5).

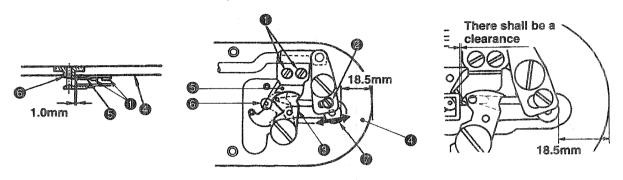
(19) Adjustment of the moving knife and counter knife position

Standard Adjustment

Counter knife position: The clearance between the counter knife and the needle hole guide is 1.0mm. Moving knife position: Before thread trimmer operation (standby state), the distance from the throat plate

front end to the tip of the thread cutter lever (small) @ is 18.5mm.

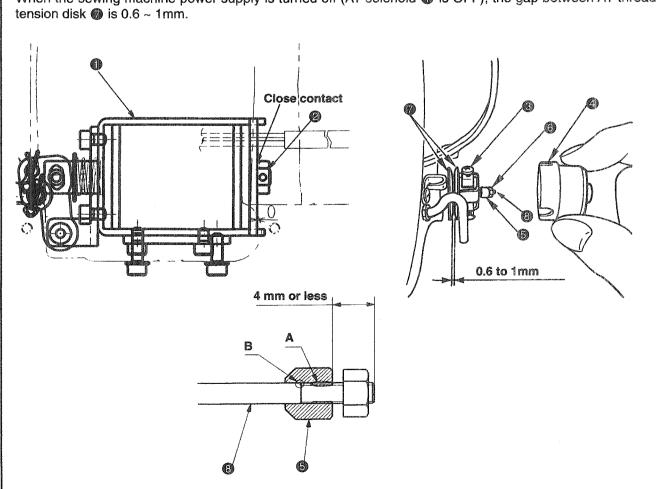
However, there shall be a proper clearance toward the moving knife tip during needle thread clamp and feed forward.



(20) Floating amount of the thread tension disk

Standard Adjustment

When the sewing machine power supply is turned off (AT solenoid (a) is OFF), the gap between AT thread



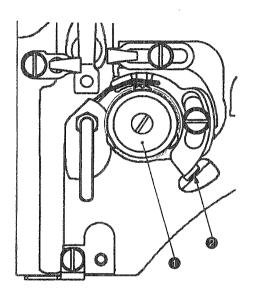
Adjustment Procedures	Results of Improper Adjustment
 Counter knife position Loosen the counter knife set screw to adjust the position. Moving knife position Loosen the screw to adjust the position. 	o If the clearance is less than 1.0mm, thread may be cut by the counter knife blade when the thread is pulled with the moving knife . In this case, upper and lower threads are cut into short pieces. o If the clearance is more than 1.0mm, the residual thread length after thread cutting operation becomes longer beneath the work.

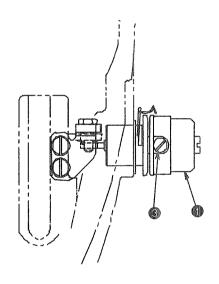
Adjustment Procedures	Results of Improper Adjustment
 Turn off the power supply and look for any close contact between the AT solenoid and the thrust collar . 	o If the amount of disc floating is too less, the residual thread length
 Loosen the three set screws and remove the thread tension cap . 	can be changed or shortened when the thread is thick.
 Hold the tension releasing pin adjust collar not to let it rotate, and loosen the nut . 	o If the amount of disc floating is too much, the thread tension discs
 Turn the tension releasing pin adjust collar and adjust the gap between the thread tension disk . (Adjustment of thread tension disc floating) 	cannot close completely and nor- mal thread tension may fail to be chosen. This can be a cause of imperfect sewing.
5. Hold the tension releasing pin adjust collar 6 and tighten the nut 6. Mount the thread tension cap 6 by means of the set screw 6.	o If the thread section of the tension releasing pin adjusting collar ⑤
Turn on the power supply and set up the thread tension. Confirm that the thread tension disk	is engaged with the incomplete thread section of the thread tension releasing pin (a), the thread
(Caution) When the tension releasing pin adjusting collar (3) is rotated, the thread section should not be engaged with the incomplete thread section of the thread tension releasing pin (3). (The thrusting distance of the thread tension releasing pin (3) should be 4 mm or less from the tension releasing pin adjusting collar (3).) * If the amount of disc floating cannot be adjusted properly under the condition that the thrusting distance is 4 mm or less, loosen the set screw (3) and adjust the AT link unit (front) in the right-left direction. Refer to "(22) AT unit connection/disconnection".	sion releasing pin (3), the thread tension releasing pin (3) may be damaged.

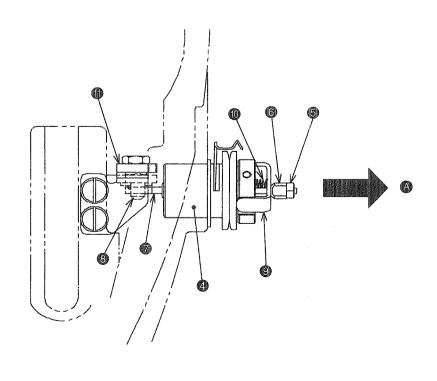
(21) Second thread tension connection / disconnection

Procedures of disassembling

- 1. Loosen the set screw @.
- 2. Remove three setscrews @ and take out the thread tension cap ...
- 3. Remove the nut (a) and the tension releasing pin adjusting collar (b). Then take out the thread tension disc pressing plate (a) and three thread tension disc return springs (a).
- 4. Pull out the second thread tension (a) to remove it. (Arrow (a))
- 5. For reassembly, follow the steps of 4. to 1. above.





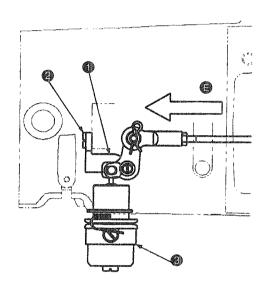


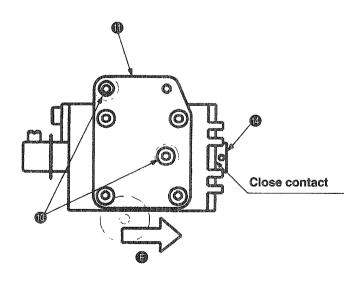
Procedures of assembling	
 When mounting the second thread tension , confirm in advance that the pin block of the AT link us (front) is exactly settling in the hole of the thread tension pressing pin . If you try to mount the second thread tension of forcedly with the pin area left disengaged, this may result in breakage in the thread tension pressing pin or malfunction. After the completion of mounting, make adjustments of (20) Floating amount of the thread tension disk at (39) Adjustment of thread take-up spring; 1) Stroke adjustments. 	

(22) AT unit connection / disconnection

Procedures of disassembling

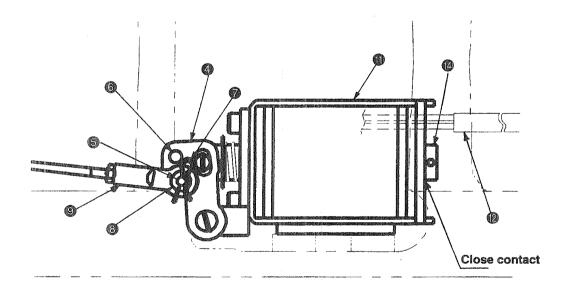
- 1. Remove the set screw of the AT link unit (front) and take out the second thread tension (21) Refer to "Second thread tension connection / disconnection.")
- 2. Draw out the cotter pin from the pin block (H type) or (S type) of the AT link unit (rear) . Be careful not to drop the washer (3) at that time.
- 3. Lift the AT joint block (a) of the AT unit upward to remove the block from the pin block (b) (H type) or (c) (S) type) of the AT link unit (rear) (a).
- 4. Draw out the AT link unit (front) from the plane side (in the direction of the arrow) and remove it.
- 5. Remove the two set screws (1) and take out the AT solenoid unit (1).
- 6. For reassembly, follow the steps of 5. to 1. above.

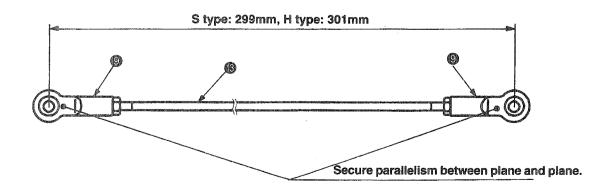




Procedures of assembling

- 1. For incorporating the AT solenoid unit (i) into the system, run the solenoid cable (ii) from the rear of the AT solenoid unit to the rear end of the machine arm.
- 2. The center-to-center distance between the AT joints ① of the AT connector rod ⑥ is 299 mm for S type and 301 mm for H type.
 - When the AT joints are disassembled or assembled, make sure that the center-to-center distance is correct, and that the front and rear of the AT joints are parallel. Failure to observe this may cause AT malfunction resulting in incorrect thread tension.
 - (When the AT joint) is turned 4 times, the feed move amount comes to attain 2mm.)
- 3. For the pin block of the AT link unit (rear) (4), use the pin block (5) for H type and the pin block (6) for S type. The wrong pin position may cause AT malfunction resulting in incorrect thread tension.
- 4. After completion of all assembly work, make sure that the thrust collar (a) closely contacts with the AT solenoid unit (b). If there is a clearance between them, loosen 2 set screws (c) and move the AT solenoid unit (d) to the rear (Arrow (a)) and secure it again.
 - * If the above-mentioned center-to-center distance is great between the AT joints (9), the clearance will be opened wider.

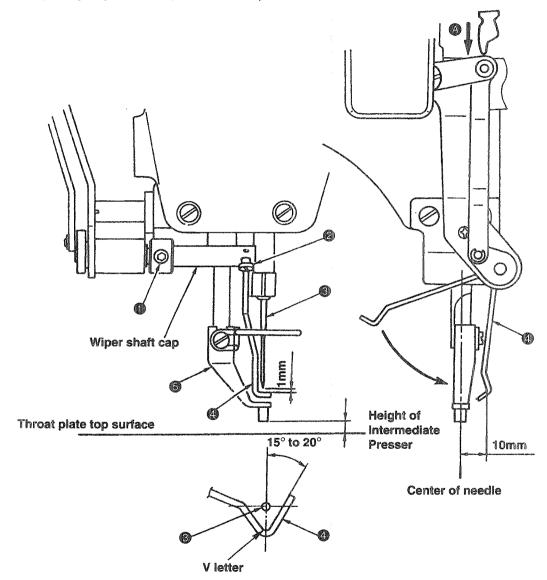




(23) Wiper adjustment

Standard Adjustment

- 1. When lowering the intermediate presser at the stop position after thread trimming (needle ® height from the top surface of throat plate is 17.7 mm.) and pressing wiper link section ®, adjust the clearance between the center of needle ® and the inside of V letter of the wiper © to 10 mm.
- 2. Press wiper link section
 on the way and when the wiper has come to the underside of needle, adjust the clearance to 1 mm.
- 3. The opening angle of the top end of the wiper ② is 15° to 20°.



(Caution) The intermediate presser supplied as standard accessory is available up to 5 mm material thickness.

However, the intermediate presser can not be used for the 3 mm material thickness or more since the wiper can not pass the space between the tip of needle and the intermediate presser.

Turn OFF the wiper switch in case of 3 mm material thickness or more.

Adjustment Procedures

- 1. Turn OFF the power after stopping the thread trimming, or turn ON the threading switch and lower the intermediate presser ...
- (Caution) As for the height of needle (3) when adjusting the wiper (4), set the height when the sewing machine stopped after trimming the thread actually.
- 2. Push wiper link section and move the top end of the wiper to the under side of the needle.
- 3. In the state of the above item 2., loosen setscrew and adjust the clearance between the wiper and the tip of the needle should be (1 mm) and the opening angle should be (15° To 20°). Then tighten setscrew .
- 4. Push wiper link section (a) to the last and loosen setscrew (i).
- 5. In the state of the above item 4., adjust the longitudinal (10 mm) and lateral positions of the wiper . Then tighten setscrew .

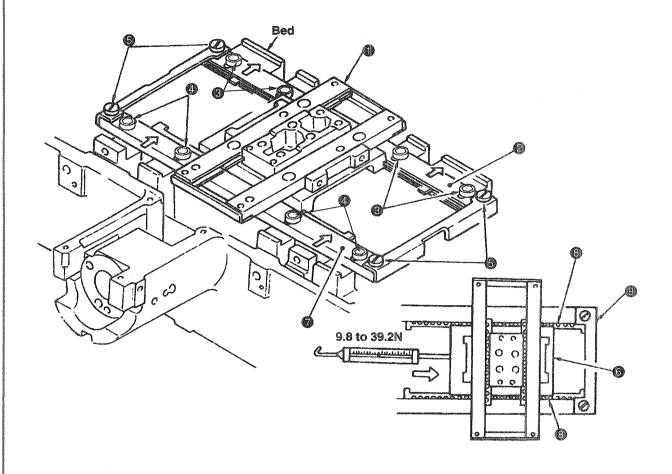
Results of Improper Adjustment

- o If the clearance between the wiper and needle is too small, the wiper comes in contact with the needle uneven stop position of the main shaft, causing needle breakage.
- o If the clearance between the wiper and needle is excessive, the wiper comes in contact with the intermediate presser and the wiper will damage the intermediate presser can not go up.
- o If a clearance of 10 mm between the inside of V letter of the wiper
 and the center of needle is mistakenly set, the wiper fails to spread the thread.
- o Similarly, If the center of needle does not align with the V letter of the wiper ②, the wiper fails to spread the thread.
- o If the opening angle of the wiper
 is excessive, thread sweeping failure will occur.

(24) Adjusting the pre-load of the X-Y table

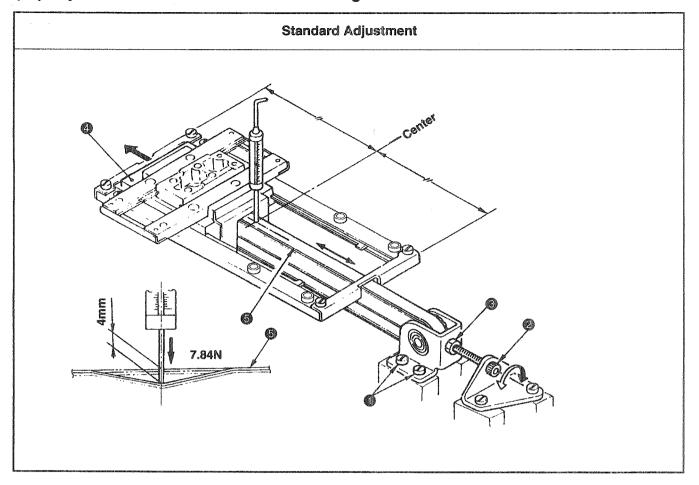
Standard Adjustment

When removing the X-Y table assy from the sewing machine, re-adjustment of the pre-load is necessary for the X axis only.

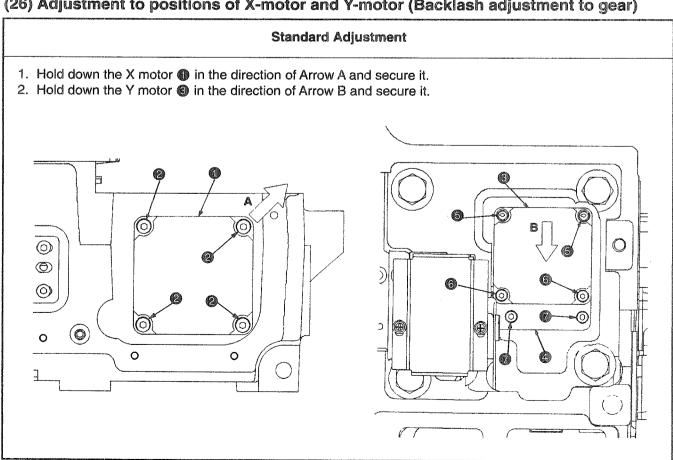


Adjustment Procedures	Results of Improper Adjustment
 Hold down the X fixed race (rear) in the direction of the arrow to tighten 4 set screws in. Loosen 4 set screws in the direction of the arrow to tighten 4 set screws in the tight and left sides. Tighten 4 set screws in the tight and left sides. Retainer compensating torque: This is a load necessary to move the race table in after the retainer in the tight and left sides. This torque should be measured when the belt is slack before pulse 	
motor installation.	

(25) Adjustment of the tension of the X timing belt



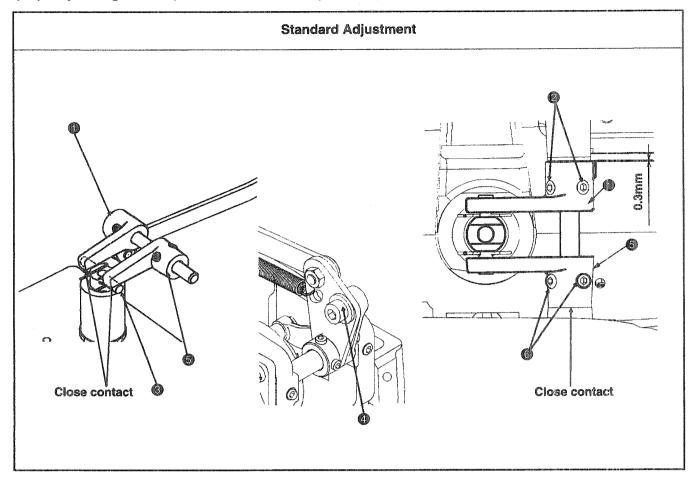
(26) Adjustment to positions of X-motor and Y-motor (Backlash adjustment to gear)



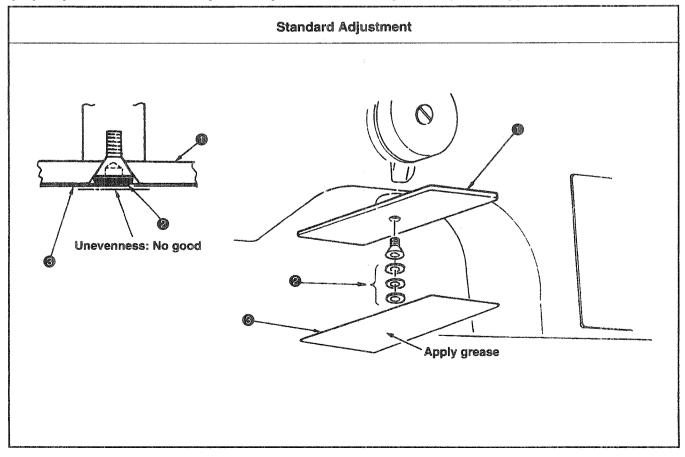
Adjustment Procedures	Results of Improper Adjustment
1. Move the race table 4 to the left end (in the direction of the arrow). 2. Tighten the adjusting screw 2 and fix the nut 3 so that the load point makes a warp of 4mm when a load of 7.84N (800gf) measured by a spring balance is applied to the timing belt 3. 3. Tighten the set screw 1 and check the amount of deflection again.	o If the tension is excessive, it will cause timing belt breakage. o If the tension is too low, it will cause failure of the feed.

Adjustment Procedures	Results of Improper Adjustment
 Loosen 4 set screws securing the X motor . Hold down the X motor in the direction of Arrow A and tighten 4 set screws to secure the X motor . Loosen 2 set screws , 2 set screws , all of which secure the Y motor , and 2 set screws securing the Y motor mounting plate . Hold down the Y motor in the direction of Arrow B and tighten 2 set screws that are positioned upper. Then, tighten 2 set screws that are positioned lower and 2 set screws securing the Y motor mounting plate . 	o If the X motor or Y motor is held down inadequately, feeding gear backlash is increased and needle location accuracy may be reduced. In addition, feeding error may be caused resulting in needle breakage, and other problems. o If the pushing is excessive, the load of the feed will become large, causing the failure of the feed.

(27) Adjusting of the presser lower arm (Motor type only)



(28) Adjustment when the presser plate sheet is replaced (Motor type only)



Adjustment Procedures	Results of Improper Adjustment
 Secure the presser lower arm A	o If the angle of the presser lower arm A and B is not equal, it will cause loosening the arm asm. screws or the breakage. o If the clearance is too small between the presser lower arm A and the arm, this can be a cause of maloperation during pushing down.

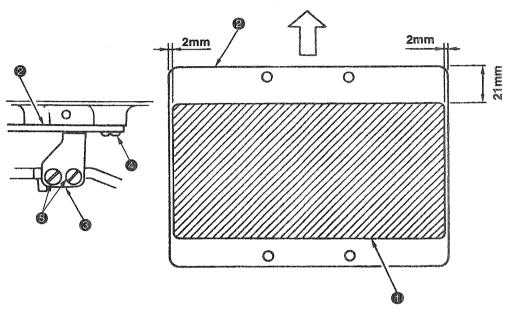
Adjustment Procedures	Results of Improper Adjustment
1. Put an appropriate number of the spacers ② into the presser plate ③ to make the presser plate sheet ③ even. 2. In regard to the application of grease, refer to "PRESSER PLATE & MANUAL PRESSER MECHANISM COMPONENTS" described in 10(4) Parts to which grease•lock-tight is applied.	o The step difference will cause malfunction of the feed.

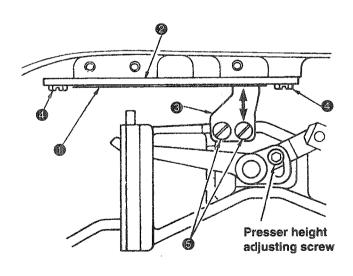
(29) Height of the slider and pasting of the presser plate sheet (Pneumatic type only)

Standard Adjustment

- 1. Follow the dimensions in the drawing below for pasting the presser plate on the presser plate Apply grease after pasting the sheet.
- 2. Bring the upper end of the slider 3 into close contact with the presser plate 2.

Rear side of the sewing machine



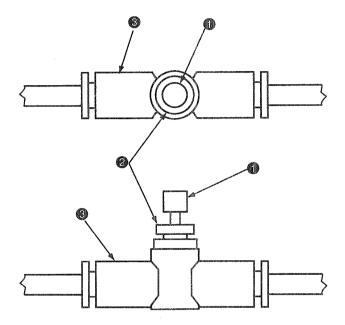


Adjustment Procedures Results of Improper Adjustment 1. Remove 4 set screws (a) to remove the presser plate (a), and replace o If the position where the presser the old presser plate sheet (1) with new one. plate sheet • was pasted is 2. After mounting the presser plate ②, adjust the height of the slider ③ wrong, abrasion of related with 4 set screws . To position the height, lightly press the slider components or peeling of the 1 to the presser plate 2 when the presser goes up. presser plate sheet may occur resulting in a feed error due to direct contact between the slider and presser plate ②. o Wrong slider 6 height may cause a feed error.

(30) Adjusting the speed of the work clamp feet (Pneumatic type only)

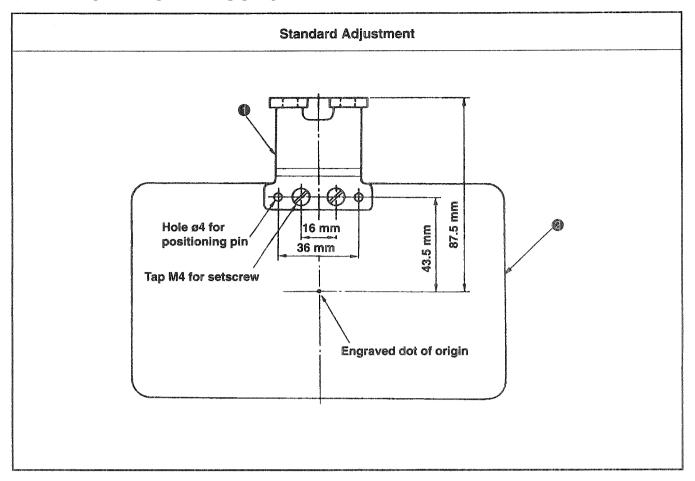
Standard Adjustment

- 1. Adjust the knob 1 and the knob 2 of the speed controller mounted on the solenoid valve and make adjustments as described below.
 - Presser lifting (tube label: 1-A, 2-A) and presser lowering (tube label: 1-B, 2-B).
 - Loosen the knob 2 ② and turn the knob 1 ① once fully to the right in order to make 3 turns to the left. Since then, tighten the knob 2 ②.



Adjustment Procedures	Results of Improper Adjustmen
 Adjust the speed referring to Standard Adjustment. To increase the speed of lowering/raising the work clamp foot, turn the knob 1 counterclockwise. To decrease the speed, turn the knob 1 clockwise. 	When the work clamp foot come down, the noise is big. The work clamp foot fails to rise

(31) Making the origin setting gauge



(32) Adjusting the X origin sensor

Standard Adjustment When the feed is in the mechanical origin, align the tip of the needle with the lateral position of the engraved dot of the origin.

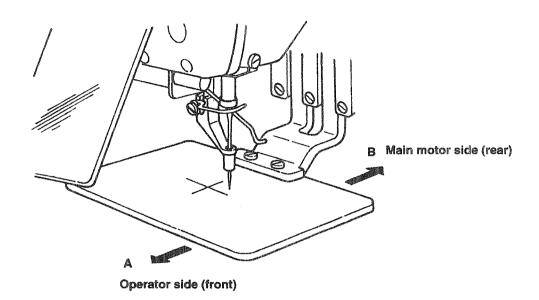
Adjustment Procedures	Results of Improper Adjustment
 Make an origin setting gauge as shown in the figure, and attach it to the work clamp foot . 	

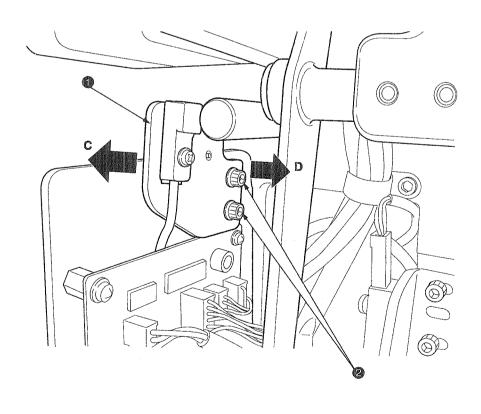
Adjustment Procedures	Results of Improper Adjustment
 Start the test mode I06 (IP-400), or CP-2 (CP-20). When the star pedal is depressed, the feed moves to the mechanical origin and stops. Lower the needle and check the right and left displacement based on the engraved marking of the origin. When the engraved marking of the origin is found to be displaced in Direction A from the needle tip, loosen the two set screws and adjust the sensor mounting plate in Direction C. After adjustments, tighten the two set screws and adjust the engraved marking of the origin is found to be displaced in Direction B from the needle tip, loosen the two set screws and adjust the sensor mounting plate in Direction D. After adjustments, tighten the two set screws and adjust the sensor mounting plate in Direction D. After adjustments, tighten the two set screws and adjustment the two set screws and adjustment the sensor interfere with the sensor. 	

(33) Adjusting the Y origin sensor

Standard Adjustment

When the feed is in the mechanical origin, align the tip of the needle with the longitudinal position of the engraved dot of the origin.



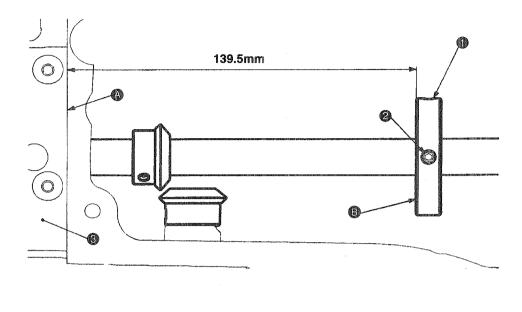


Adjustment Procedures	Results of Improper Adjustment
 Start the test mode I06 (IP-400) or CP-2 (CP-20). When the pedal is trodden on, the feed moves to the mechanical origin and then stops. Lower the needle and check the front-rear displacement from the engraved marking of the origin. When the engraved marking of the origin is found to be displaced in Direction A from the needle tip, adjust the sensor mounting plate in Direction C. (Loosen the set screws after adjustments.) When the engraved marking of the origin is found to be displaced in Direction B from the needle tip, adjust the sensor mounting plate in Direction D. (Loosen the set screws and fix the set screws after adjustments.) 	

(34) Adjustment of the bobbin winder driving wheel position

Standard Adjustment

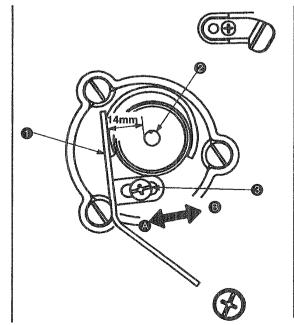
The distance is 139.5 mm between the measuring plane 6 of the bobbin winder driving wheel 6 and the cover mounting plane 6 of the sewing machine frame 6.

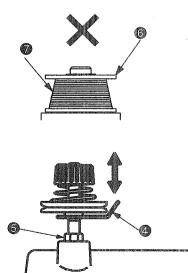


(35) Adjusting the bobbin winder amount

Standard Adjustment

The position of the bobbin winder lover (a) is based on the standard that it is 14 mm apart from the bobbin winder shaft (b). Try to perform bobbin winding actually and make fine adjustments of the bobbin lever set screw (a) in the directions of the arrows (b) and (c) so that the amount of thread winding becomes adequate (recommended value: 80 to 90% of the bobbin.)





Adjustment Procedures	Results of Improper Adjustment
 Loosen the two set screws to adjust the position (139.5mm) of the bobbin winder driving wheel and fix it with the two set screws . 	o If the distance of 139.5mm is insufficient, rubber ring wear may occur in the bobbin winder unit. In addition, the bearing life may be reduced in the bobbin winder unit.
	o If the distance of 139.5mm is excessive, normal thread winding may fail. In addition, this will also cause rubber ring slippage in the bobbin winder unit and give rise to wear.

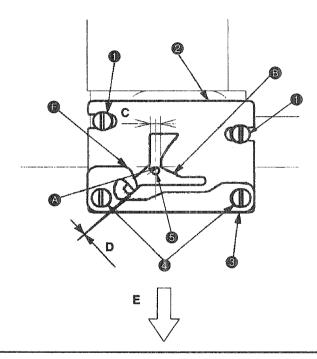
Adjustment Procedures	Results of Improper Adjustment
 Loosen the set screw of the bobbin winder lever and adjust the distance to 14mm between the bobbin winder lever and the bob- bin winder shaft . After that, tighten the set screw of the bobbin winder lever. 	o If too much thread is wound (thread protruded from the bobbin winder (3)), the thread (2) will come in contact with the inside of
Start the sewing machine and wind the thread at the bobbin winder.Confirm the amount of winding.	the bobbin case and this can be a cause of sewing deficiency.
 If the amount of winding seems to be too much, adjust the bobbin winder lever in the direction of the arrow . If the amount of winding seems to be too less, adjust the bobbin winder lever in the direction of the arrow . 	 o If the amount of thread winding is uneven at top and bottom of the bobbin winder (6), stitch perfora- tion may become irregular.
 3. If the winding state of the thread around the bobbin winder seems to be uneven, loosen the nut and adjust the height of the thread tension control . (Example) If the amount of the wound thread is less on the upper side of the bobbin winder as illustrated, adjust the thread tension control upwards. 	

(36) Adjustment of the shuttle upper spring and lower thread holder position

Standard Adjustment

- 1. Shuttle upper spring @
- : In regard to the right and left positioning, secure coincidence between the center of the needle and that of the groove width C. For the front-rear positioning, join the needle rear end and the corner block.
- 2. Lower thread holder 3
- : The amount of overlapping with the shuttle upper spring ② should be adjusted so that the thread of Vinylon #8 can pass smoothly when it is pulled in the direction of the arrow E. After the best positioning has been secured, fasten the two set screws ③.

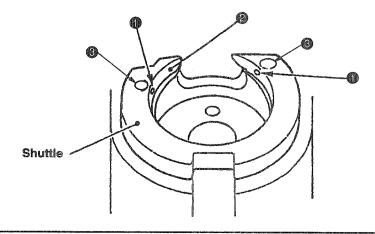
(Caution) If Part (3) and (3) is damaged, this is the cause of thread breakage, hangnail of thread, stain on thread, etc. Therefore, this part should be polished by the use of a buff or the like. In particular, the rear side should be handled with care.



(37) Shuttle felt

Standard Adjustment

- Two pieces of the shuttle felt (a) are inserted in the holes of the shuttle race (a). Confirm that the shuttle felts (a) are not overloaded when the inner hook is set and turned along the shuttle race (a).
- Shuttle packing (a) has been inserted in the hole of the shuttle race (a).



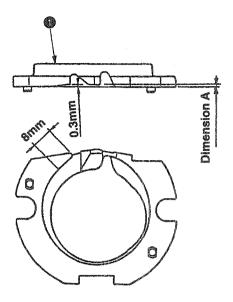
Adjustment Procedures	Results of Improper Adjustment
 Remove the work feed bar, feed plate, and the throat plate. Adjust the positioning of shuttle upper spring with the set screws (2 pcs.). Using the set screw (3), adjust the amount of overlapping D for the lower thread holder (3) and the shuttle upper spring (2). (Caution) The right and left positions can also change during (15) hook adjustments. Position adjustment for the shuttle upper spring (2) should be done after the completion of standard hook adjustment, without fail. 	o If there is a front and rear displacement or a right and left displacement, needle thread biting may occur into the hook. Too much motion to the rear side will cause the moving knife to fail to hook the needle thread. o Too much motion to the rear side will cause the moving knife to fail to hook the needle thread. o Too much motion to the left side will cause the moving knife to fail to hook the bobbin thread.

Adjustment Procedures	Results of Improper Adjustment
 If the shuttle felt seems to be protruded or it has been replaced with a new one, push it in by means of tweezers or the like. (Caution) Do not push it in excessively. Align the height and the plane of the shuttle race . Confirm that the shuttle packing has been mounted assuredly. 	 o If the shuttle felt is protruded, this will be turned into a rotary load of the inner hook, causing a sewing error. o If the shuttle felt is missing or pushed in too much, this will result in hook lubrication deficiency, causing hook overheating and wear. o If the shuttle packing has been missing, the shuttle felt and others may be lost, and this can be a cause of shuttle heating and wear.

(38) Shape of the shuttle race ring

Standard Adjustment

If wear seems to be too much around the pointed tip of the inner hook, release the shuttle race ring @ and confirm that the dimensions of the hatched area on the rear side are 0.3 x 8mm.



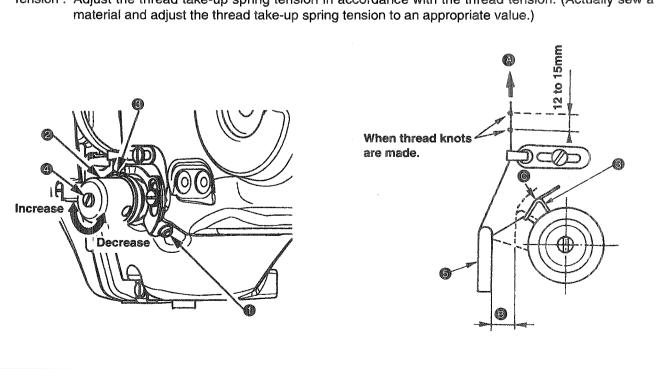
(39) Adjustment of thread take-up spring

Standard Adjustment

Stroke : The movable distance of the needle thread when the needle thread is pulled in the direction @ until

the thread take-up spring stops. 12 to 15 mm for S type, 12 to 18 mm for H type.

Tension: Adjust the thread take-up spring tension in accordance with the thread tension. (Actually sew a



Adjustment Procedures

Results of Improper Adjustment

1. If the dimensions of 0.3 x 8mm are not secured, retouching is required with the aid of an oil stone.

Dimension A (mm)	Part No.	Name of part	Remarks
0.8	14103253	Shuttle race ring A	Optional
1.3	14103352	Shuttle race ring B	Standard
1.7	14103659	Shuttle race ring C	Optional
1.9	B1817210DAD	Shuttle race ring D	Optional

Adjustment Procedures

Results of Improper Adjustment

- 1) Stroke adjustment
 - Loosen the set screw ①, and turn the thread tension assembly ②. Turning it clockwise increases the movable distance and thread drawing amount.
- 2) Adjustment of thread take-up spring tension
 - Turn the thread tension post ② using a thin driver with the set screw ① tightened to adjust the thread take-up spring ③ tension. Turning it clockwise increases the thread take-up spring ③ tension, and turn it counterclockwise decreases the tension.

(Caution) Set the stroke of the thread take-up spring **3** shorter for thin threads with thread number #50 or higher.

- o If the stroke of the thread take-up spring is larger than the specified value:
 - Length of remaining needle thread is shortened, causing the needle thread to slip off the needle at the sewing start.
- o If the stroke of the thread take-up spring is smaller than the specified value:
 - Needle thread breakage will occur at the time of thread trimming when using a thin thread.

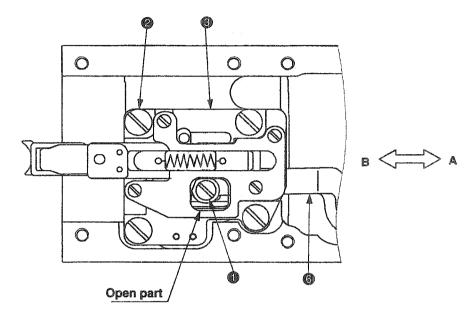
(Caution)

If the thread take-up spring (a) interferes with the L-shaped thread guide (a), the thread take-up spring (a) may fail to return to the initial position before thread trimming, and the length of remaining needle thread may be short. If such a trouble occurs, bend the section (a) of the thread take-up spring (b) to widen the clearance (b).

(40) Needle thread clamp device connection/disconnection

Procedures of disassembling

- 1. Remove the hinge screw .
 - * If the hinge screw acannot be seen from the open part of the needle thread clamp device , try to move the needle thread clamp connector link by hand in the direction of A or B.
- 2. Remove the four set screws ② of the needle thread clamp base and take out the needle thread clamp device ③.



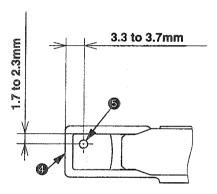
Procedures of assembling

- 1. Push the needle thread clamp device (3) in the direction of A and fix it with the four set screws (2). Tighten the hinge screw (1).
- 2. Turn on the power supply and press the key twice so that the needle thread clamp support plate complete is positioned at the far advanced end.

 Confirm that the distance between the needle thread clamp support plate complete and the needle is 3.3 to 3.7mm and 1.7 to 2.3mm, respectively.
- 3. If the distance seems to be inadequate, loosen the four set screws ② and move the needle thread clamp device ③ for adjustment.

(Caution) For the prevention of injury, the distance should be checked only if the sewing LED is unlit. (Press the O key twice after the power supply has been turned on.)

4. After the completion of the above-mentioned reassembly, make adjustments according to "(41) Adjusting the needle thread clamp sensor."



(41) Adjusting the needle thread clamp sensor

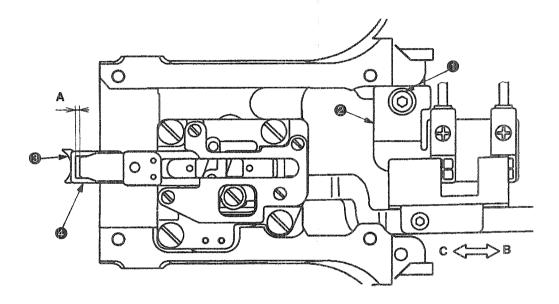
Standard Adjustment

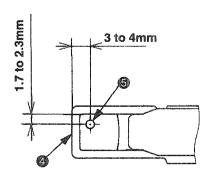
When the needle thread clamp support plate complete (a) is withdrawn by 3 to 4 pulses from the needle thread clamp position (Caution 1., 2.) the clearance A toward the needle thread clamp (a) becomes 0.

- (Caution) 1. The needle thread clamp position is known as the position returned by one step from the most advanced position when the capable key is pressed after the origin retrieval by the Test Mode I08 (IP-400) or CP-7 (CP-20).
 - 2. According to the thread clamp specifications, the memory switch U69 may change.

S Type $\rightarrow 0$

H Type \rightarrow 1





Adjustment Procedures

In the first place, confirm that the setting value of the memory switch U69 is [0] for S Type and [1] for H Type. Since then, make the adjustments as specified below.

- 1. Start the Test Mode I08 (IP-400) or CP-7 (CP-20).
- 2. Tread on the pedal for needle thread clamp @ origin retrieval.
- 3. Press the key twice and set the needle thread clamp support plate complete in the needle thread clamp position.
- 4. Confirm that the clearance A becomes 0 between the needle thread clamp (a) and the needle thread clamp support plate complete (b) when the [-] key is pressed 3 to 4 times (for 3 to 4 pulses), and that both the needle thread clamp (b) and the needle thread clamp support plate complete (a) move together when the [-] key is pressed again.
- 5. If the clearance A becomes 0 with 5 or more pulses, loosen the set screw (1) and fix the sensor mounting plate (2) after moving it in the direction B.

If the clearance A becomes 0 with less than 3 pulses, loosen the set screw
and fix the sensor mounting plate
after moving it in the direction C.

After the sensor mounting plate ② has been fixed, check the above-mentioned steps 2. to 4.

- 6. Using 3 to 4 pulses, repeat the steps 2. to 5. above until the clearance A becomes 0.
- 7. Tread on the pedal for needle thread clamp origin retrieval and define the most advanced position by pressing the key once.
- 8. Confirm that the distances between the needle thread clamp support plate complete and the needle are kept at 3 to 4mm and 1.7 to 2.3mm, respectively.
- 9. If the distance is found to be inadequate, adjust the position toward the needle (a) according to (40) Needle thread clamp device connection/disconnection. Since then, make the above-mentioned sensor adjustments again.

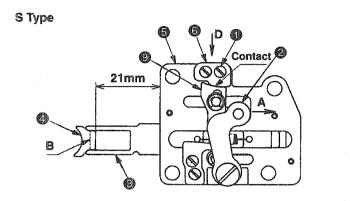
Results of Improper Adjustment

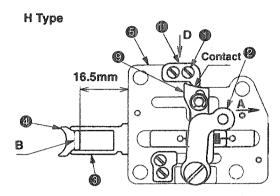
- o If there are too many pulses used until the clearance A becomes 0, this can be a cause of unthreading at the beginning of sewing.
- o If the number of pulses is too small until the clearance A becomes 0, the resistance toward the needle thread becomes large and this can be a cause of thread breakage at the beginning of sewing.
- o If the distance is improper between the needle thread clamp support plate complete and the needle , this will give rise to interference between the needle thread clamp and the needle .

(42) Adjusting the needle thread clamp notch

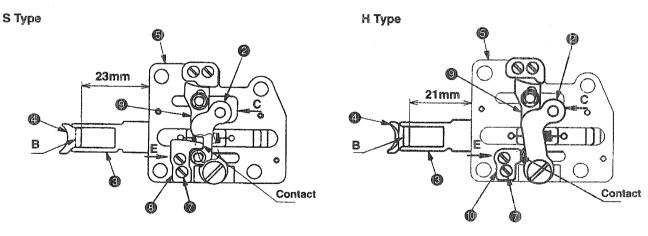
Standard Adjustment

- 1. Needle thread clamp notch R position
 - When the needle thread clamp link complete ② is pressed in Direction A, and Part B of the needle thread clamp support plate complete ③ and the needle thread clamp ④ begins to open, the distance between the needle thread clamp ⑤ and the needle thread clamp base ⑤ becomes 21mm for S Type and 16.5mm for H type.





- 2. Needle thread clamp notch F position
 - When the needle thread clamp link complete is pressed in Direction C, and Part B of the needle thread clamp support plate complete and the needle thread clamp begins to open, the distance between the needle thread clamp and the needle thread clamp base becomes 23mm for S Type and 21mm for H Type.



Adjustment Procedures

Results of Improper Adjustment

- 1. Needle thread clamp notch R adjustment
- 1) Loosen the two set screws 1.
- 2) Press the needle thread clamp link complete in Direction A so that the distance between the needle thread clamp and the needle thread clamp base becomes 21mm for S Type and 16.5mm for H Type.

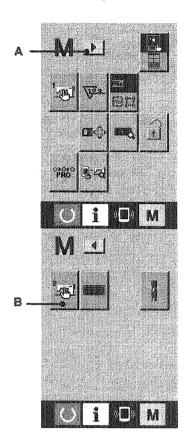
Move the needle thread clamp notch R (a) (S Type) or the needle thread clamp notch RH (b) (H Type) in Direction D, lightly press it toward the needle thread clamp cam plate (a), and tighten the two setscrews (b).

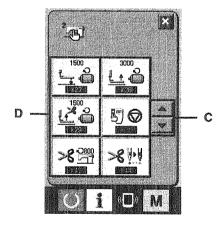
- o If the distance is too long between the needle thread clamp (a) and the needle thread clamp base (a), the needle thread release timing becomes earlier and this can be a cause of unthreading at the beginning of sewing.
- o If the distance is too short between the needle thread clamp and the needle thread clamp base, the needle thread release timing is delayed and this can be a cause of needle thread end remaining on the rear side of the material.

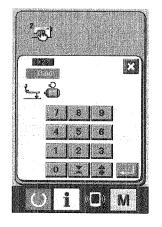
- 2. Needle thread clamp notch F adjustment
- 1) Loosen the two set screws .
- 2) Press the needle thread clamp link complete ② in Direction C so that the distance between the needle thread clamp ③ and the needle thread clamp base ⑤ becomes 23mm for S Type and 21mm for H Type. Move the needle thread clamp notch F ③ (S Type) or the needle thread clamp notch FH ① (H Type) in Direction E, lightly press it toward the needle thread clamp cam plate ⑤, and tighten the two setscrews ⑥.
- o If the distance is too long between the needle thread clamp (a) and the needle thread clamp base (a), the needle thread release timing becomes earlier and this can be a cause of needle thread end remaining on the rear side of the material or jamming of needle thread into the needle thread clamp (a).
- o If the distance is too short between the needle thread clamp and the needle thread clamp timing is delayed and this can be a cause of failure in needle thread clamping.
- Adjustments should conform to the adjustment values according to the needle thread clamp specifications (S Type or H Type). Otherwise, this can be a cause of failure in needle thread clamping operation.

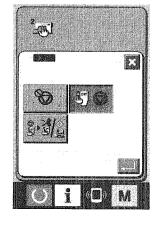
4. Memory switch

(1) Start and change









To change the memory switch (level 2):

The sewing machine operation can be changed by changing the setting of the memory switch.

1. For IP-400:

(1) To call up the screen showing the memory switch data (level 2) list:

Hold down the M switch for approx. 6 seconds, and the page change button (A) appears at the top of the screen. Press the page change button to call up the next page, and the memory switch (level 2) button (B) appears. Press the memory switch (level 2) button to call up the screen that shows the list of memory switch data (level 2).

(2) To select the memory switch button to be changed:

Select the data item (D) to be changed using the up and down scroll buttons (C).

(3) To change memory switch data (level 2):

Memory switch data (level 2) has 2 types of data items: one is where a value is changed, and the other is where a pictograph is selected. The data items where a value is changed are colored pink and numbered such as and the value can be changed with + and - buttons shown on the screen. The data items where a pictograph is selected are colored blue and numbered such as and pictographs shown on the screen where data items are changed are selectable.

Refer to "4.-(2) Function list" for further information about memory switch data (level 2).



Upper 3 figures indicate a memory switch number.

Lower 2 figures indicate setting contents.

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DATER SERVICES		

2.	For	CP-	20.

- Press the M key when the sewing LED is off to activate the user setting mode (Level 1) of the memory switch.
 Hold down the M key for 6 seconds to activate the service setting mode (Level 2) of the memory switch.
 (Caution) A 3-second and a 6-second buzzers sound when the key is held down. The 3-second buzzer informs users of activation of the test mode.
- 2. Change the memory switch number with the +/ the and keys.
- 3. Press the key when the memory switch number to be changed appears. On this occasion, the sewing LED is turned on.
- 4. Change the contents of the memory switch with the $+/\underline{\square}$ and $-/\underline{\square}$ keys.
- 5. The factory settings can be restored with the key
- 6. Press the key to register the changes. The sewing LED is turned off and the screen returns to the one where the memory switch number is selected.
- 7. Press the M key to end the memory switch setting mode and to return to the regular mode.

(2) Function list Level 1 (Refer to the instruction manual for changing procedure.)

	SL/HL SL/HL 2206 2210 FU05 FU05				A SAMON AND AND AND AND AND AND AND AND AND AN	2 2 10 2 7 2 4 2 10 10 10 10 10 10 10 10 10 10 10 10 10	ANCHI CANAN			3370					
	SL/HL SI 1510 2 FU05 F														не при
	SL/HL 1306 1306 FU05														Medicalization of the second
Initial value	SS/HS 1306 FU05	2700	1500	2700	2700	2700	2700	200	0	0	200	009	1000	1500	2000
Initial	SL/HL 2210	27	15	27	27	27	27	20))	20)9	10	15	20
	SL/HL 2206														opęp yta cytacy augustus och
	SL/HL 1510														EXPENSES ENGINEERING PROPERTY OF THE PROPERTY
	S SL/HL 1306														
	SS/HS 1306						***************************************								
The second secon	Smallest change- able unit	100rpm	100rpm	100rpm	100rpm	100rpm	100rpm	-	-	1 (4°)	100rpm	100rpm	100rpm	100rpm	100rpm
ekuseuserkoiste mõiste Pätis ährinikannassassassantamastassassassassassas	Setting range	200 to 2700rpm	200 to 1500rpm	200 to 2700rpm	200 to 2700rpm	200 to 2700rpm	200 to 2700rpm	0 to 200	0 to 200	6 to 4	200 to 1500rpm	200 to 2700rpm	200 to 2700rpm	200 too2700rpm	200 to 2700rpm
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	Item	Maximum sewing speed	Sewing speed of 1st stitch In case of with thread clamp	Sewing speed of 2nd stitch In case of with thread clamp	Sewing speed of 3rd stitch In case of with thread clamp	Sewing speed of 4th stitch In case of with thread clamp	Sewing speed of 5th stitch In case of with thread clamp	Thread tension of 1st stitch In case of with thread clamp	Thread tension setting at the time of thread trimming	Thread tension changeover timing at the time of thread trimming	Sewing speed of 1st stitch In case of without thread clamp	Sewing speed of 2nd stitch In case of without thread clamp	Sewing speed of 3rd stitch In case of without thread clamp	Sewing speed of 4th stitch In case of without thread clamp	Sewing speed of 5th stitch In case of without thread clamp
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	No.	Item		Setting range	smallest change- able unit	SS/HS 1306	SL/HL 1306	SL/HL SL/HL 1510 2206	0) (4	AL SS/HS 1306 FU05	S SL/HL 3 1306 5 FU05	SL/HL 1510 FU05	SL/HL 2206 FU05	SL/HL 2210 FU05
5		Thread tension of 1st stitch In case of without thread clamp	<u>9</u>	0 to 200	Υ-					0		PPA TOWNSTREETERSCOACHES	-	
16		Thread tension changeover timing at the time of thread trimming In case of without thread clamp	# Me	-5 to 2	-					ၾ				
				0: Normal									REPORTED BY THE PARTY OF THE PA	
17		Operation panel key lock mode (CP-20 only)		1: X enlarging/ Y enlarging/speed- Item skip	ı					0				
18		Counter motion selection		0: Sewing up counter	ı					c				
		(CP-20 only)		1: Bobbin thread Down counter						>				
19	977	Height of presser at the time of 2-step stroke	4	50 to 90	-					70				
			6	0: Without buzzer sound										
50		Buzzer sound can be prohibited	¢	1: Panel operating sound	ı					0				
			\$	2: Panel operating sound + error										
51		Number of stitches of thread clamp release is set	WVZ3.	1 to 7 (stitches)	-					2				
22	757	Clamping timing of thread clamp can be delayed	3	-10 to 0	-					0				
23		Thread clamp control can be prohibited	Je P	0: Normal	1					0				
			き	1: Prohibition			And the second s			and to the first of the properties of the parties o		gith military management		Dispussed Medical Annual Services

Initial value	Smallest change able unit SS/HS SL/HL SL	-8 to 16 (4° in steps 1 (4°) 3 of, 140 to 44°)	0: Presser goes up after moving at start of sewing	1: Presser goes up – 0 immediately afterend of sewing	2: Presser goes up by pedal operation after moving at start of sewing	0: With presser up		0	1: With origin retrieval		0		0	1. Drace or rice writh
majority of the service of the formal designation of the service o		-8 to	0: Presse after mov of sewing	1: Pressel immediatel of sewing	2.5. Pe	0:0	oH	0: Without origin retrieval	- 4 1	0: Without origin retrieval	1: Every time 1 pattern is finished	2: Every time 1 cycle is finished	O: Presser rise	14 14 1-
	ltem	Feed motion timing is selected Set the timing in "-" direction when stitch is not well-tightened.		State of the presser after end of sewing is selected		Presser lifting motion at the end		rformed	(other than cycle sewing)	Origin retrieval in cycle sewing can be set		Popular	Start of presser when sewing machine stops by temporary stop	
	No.			C 27		182	****	E-6 V-2 E-9					5 1	
Day of the second		24	ki ka sa	25	(d-10)	26		27	410000000000000000000000000000000000000	78		CONTRACTOR OF STREET ASSESSMENT	29	desiral ou = v =

Initial value	SL/HL SL/HL SL/HL SS/HS SL/HL SL/HL SL/HL SL/HL 1510 2206 2210 FU05 FU05 FU05 FU05 FU05 FU05 FU05 SUME	0		7	-	80	ဇ	0
	SS/HS SL/HL 1306 1306							0
	Smallest change- able unit	-			 	-	-	-
CONTRACTOR AND THE PROPERTY OF	Setting range	0: Standard (front)	1: Rear	0: Disabled	1: Enabled	0 to 15 stitches	0 to 15stitches	(For motor-driven frame) 0: 1 step 1: 2-step stroke (move downward to the owest point with presser SW) 2: 2-step stroke (start to move downward to the lowest point with start SW) 3: 2-step stroke (With presser SW1: mid-point, lowermost position, rise) 4-99: 1 step (For pneumatic frame) 0: Intigrated type frame 1: Right-left separate type frame, order. left ⇒ right ⇒ left stroke, between right and left 3: Right-left separate type frame, order. left ⇒ right ⇒ left stroke, between right and left 5: Right-left separate type left stroke, no preference between right and left 5: Right-left separate type left stroke, no preference between right and left for the stroke, order: right → left 7: Right-left separate type left stroke, order: right → left 7: Right-left separate type left stroke, order: left → right elegs stroke, order: left → right elegs stroke, order: left stroke, order: left + right elegs stroke, order: left stroke, order: left + right elegs stroke, order: left + right ele
op de proposition de la company de la compan				8	**	- EZ\	10 MAG	
	ltem	Thread clamp and thread clamp position selection	-	T	ineau preakage detection selection	Number of invalid stitches at the start of sewing of thread breakage detection	Number of invalid stitches during sewing of thread breakage detection	Feeding frame control/pedal open-close
NACESCRIPTOR OF THE PROPERTY O	No.	80			D)	0		2
	NO MONTH OF THE REAL PROPERTY	89		6	<u> </u>	94	44	45

	- SL/HL 2210	}		- Agu				
	SL/HL 2206 FU05	N						
	SL/HL 1510 FU05							
	SL/HL 1306 FU05							
Initial value	SS/HS 1306 FU05							
Initial	SL/HL 2210		,					
	SL/HL 2206	•						
	SL/HL 1510							
	SL/HL 1306	-						
er de la companyation de la comp	SS/HS 1306	0						
Q	change- able unit	-	i i i		ı		1	
n (in the second consequence of the second c	Setting range	(For motor-driven frame) 0: 1 step 1: 2-step stroke (move downward to the lowest point with presser SW) 2: 2-step stroke (start to move down- ward to the lowest point with start SW) 3-99: 1 step (For pneumatic frame) 0: Integrated type frame 1: Right-left separate type frame, no preference between right and left 2: Right-left separate type frame, order: left → right 4: Integrated type frame stroke 5: Right-left separate type left stroke, no preference between right and left 6: Right-left separate type left stroke, order right → left 7: Right-left separate type left stroke, no preference between right and left 6: Right-left separate type left stroke, order right → left 7: Right-left separate type left stroke, order right → left 7: Right-left separate type left stroke, order right → right 7: Right-left separate type left stroke, order: left → right	0: Without	1: With	0: Without	1: With	0: Without	1: With
			1	₩ 1	**	7 H	3.	** **
1			(A) a	·	য		Andrews	
	Item	Feeding frame control: midway stop time open/close	Pedal SW 1 with/without latch	•	Pedal SW 2 with/without latch		Pedal SW 3 with/without latch	
	No.						AND SECU	

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	No.	Item		Setting range	Smallest - change- able unit	SS/HS 1306	SL/HL 1306	SL/HL 1510	SL/HL 2206	SL/HL 2210	SS/HS 1306 FU05	SL/HL 1306 FU05	SL/HL 1510 FU05	SL/HL 2206 FU05	SL/HL 2210 FU05
7.4	I.E.	Dodol OM 4 with height a lead		0: Without			Antro-chiliana over a versioni fan			4	T meta-samuar Nada-samuning property of the control				
f	-		.	1: With	Į.					-					Marie (Augusta)
				0: Prohibition											
48	12. 	Enlarging/reducing function mode (CP-20: increasing/decreasing of pitch only)	VZa:&	1: Stitch count enlargement/ reduction (pitch fixed)	1					***					ALTERNITOR TO A TRANSPORTED TO A TRANSPO
				2: Pitch enlargement /reduction (stitch count fixed)											alan Carama ayan kan 1994 hasa dalah
				0: Prohibition											
49		Jog move function mode	**************************************	1: Parallel move	l					N					
Chi dhala a waka wa mara a				2: Second origin specified later	1										
(Ž	-	母器	0: Without motion											
ଛ		Hetainer compensation motion: selection of motion	皆序	1: With motion	ı					0					
72			8 편1	0: Without				(,		da jejenini govjeni da kale zaveni zna
		at the time of origin retrievaly/ return to origin		1: With	1			0					-		***************************************
			% 0	0: Automatic thread trimmer											
52	F GB 	Temporary stop, thread trimming operation	% ©	Manual thread trimmer (by pressing stop SW again)	1					****					

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Main motor XV feed synchronized control speedsylicin control speedsylicin control speedsylicin control speedsylicin control in thermediate presser with without a presser i wiper sweeping West of the control in the co	No.	Item		Setting range	change- able unit	SS/HS 1306					ļ	SL/HL 1306 FU05	SL/HL 1510 FU05		SL/HL 2210 FU05
Control, speediplich Control, speediplich Control, speediplich Control, speediplich Control Contr			4 2700/pm	0: 2700rpm/3.0mm		-				Red Bill (1975) the second design of the second des	and have consequently and the second	Paracona de la companya de la compan	омешин-колором не колором на постава и п	t	
Intermediate presser with without air pressure detection With without air pressure detection With without air pressure detection			2200rpm	1: 2200pm/3.0mm	ı					0					A Marining of the Court of State
Intermediate presser with/without Control Cont			4 1800rpm	2: 1800rpm/3.0mm											
Inhermediate presser with/without control cont			4 1300rpm	3: 1300rpm/3.0mm											2.21.24.14
Intermediate presser with/without control contr	 		= j	0: Disabled (lowering fixed)											
Intermediate presser lowering iming the front and feeling teach from a machine head activation activation intermedia presser: wiper sweeping wiper wearing) With the feeling teach from the selection (side-sweeping wiper wearing) With the feeling teach from the feeling from presser (intermediate presser intermediate from the feeling from presser (intermediate presser intermediate from the feeling from th	 S		= 2	1: Enabled (lowering with sewing data during operation)	ı					-					
Intermediate presser lowering timing	 2 - - - - - - - -			2: Enabled (lowering during feeding front and feeding back)											
Intermedia presser: wiper sweeping Position (side-sweeping wiper wearing) With/without air pressure detection With/without air pressure detection With without air pressure detection	 1000 1000 1000 1000 1000 1000	Intermediate presser lowering timing	.	0: Immediately before sewing machine head activation	I					0					
Intermedia presser: wiper sweeping position (side-sweeping wiper wearing) With/without air pressure detection With/without air pressure detection Compared to the pressure detection Compared				1: Synchronization with last feeding frame											
position (side-sweeping wiper wearing) (2. Below intermediate presser (3. Below intermediate presser (4. With/without air pressure detection	 912) 1222 1233 1234	Intermedia presser : wiper sweeping		0: Above intermediate presser											
With/without air pressure detection With/without air pressure detection I: with		position (side-sweeping wiper wearing)	訓賞	1: Above intermediate presser (intermediate presser lowest position)	ı					0					
With/without air pressure detection With/without air pressure detection The state of the state			₹	2: Below intermediate presser											
will/without air pressure detection 1: with 1: with		Mister (crish		0: without		•									
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	No O	Item		Setting range	Smallest change- able unit	SS/HS 1306	SL/HL 1306	SL/HL 1510	SL/HL 2206	SL/HL SS/HS 2210 1306 FU05	SS/HS 1306 FU05	SL/HL 1306 FU05	SL/HL SL/HL 8 1510 2206 7 FU05 FU05 P	SL/HL 2206 FU05	SL/HL 2210 FU05
58	2411	Intermediate presser down position setting Refer to Instruction Manual, "I-4-7. Intermediate presser height".	P	0 to 7.0mm	0.1				_	3.5					Microscope ven montrettable academical maccas macca
Ç	(2) G.	With the transfer of the trans	16.50	0: Without						7					With the file of the common and the figure is a
n C		WILLYWILLIOUT HEEGIE COOLET COTHIO		1: With	l					-					
09		Greas-up error Clearing of number of stitches of grease-up is performed	O EA	Counted by 1 stitch Only "clear" is available.	I					l					
			日本語	1: Japanese											
2		Language selection	English	2: English	-					-					
			女士	3: Chinese									:		HAMMA COAST

• Level 2

	- Control of the Cont		ill web years and a continuous and management to any any another to	AND THE PROPERTY OF THE PROPER					Initial value	alue	Table Description of the Control of			
	No.	Item		Setting range	Smallest change- able unit	SS/HS SI 1306 1	SL/HL SL/HL 1306 1510	SL/HL 2206	SL/HL 22210	SS/HS 1306 FU05	SL/HL 1306 FU05	SL/HL 1510 FU05	SL/HL 3 2206 FU05	SL/HL 2210 FU05
<u> </u>	1.	Motor presser presser lowering drive speed	ζĴ,	100 to 1500pps	10pps				1500	0				
CI	25	Motor presser presser rising drive speed	○	100 to 3000pps	10pps				3000	0				
დ	k29	Thread trimming drive speed (+ presser rising)	2 2	100 to 1500pps	10pps				1000	Q				
and the second s			P	0: Ineffective								To be the second of the second		
· · · · · · · · · · · · · · · · · · ·			6	1: Effective	ı				-					
4	9	Temporary stop input selection	♦୬ KB ØB	2: Thread trimming with temporary stop switch or start with start pedal after temporary stop										
ц		T	%	0: 400rpm					7					
O		inead tinining speed	%	1: 800rpm	1				_					
ď	E-0.2	Colombia of the control of second transfer of secon	16 8×	0: Ineffective					,					
o		Selection of unead uniming jump feed control	*	1: Effective					-					
7	E \$2	Needle hole guide diameter at controlling thread trimming jump feed	ni Ni	1.6 to 4.0mm	0.2mm		St	S tyoe: 1.6/H type: 2.0	type: 2.0					
α		Thread trimmer control prohibition	%	0: Normal operation					C					
·	2		Ø.	1: Prohibited to use	l				0					·
တ	(52)	Output time of magnet wiper on	%	10 to 500ms	10ms				20					
9	3.3 11.5	Delayed time of magnet wiper off	0	10 to 500ms	10ms				80	DOMESTIC VIOLENCE VI	CHAC		A CONTRACTOR OF THE PROPERTY O	

				Nantourskielelelele Theman to postar black and the Control of the					a dia vitro de de desenvitro de la constanción del constanción de la constanción de	Initial value	value	in management and the state of	A CONTRACTOR OF THE PROPERTY O	10000000000000000000000000000000000000	
	No.	ltem		Setting range	smallest change- able unit	SS/HS 1306	SL/HL 1306	SL/HL 1510	SL/HL 2206	SL/HL 2210	SS/HS S 1306 F FU05 F	SL/HL 1306 FU05	SL/HL 1510 FU05	SL/HL 2206 FU05	SL/HL 2210 FU05
T-	17. 17. 26.	Wiper output timing select at upper	17	0: Up position	(
		מפמק לסונו פוסלי	# <#	1: Upper dead point											
12	Kab	Moving limit range in +X direction	中	0 to 819mm	-	99+	9	9/+	+111	+111	99+		9/+	+111	+111
13		Moving limit range in -X direction	4	-819 to 0mm	-	99	9	9/-	-111	-111	99		92-	-111	-111
4	(58	Moving limit range in +Y direction	中	0 to 819mm	-	+31	-	+51	+31	+51	+31		+51	+31	+51
15	(इंद	Moving limit range in -Y direction	#	-819 to 0mm	-	-31	-	-51	-31	-51	-31		51	-31	-51
16	323	Selection of automatic		0: Ineffective											
OMOONOMERS (IVANE S		אופקאואווסון או אסעיפן טוו	哲	1: Effective	l										
17	E.	Selection of needle bar stop	8	0: Ineffective	l					•					
				1: Effective											
18	E	Thread tension output while wiper output is active	Ør H	0: No output (with thread trimming tension kept)	ı						0				
			8	1: Maximum output											
<u>6</u>		Selection between motor presser		0: Motor presser		(•			C		*		
		and pneumatic presser		1: Pneumatic presser		O .		_			>				
20	15	Pneumatic presser lowering delayed time (Disabled with motor presser selected)	(a)	0 to 1000ms	10ms					7	100				
21	2	Control of feeding frame/ automatic opening and closing		0-99: Full open, full holding	-				\$50Q\$645525680000000000000000000000000000000000		0	ded transcription	gaanooglogusergestrang/ggo	ERCENCENSPROMPROCEDIFFENERAL	SCHOOLOGIA

			AND CONTRACTOR OF THE CONTRACT				WIND CONTROL OF THE WIND STREET OF THE WIND STREET	ATTENTION OF THE STATE OF THE S		Initial value	alue	Spirit sp	STREET,	- in Addition in A	
NAME OF THE OWNER, WHITE OF THE OWNER, WHITE OF THE OWNER, WHITE OWNER, WHITE OWNER, WHITE OWNER, WHITE OWNER,	No.	Item		Setting range	smallest change- able unit	SS/HS 1306	SL/HL 1306	SL/HL 3	SL/HL 2206	SL/HL 2210	SS/HS 1306 FU05	SL/HL 1306 FU05	SL/HL 1510 FU05	SL/HL 2206 FU05	SL/HL 2210 FU05
		Feeding frame control and		0: Full open					SEA CONTRACTOR OF THE CONTRACT	COOLEGICAL CACHERONIC PROPERTY CACHERONIC PROP					
22	80 80	(enabled only if were lift of work		1: Stroke position	ı						0				
-in-terminal and an in-		end (=1))		2 to 99: Full open											
23		Selection of the fixed refuse position		0: Nonuse											
				1: Use							>				
24	86	Origin retrieval under normal	4	0: Standard											
Di Marinina di Antonio di Salamania di Salamania di Salamania di Salamania di Salamania di Salamania di Salama		conditions/origin reset route selection	- 2 1	1: Inversion	l						0				Alaka communicaci megaliya ing
omo-salas salas sala			1	2: Y-axis → X-axis											Walland Control
			## ## ## ## ## ## ## ## ## ## ## ## ##	3: X-axis → Y-axis											
			+ 4	0: Standard											
C	II. II.		马坦	1: Inversion											
S	7.1 7.1	Origin retrieval at mealing/ origin reset route selection		2: Y-axis → X-axis	l						0				
				3: X-axis → Y-axis											
56	1695	Thread trimming timing	%?	-2 to 2	-			T			0				
27	E _{fr})	Constant reading of pattern in Smart Media	200	O: Disabled (backup data enabled)	1						0				
				1: Enabled											OVER THE BOOK SECTION AND A SE

	NOTE Well transfer a control for the control of the		The strange control of the Control o	TO THE TOTAL OF THE	Cmollog					Initial value	ilue	ercentral commenters.			
	No.	Item		Setting range	smallest change- able unit	SS/HS 1306	SL/HL 8 1306	SL/HL S 1510 2	SL/HL S 2206 2	SL/HL S	SS/HS 1306 FU05	SL/HL 1306 FU05	SL/HL 1510 FU05	SL/HL 2206 FU05	SL/HL 2210 FU05
28	Sil	Jump command/top position rest time	\odot	0 to 100ms	10ms					20					
29		Input command/timeout period	⊕ ⊕ our	0 to 10000ms (0: No timeout)	100ms					0					
90		End command/ston control	0	0: Ineffective	!					c					
3			P. 0	1: Effective						•					
 		Main motor XY feed synchronizing	‡	0: Standard						c					
			©	1: Extension unit	I					>					
32		Intermediate presser lowering speed		100 to 3000pps	10pps					3000					
33	265 265 267 267	Intermediate presser rising speed	ু কু	100 to 3000pps	10pps					3000					
ç	Ē	Manager Company of the Company of th	8	0: Without						,					
3		Material end detection control Y/N		1: With	1					-					
r.			0-1	0: Without						4					
3			. ******	1: With	I					-					
36		Automatic inversion device Y-axis		0 to 100.0mm	0.1mm					17.0					COMPANIA CONTRACTOR CO
37	2 12 25	XY inching control/first step time	1	100 to10000ms	10ms				:	400	_				
38	5	XY inching control/second step time		100 to 10000ms	10ms					1200	0				
39		XY inching control/max. speed	\$\\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\	100 to 2000pps	10pps	PO-PODACP-OTOLOGICA-NOVEMBERGELES	New Section Co.	THE PASSAGE AND THE PASSAGE AN	- nazaratendenen	1000	(- CONTRACTOR CONTRACTO			

		THE REPORT OF THE PROPERTY OF	decontraction and desired and			CONTROL OF THE PROPERTY OF THE		A CONTRACTOR OF THE PROPERTY O	DAZINI KIRINGA KANDA	Initial value	alue	WOODER TO WAS THE BOOK OF THE			
	No.	Item		Setting range	Smallest change- able unit	SS/HS 1306	SL/HL 1306	SL/HL S 1510	SL/HL 8	SL/HL 2210	SS/HS 1306 FU05	SL/HL 1306 FU05	SL/HL 1510 FU05	SL/HL 2206 FU05	SL/HL 2210 FU05
40		Fixed move-aside position, X-axis		-800.0 to 800.0mm	0.1mm	MODELE CONTRACTOR OF THE PROPERTY OF THE PROPE	est production and the state of	minimostratorem (m. 1876).	ri de la companya de	0	- Marine Children		Commence of the Commence of th		
4	17. 12. 27. 27.	Fixed move-aside position, Y-axis		-800.0 to 800.0mm	0.1mm					0					
42		XY feed move speed/origin. origin → sewing start	i Po÷	100 to 1000pps	10pps					10000	8				
43	7.	XY feed speed/sewing end point → sewing start point/at work clamp foot closed		100 to 10000pps	10pps					10000	00				
44	S.	XY feed speed/sewing end point → sewing start point/at work clamp foot opened	÷91	100 to 10000pps	10pps					2000	0				
45	ZZ	XY feed moving speed/forward/backward	ं•े]	100 to 10000pps	10pps					2000	0				
46	66 131 132	XY feed moving speed/return-to-origin	<u>†</u>	100 to 10000pps	10pps		OCCUPATION OF THE PROPERTY OF			2000	0				
47	ž	XY feed speed/retainer compensation	•ু ়•ংৱ	100 to 10000pps	10pps					2000	0				
48	729	XY feed moving speed/at origin retrieval	-≦ 1 ⊹∘त	100 to 10000pps	10pps					2000	0				
49	K126	XY feed moving speed/direction dependence, first region (X-axis neighborhood)	₩ ;•• sī	100 to 10000pps	10pps					10000	00				
20	[2]. [2]	XY feed moving speed/direction dependence, second region (Y-axis neighborhood)	¾ €	100 to 10000pps	10pps					10000	0				
51	SZ -	XY feed moving speed/direction dependence, third region (45° neighborhood)	 ₩	100 to 10000pps	10pps					10000	0				
			ő	0: None											
-			₽ ₽	1: 2 patterns recognition											
52	5	Bank connection selected terminal count	On I	2: 4 patterns recognition	1					0					W. v. probably
			On xg	3: 8 patterns recognition											
			Ç Ş	4: 16 patterns recognition											THE PERSON NAMED IN THE PE

	SECONDATA SAN CANADA S			NAMES AND DESCRIPTION OF THE PROPERTY OF THE P				The state of the s		Initial value	value	oceanness and a second	criticis de la company de la c	SANSON CONTRACTOR OF THE SANSON SANSON	
	No.	ltem		Setting range	Smallest change-able unit	SS/HS 1306	SL/HL 1306	SL/HL 1510	SL/HL 2206	SL/HL 2210	SS/HS 1306 FU05	SL/HL 1306 FU05	SL/HL 1510 FU05	SL/HL 2206 FU05	SL/HL 2210 FU05
ď		Dracear lifting at tamparany cton array VA	30	0: Without	I	,				_	C				P _{rocess} , Carlon, Process of Carlos, C
3		riessei iiuig at teriporaly stop error ma-		1: With		-				,					
54		Prohibition selection of machine head safety switch	Ę	0: Normal	1						0				00000000000000000000000000000000000000
Note and reference succession and		סמופו) סאווכו		1: Prohibition						,					
55	ā	Model classification		0 to 19	-	1/0	2/3	4/5	2/9	8/8	10/11	12/13	14/15	16/17	18/19
S.	300 to 401	No. 300 to 401 items are applicable only to the simplified panel. For IP-400, the port setting screen is available for input.	ed panel. Fo	r IP-400, the port sett	ing screen is	availab	e for inp	ut.							
56	300	Input terminal 1 assignment		0 to 199	-						0				
1	8			0: LOW							c				akara m inatakan propinsi
<u>`</u>	- - - -	input terminal I active		1: HIGH	I										
58	302	Input terminal 2 assignment		0 to 199	1						0				
ć	C	6 1000		0: LOW		,					c				
Ĉ.	SOS	input terrimal z active		1: HIGH	I										
99	304	Input terminal 3 assignment		0 to 199	-						0				
(L G			0: LOW							c				
5	305	input terminal 3 active		1: HIGH	9900		And the Control of th	Leading of the second s							anno anno controlina (a
62	306	Input terminal 4 assignment		0 to 199	→						0			The second secon	
{	9	4 4		0: LOW							c				ok dak warmio poli fizik Milita
8) S	inpur terminal 4 active		1: HIGH	1										
The second secon		<u>sopiet et annet om et en mannen mannen mannen mannen mannen et annet mannen med en men den men den de de de de</u>	Application of the second of t	<u> Spranschopus Produktoberszerennennen produktoran menskan men men men men men men men men men me</u>	May Care Control with the second second second	Competition of the Competition o	MONTH CONTROL	TO CONTRACT TO CON		NA PERSONAL PROPERTY.	SCENED Second community of the				

	Parent and the parent		NATIONAL DESCRIPTION OF THE PROPERTY OF THE PR			Page 1			Initial value	alue		Syllodesis 200 eventoris mentales sur sur sur sur sur sur sur sur sur su		
Nocky Section 1	No.	ltem	Setting range	Smallest change- able unit	SS/HS 1306	SL/HL 1306	SL/HL 1510	SL/HL 2206	SL/HL 2210	SS/HS 1306 FU05	SL/HL 1306 FU05	SL/HL 1510 FU05	SL/HL 2206 FU05	SL/HL 2210 FU05
64	308	Input terminal 5 assignment	0 to 199	v		G1994 destrokens en managen en fast	NATA PROGRAMMENT AND ADDRESS OF THE PROGRAMMENT AND ADDRESS OF	Chirthern chichenne communication	0	e de la companya de l	Andrews of the second of the s		ł	
ñ	300	Innut terminal 5 activa	0: LOW											
3	8	ייוְשׁמּוֹ נְפְּוֹזְיִיוֹיִיםְ טַ מְּפְנֵּיִעְּפְּ	1: HIGH	*					>					
99	310	Input terminal 6 assignment	0 to 199	-					0					
7	31	Input torminal 6 activa	0: LOW		Personal Control of the Control of t			A THE COLUMN TO						
5	5	יייטען נפוניוווומן ט מכנועפ	1: HIGH	I					o					
89	312	Input terminal 7 assignment	0 to 199	-					0					
000	313	Innut terminal 7 active	0: LOW											
3	2	יייןטען נפוווווומן ז מכוועם	1: HIGH	l					D					311.00 13 p. 17 (14 g. 14 g
02	314	Input terminal 8 assignment	0 to 199	-					0					
7	2. 7.	Inbuit torminal 0 patitus	0: LOW											
	2	יייטער נפון וווומן ט מכוועפ	1: HIGH	ı					5					
72	316	Input terminal 9 assignment	0 to 199	-					0					
73	317	Innut terminal 0 active	0: LOW											
2	5	ייין שני נפון ווווומו פן מכנועפ	1: HIGH	Į.					0					
74	318	Input terminal 10 assignment	0 to 199	-					0					
75	0.00	Invite towning 10 costs.	0: LOW						•					
5	9	input terrilliai 10 acilive	1: HIGH	ł					0					

Manager (C. Accounted							THE REAL PROPERTY AND ADDRESS OF THE PERSONS AND ADDRESS AND ADDRESS OF THE PERSONS AND ADDRESS		Initial value	í			
	No.	ltem	Setting range	change- able unit	SS/HS (1306	SL/HL 1306	SL/HL SL 1510 22	SL/HL SL 2206 22	SL/HL SS/HS 2210 1306 FU05	4S SL/HL 36 1306 35 FU05	SL/HL 1510 FU05	SL/HL 2 2206 FU05	SL/HL 2210 FU05
76	320	Input terminal 11 assignment	0 to 199	-					0				
1	201	Innit towning 11 active	0: LOW						c				
1,	32	iriput terriinai 11 active	1: HIGH	I					o				
78	322	Input terminal 12 assignment	0 to 199	-					0				
Ç 1	C		0: LOW						c				
6/	323	input terminai 12 active	1: HIGH	ı					o				
80	324	Input terminal 13 assignment	0 to 199	-					0				
Č	200	Commission of the commission o	0: LOW						c				***************************************
-	923	III put terriniar 15 active	1: HIGH	I					D				
82	326	Input terminal 14 assignment	0 to 199	-					0	er regermen principal de la cinque de principal de principal de la cinque de la cin			
Ç	1		0: LOW						c				and the sent source of the sent
ž	327	Input terminal 14 active	1: HIGH	l					0				
84	328	Input terminal 15 assignment	0 to 199	-					0				
L C	Ö		0: LOW						c				k <u>adeny</u> ki mendelaka 2008an
င္သ	328	input terminal 15 active	1: HIGH	a company					D		A Committee of the Comm		
98	330	Input terminal 16 assignment	0 to 199	-			**************************************		0				
1	Š		0: LOW						c				aroumiteroechilustikuro
β	33	Input terminal 15 active	1: HIGH			новатропортинеторогом		Endourous Ports of Energia Section 1989)	Messacana negati de sa septil de principo.			

		meneral procession control of the co	THE THE PROPERTY OF THE PROPER	no como constructivo de la companya	and the second s	OCCUPATION OF THE PROPERTY OF	A CATALON CONTRACTOR AND A CATALON A CATALON	Initial value	alue	NATORITO DE CONTROLO DE CONTROL DE CONTRO			
	No.	ltem	Setting range	Smallest change- able unit	SS/HS SL 1306 13	SL/HL SL/HL 1306 1510	SL/HL 2206	SL/HL 2210	SS/HS 1306 FU05	SL/HL 1306 FU05	SL/HL 1510 FU05	SL/HL (2206 FU05	SL/HL 2210 FU05
88	332	Output terminal 1 assignment	0 to 199					-					
g	200	Outent to to a control	0: LOW	3				C					
8	2	Output terrimial I active	1: HIGH	1				>					
06	334	Output terminal 2 assignment	0 to 199	·				2					
3			0: LOW					(BARAS POR THE STREET, SAN
55	335	Output terminal 2 active	1: HIGH	l				0					
92	336	Output terminal 3 assignment	0 to 199	-				4					
S	001	C. tike C. C. Local conserved.	0: LOW					C					
3	/00	Output terminal 3 active	1: HIGH	1	-			O					
94	338	Output terminal 4 assignment	0 to 199	-				7					
Ç	000		0: LOW					C					**************************************
င္တ	655	Output terminal 4 active	1: HIGH	ı	The state of the s	;		0					
96	340	Output terminal 5 assignment	0 to 199	-			1	0					
07	22	Outhout torminal 6 active	0: LOW					c					
5	5	כתוחת נפונווו ומו כן מכוועם	1: HIGH					o					
86	342	Output terminal 6 assignment	0 to 199	-				0					
S		0 1 mm of 4 mm	0: LOW					C					Andrews Etiliber
86	2+0	Output terrificat o active	1: HIGH	I	N		deen Kataban eit Matheth de belannen een	0	historia anticomina periodi di della				

	CONTRACTOR		оринической ретельного Роск Ментельного серений профессионального по поделения в поделения по поделения в поде В поделения в	Angeres de consequence de consequenc	edecarramente de la companya del companya de la companya del companya de la compa	A STATE OF THE STA	THE CONTRACT OF STREET, STREET	Manager to company of the last	Initial value	alue	040044	THE RESERVE OF THE PERSON OF T		
	No.	ltem	Setting range	Smallest change- able unit	SS/HS 1306	SL/HL 1306	SL/HL S 1510 2	SL/HL 8	SL/HL 92210	SS/HS 1306 FU05	SL/HL 1306 FU05	SL/HL 1510 FU05	SL/HL 2206 FU05	SL/HL 2210 FU05
100	344	Output terminal 7 assignment	0 to 199	-					0	Opposite Property		Landerston - Province	- Committee of the Comm	The state of the s
Š	770	C. ibac 7 Laci man at the sate of	0: LOW						c					
<u> </u>	345	Output terminal / active	1: HIGH	1					>					
102	346	Output terminal 8 assignment	0 to 199	-					0					
(į	-	0: LOW						(NOON CALCIUM ENGAGE
103	347	Output terminal 8 active	1: HIGH	ı					0					
104	348	Output terminal 9 assignment	0 to 199	τ-					0					
L C	6		0: LOW											
<u>S</u>	349	Output terminal 9 active	1: HIGH	1					5					
106	350	Output terminal 10 assignment	0 to 199	-					0					
Ş	Ĺ		0: LOW						c					HALIDON IN JANUTAN PYROT
2	- cs	Output terminal to active	1: HIGH	I					>					
108	352	Output terminal 11 assignment	0 to 199	-					0					
Ç	C L	O date to the second and the second of the s	0: LOW						c					
2 2	333	Output terminal 11 active	1: HIGH	1					>					
110	354	Output terminal 12 assignment	0 to 199	-		***************************************	Mary Active property or vacant management of the Constitution of t	- Part of the Control	0			enejerjerinkerserrenene betrekten de um terrekten bet		
4	L L	C. share C. A. San	0: LOW						c					O
_	CC5	Output terminal 12 active	1: HIGH		ASSAULTANT PROPERTY CONTRACTOR AND PROPERTY CONTRACTOR	. Hotelstein ein ein ein ein ein ein ein ein ein	NA PROPERTY AND PR	Petricularisment (1997)	>		stel sominanten den del		10 to	

				NAMES OF THE PARTY	o promote a superior de la companya	Westerlanderschaft		dermostoevh0rothermos	anley leitin	91	THE CONTRACTOR OF THE PROPERTY		A CONTRACTOR AND A CONT	
	No.	ltem	Setting range	Smallest change- able unit	SS/HS 5	SL/HL S 1306 1	SL/HL SI 1510 2	SL/HL S 2206 2	SL/HL St	S 0 12	SL/HL 8 1306 FU05	SL/HL 1510	SL/HL 2206	SL/HL 2210
112	356	Output terminal 13 assignment	0 to 199	-					0	-		-		
<u>+</u>	357	Output terminal 13 active	0: LOW	:										
			1: HIGH	**CO					0					ki effetik i ki iliyele jeweyen
114	358	Output terminal 14 assignment	0 to 199	-		The state of the s			0					
U T	C C		0: LOW											
CII	Acc	Output terminal 14 active	1: HIGH	1					0					
116	360	Output terminal 15 assignment	0 to 199	-					0					
17	796	Outbut terminal 15 activa	0: LOW	-										
	3	כמוסמו וכוווווומו וכו מכוועם	1: HIGH	ı					0					
118	362	Output terminal 16 assignment	0 to 199	4					0					
2.0	363	Outhough to making	0: LOW					7						
2	3	סמקטו נפווווומן זס מכוועם	1: HIGH	ı					0					**
120	364	Virtual I/O terminal 1 assignment	0 to 199	-					0					
121	365	Virtual I/O terminal 1 I/O solostion	0: Input											
!	3		1: Output	ı					0					
122	366	Virtual I/O terminal 2 assignment	0 to 199	-					0					
23	367	With ial I/O terminal 9.1/0 acitacitas	0: Input											
	3		1: Output	-					0					Mariana o calametri de

	modes by mesself research	мень режи документа на подорож под меня и подорожно под меня и подорожно под	jūsydoplasiskai keroviniojojisis irat nekoteminina economera novemoni devininda			Cort are now the recognitive state of the State	de applicamente de la composition della composit	NUTVINEEN PROFESSION	Initial value	alue				
	No.	ltem	Setting range	Smallest change- able unit	SS/HS 1306	SL/HL 1306	SL/HL S 1510 2	SL/HL S 2206 2	SL/HL 82210	SS/HS 1306 FU05	SL/HL 1306 FU05	SL/HL 1510 FU05	SL/HL 2206 FU05	SL/HL 2210 FU05
124	368	Virtual I/O terminal 3 assignment	0 to 199	1					0					
30.	360	With 10 thought 2 10 coloration	0: Input						c					yalance to the transfer of the
	60 00	VII.Laa I/O terriiiria 3 I/O serecilori	1: Output	l					>					
126	370	Virtual I/O terminal 4 assignment	0 to 199	-					0					
1	į		0: Input						C					**************************************
12/	3/1	Virtual I/O terminal 4 I/O selection	1: Output	ı					0					
128	372	Virtual I/O terminal 5 assignment	0 to 199	-					0					
5		- cite (1-1 O) = 1 = 1 = 1 + 1/1	0: Input	7					c					topica di Sistema Incom
S V	5/5	Virtual I/O terminal 3 I/O selection	1: Output						>					
130	374	Virtual I/O terminal 6 assignment	0 to 199	γ-	,				0					
Č	, 1		0: Input						c					
5	3/3	Virual I/O terminal o I/O selection	1: Output	I					>					
132	376	Virtual I/O terminal 7 assignment	0 to 199	-	·				0					
Ç		acita class Old Common of Old Incitativ	0: Input						c					26/001
5	//6	Virual I/O terminal / I/O selection	1: Output	I					>					
134	378	Virtual I/O terminal 8 assignment	0 to 199	-					0					
0.0	270	entirolog () 1 0 Indiana () 1 Indiana	0: Input	T					<u></u>					
2	8 6	Vitual vO terrillia o vO serection	1: Output	naan .					>					
	Chiefeloreprotection				WITH THE PERSON NAMED AND ADDRESS OF THE PERSON NAMED AND ADDR									

	TOTAL STREET, TO				NAMES AND ADDRESS OF THE PROPERTY OF THE PROPE	Marrie Construction of the		4	Initial value	**************************************	TOTAL CONTINUES OF THE OWNER OWN		
	No.	Item	Setting range	change- able unit	SS/HS 1306	SL/HL 1306	SL/HL SL 1510 22	SL/HL SL 2206 22	SL/HL SS/HS 2210 1306 FU05	4S SL/HL 6 1306 15 FU05	SL/HL 1510 FU05	SL/HL 2206 FU05	SL/HL 2210 FU05
136	380	Virtual I/O terminal 9 assignment	0 to 199	-	A CONTRACTOR OF THE PROPERTY O	service recognition and continued deposition of the contin	A CONTRACTOR OF THE CONTRACTOR		0				
137	200	Virtual I/O terminal Q I/O calamion	0: Input			-							
2	3		1: Output	l					5				
138	382	Virtual I/O terminal 10 assignment	0 to 199	-					0				
30	or or	Section 10 Miles from the Control of	0: Input										
2	000	VII.wa I/O (eiri iiriai 10 I/O sejection	1: Output	1					0				Vario
140	384	Virtual I/O terminal 11 assignment	0 to 199	-					0				
,	ос п	Cite of the local control of t	0: Input										
<u> </u>	99		1: Output	ı					0				**************************************
142	386	Virtual I/O terminal 12 assignment	0 to 199	-					0				
1/3	387	Mithing 10 Million to Michigan	0: Input										
}	ò		1: Output	ı					0				<u></u>
144	388	Virtual I/O terminal 13 assignment	0 to 199	-					0				
145	380	With Isl I/O terminal 13 I/O colonius	0: Input						· ·				
2	890		1: Output	f					0				
146	390	Virtual I/O terminal 14 assignment	0 to 199	-				***************************************	0				
147	301	With Isl IV terminal 14 IV.	0: Input						(
È	60		1: Output	-	A PARTICIPATION OF THE PARTICI				0				

	deconstant velocements.			Section of the sectio	No. of the last of	Nomes and the fact that the function is		A THE RESIDENCE OF THE PARTY OF	Initial value	alue	THE CONTRACTOR OF THE CONTRACT		selvenzankoldekindultskildekindu	
	No.	ltem	Setting range	Smallest change- able unit	SS/HS 1306	SL/HL 1306	SL/HL S 1510 ,	SL/HL 2206	SL/HL 2210	SS/HS 1306 FU05	SL/HL 1306 FU05	SL/HL 1510 FU05	SL/HL 2206 FU05	SL/HL 2210 FU05
148	392	Virtual I/O terminal 15 assignment	0 to 199	-					0					
5	c c	Virtual IV terminal 15 1/0 and order	0: Input						c					
- 1 2	280		1: Output	ì					>					
150	394	Virtual I/O terminal 16 assignment	0 to 199	τ-					0					
ļ	(0: Input	ľ					(
T6T	395	Virtual I/O terminal 16 I/O selection	1: Output	ı					o					
			0: LOW						ı					
152	396	Pedal SW1 active	1: HIGH	1					0			,		
(L	ľ		0: LOW						C					
3	786	Pedal SWZ active	1: HIGH	1					D				La caración de la car	
Li T	o c	Dodo! CMO cat.	0: LOW						c					PHONE OF PARTY CORDS
2	0 60	redal SWS active	1: HIGH						>					
L L	C	T T T T T T T T T T T T T T T T T T T	0: LOW						c					
င္ပ	388	Pedal SW4 active	1: HIGH	2					O					
() [] T	Ç	Ober OW costs	0: LOW						c					COMMISSION OF STREET
8	90+	olari ovy active	1: HIGH	1	endedand to Typy yn megawaaa				>					
ļ	Š	T	0: LOW						•					
/C	5	remporary stop SW active	1: HIGH	and the state of t	TAXABLE CONTRACTOR CON	CHEROLOGICAL CONTROL C	uma en estado de deserva estado de deserva de la como en estado de estado de estado de estado de estado de esta	SAMOON CANADANA AND COMPANY	THE PROPERTY OF THE PROPERTY O	NAKOROBODOWANIATIA	eronnearente (et heroniete			

5. Supplemental remarks of each function number and explanation of each function

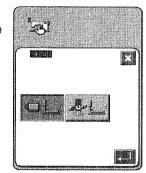
(1) Feeding frame operational sequence setup

For the AMS-210E, it is possible to change the method of feeding frame and pedal operation by means of a memory switch.

1. Presser driving type setup

Using the memory switch K74, it is possible to set up the feeding frame of the pulse motor driving type and the air driving type.

Setup	Contents	Explanation
CP20: 0	Pulse motor driving	AMS210ESS/EHS-1306
co <u>!</u> CP20: 1	Air driving	AMS210ESL/EHL-1306/1510/2206/2210



2. Feeding frame driving way setup

By changing the memory switches K80 and K83, it is possible to set up feeding frame and pedal operation.

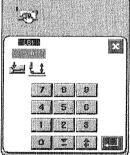
(1) Automatic lowering or lifting

The memory switch K80 is used to set up the operational sequence of the feeding frame, irrespective of pedal operation at the time of READY key ON, feeding frame lifting with a temporary stop command in the pattern data, presser lowering key ON, and so on.

Setup	Contents	Explanation
0 to 99	All lowering, all lifting	All lowering, all lifting only

(2) Feeding frame ON/OFF operational sequence by ordinary pedal operation Using the memory switch U81, it is possible to set up the operational sequence of the feeding frame by ordinary pedal operation.

In regard to the setup items, refer to the [(5) List of feeding frame and pedal setup].



(3) Feeding frame ON/OFF operational sequence by a temporary stop command Using the memory switch U82, it is possible to set up the operational sequence of the feeding frame by pedal operation while the feeding frame is lifted by a temporary stop command in the pattern data.

In regard to the setup items, refer to the [(5) List of feeding frame and pedal setup].

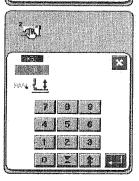
201 7 0 9 4 5 6 1 2 3 0 2 4 4

(4) Feeding frame lifting at the end of sewing

Using the memory switch K83, it is possible to set up the feeding frame lifting position in the returning phase from the end of sewing position (end of pattern data) to the start of sewing position.

Setup	Contents	Explanation
0	Lifting position	The feeding frame is lifted to the top.
1	2-step stroke position	The feeding frame is lifted to the intermediate position
2 to 99	Lifting position	The feeding frame is lifted to the top.

(Caution) This function is enabled with the memory switch U37 when feeding frame lifting has been set up at the end of sewing.



[(5) List of feeding frame and pedal setup]

Setup	Contents	Preference	Explanation
0	United clamp		Lowered to the bottom by Pedal 1.
1	United clamp, 2-step stroke	_	Lowered to the intermediate position by Pedal 1 (right). Lowered to the bottom by Pedal 2 (left).
2	United clamp, 2-step stroke	-	Lowered to the intermediate position by Pedal 1. Lowered to the bottom by the start pedal to start sewing.
3	United clamp 2-step stroke	_	Lowered to the mid-point position by the first action of the presser pedal 1. Lowered to the bottom position by the second action. Raised by the third action.
4 to 99	United clamp	_	Lowered to the bottom by Pedal 1.

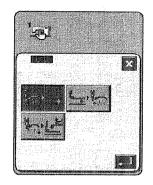
For air driving

Setup	Contents	Preference	Explanation
0	United clamp	_	Lowered to the bottom by Pedal 1.
1	Right/left separation clamp	Lowering enabled from the right or left	The right feeding frame is lowered to the bottom by Pedal 1 (right). The left feeding frame is lowered to the bottom by Pedal 2 (left).
2	Right/left separation clamp	Lowered from the right.	The right feeding frame is lowered to the bottom by Pedal 1 (right), then the left feeding frame is lowered to the bottom by Pedal 2 (left). The left feeding frame is not lowered unless the right feeding frame has been lowered.
3	Right/left separation clamp	Lowered from the left.	The left feeding frame is lowered to the bottom by Pedal 2 (left), then the right feeding frame is lowered to the bottom by Pedal 1 (right). The right feeding frame is not lowered unless the left feeding frame has been lowered.
4	United clamp, 2-step stroke	_	The feeding frame is lowered to the intermediate position by Pedal 2 (left), then lowered to the bottom by Pedal 3 (left treading-on).
5	Right/left separation clamp, left 2-step stroke	Lowering enabled from the right or left	The right feeding frame is lowered to the bottom by Pedal 1 (right), then the left feeding frame is lowered to the intermediate position by Pedal 2 (left intermediate). The left feeding frame is lowered to the bottom by Pedal 3 (left treading-on).
6	Right/left separation clamp, left 2-step stroke	Lowered from the right.	The right feeding frame is lowered to the bottom by Pedal 1 (right), then the left feeding frame is lowered to the intermediate position by Pedal 2 (left intermediate). The left feeding frame is lowered to the bottom by Pedal 3 (left treading-on). The left feeding frame is not lowered unless the right feeding frame has been lowered.
7	Right/left separation clamp, left 2-step stroke	Lowered from the left.	The left feeding frame is lowered to the intermediate position by Pedal 2 (left intermediate), then lowered to the bottom by Pedal 3 (left treading-on). Since then, the right feeding frame is lowered to the bottom by Pedal 1 (right). The right feeding frame is not lowered unless the left feeding frame has been lowered.
8 to 99	United clamp	name.	Lowered to the bottom by Pedal 1.

3. Feeding frame lifting setup at the end of sewing

Using the memory switch U37, it is possible to set up the timing for feeding frame lifting at the end of sewing.

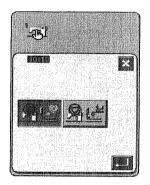
Setup	Contents	Explanation
CP20: 0	After the start of sewing reset	The feeding frame is lifted after the movement from the end of sewing to the start of sewing.
CP20: 1	Before the start of sewing reset	The feeding frame is lifted at the end of sewing. The movement is forwarded from the end of sewing to the start of sewing with the feeding frame left lifted.
CP20: 2	Pedal operation after the start of sewing reset	The feeding frame is lifted by the pedal after the movement from the end of sewing to the start of sewing.



4. Feeding frame lifting setup at the time of temporary stop

Using the memory switch U41, it is possible to set up the timing for feeding frame lifting when it has been set up with a temporary stop command in the pattern data.

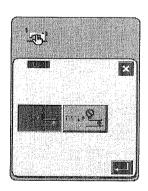
Setup	Contents	Explanation
11.9	Lifting	The feeding frame is lifted immediately with the temporary stop command.
CP20: 0		·
2-1	Pedal operation	Lifted by pedal operation with the temporary stop command. Sewing is started by the start pedal with the feeding frame left lowered.
CP20: 1		



5. Feeding frame lifting prohibition setup

Using the memory switch U38, it is possible to make setting up with the feeding frame kept lowered at all times.

Setup	Contents	Explanation
CP20: 0	Pedal operation	It is possible to lift or lower the feeding frame by pedal operation.
CP20: 1	Always lowered	The feeding frame is kept lowered even after origin retrieval and moving at the sewing start. Lifting and lowering of the feeding frame by pedal operation are also disabled.



6. Presser pedal setup

Using the memory switches U84 ~ U87 below, it is possible to set up the method of pedal operation.

U84: Used to set up the method of pedal operation for Pedal 1. (Standard pedal, PK47 right)

U85: Used to set up the method of pedal operation for Pedal 2.

(PK47 left intermediate)

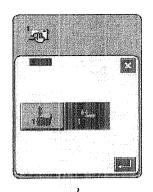
U86: Used to set up the method of pedal operation for Pedal 3.

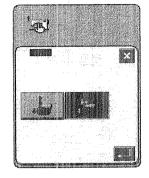
(PK47 left treading-on)

U87: Used to set up the method of pedal operation for Pedal 4.

(Not used)

gramman management and an arrangement and		
Setup	Contents	Explanation
CD00-0	Non-latch	The feeding frame is lowered only if the pedal is trodden on. It is lifted when the pedal is released.
CP20: 0		
11.	Latch	The feeding frame is lowered when the pedal is trodden on once. It is left lowered ven when the pedal is released. It is lifted when the pedal is trodden on secondly.
CP20: 1		





(2) Fixed refuge position setup

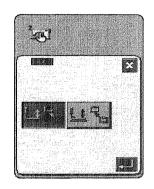
Irrespective of the second origin in the pattern data, a memory switch is available to set up the second origin (fixed refuge position) that is common to each pattern.

When the use of the fixed refuge position has been set up with the memory switch K90, the fixed refuge position becomes enabled, which has been set up with the fixed refuge position Coordinate X of Memory Switch K117 and the fixed refuge position Coordinate Y of Memory Switch K118. In this state, the feeding frame can be ready in the same position even though any pattern is used for sewing.

1. Selection of the fixed refuge position

Using the memory switch K90, it is possible to set up the fixed refuge position.

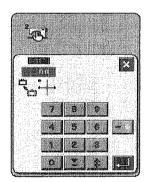
Setup	Contents	Explanation
15.1 CP20: 0	Fixed refuge position disabled	The fixed refuge position is not used.
_1 ⁽ \] CP20: 1	Fixed refuge position enabled	The fixed refuge position is used.



2. Fixed refuge position coordinates setup

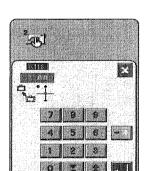
Using the memory switch K117, it is possible to set up the fixed refuge position Coordinate X.

Setup Contents		Explanation		
B .	Coordinate X of the fixed refuge position	Coordinate X of the fixed refuge position is set up within the feeding frame in the unit of 0.1mm.		



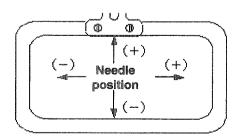
Using the memory switch K118, it is possible to set up the fixed refuge position Coordinate Y.

Setup	Contents	Explanation
Coordinate Y	Coordinate Y of the fixed refuge position	Coordinate Y of the fixed refuge position is set up within the feeding frame in the unit of 0.1mm.



(Caution) Coordinate X is (+) when the needle position is right of the origin. It is (-) when the needle position is left of the origin.

Coordinate Y is (+) when the needle position is behind the origin. It is (-) when the needle position is in front of the origin.



(3) Bank function setup

The bank function means a function of sewing effected through changeover to a pattern by an external signal, which is registered in multiple pattern buttons in cases of cassette discrimination and others.

For sewing by the bank function, an external signal input is entered before the feeding frame is lowered at the time of pedal treading-on. According to the input condition, a maximum of 16 patterns can be used for changeover. When the bank function is used, the fixed refuge position preset in regard to "5.-(2) Fixed escape position setting" is automatically enabled.

The reason is that the feeding frame in ordinary operation is made ready at the start of sewing (or the second origin). This function is always possible if there is only one sewing pattern. In the case of the bank function, however, the next sewing pattern is not always coinciding with the previous sewing pattern (or the second origin) at the start of sewing. Therefore, it is necessary to use this refuge position function to secure the same standby position for the feeding frame.

- 1. It is not always necessary to set up the memory switch K90 because the fixed refuge position mode is automatically secured for the bank function.
- 2. The fixed refuge position, defined by the fixed refuge position Coordinate X of Memory Switch K117 and the fixed refuge position Coordinate Y of Memory Switch K118, is regarded as the standby position of the feeding frame for the bank function.

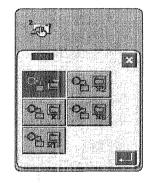
In standard setting, the feeding frame stops at the origin because the conditions are set at X:0 and Y:0. An arbitrary position can be set up with the memory switches K117 and K118.

The bank functions and the input terminals can be set up with the following memory switches:

(1) Bank function setup

The memory switch K130 is used to set up the number of banks (quantity of input terminals).

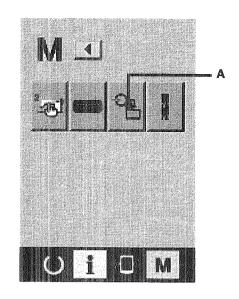
Setup	Contents	Explanation
O≟ (≧ CP20: 0	Bank disabled	The bank function is not used.
O ₃ (a)	No. of banks 2	Two patterns are set for the number of banks. One Input Terminal 0 is used.
On Market CP20: 2	No. of banks 4	Four patterns are set for the number of banks. Two Input Terminal 0 to 1 are used.
O₂	No. of banks 8	Eight patterns are set for the number of banks. Three Input Terminal 0 to 2 are used.
○-	No. of banks 16	Sixteen patterns are set for the number of banks. Four Input Terminal 0 to 3 are used.

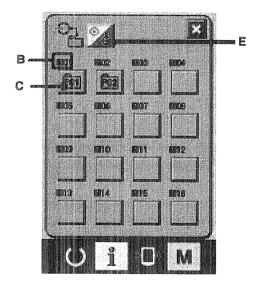


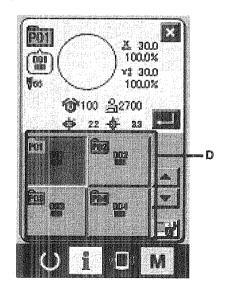
(2) External input terminal setup

The input terminal numbers to be used for the bank function are set up.

1. IP-400







1) Bank function setup screen display

When the number of K1301 bank connection select terminals is preset for the memory switch data (Level 2), the bank function button (A) is displayed on the mode changeover screen. When this button is pressed, the bank function setup screen is displayed.

2) Registration of the direct pattern number

When the direct pattern number registration button (C) is pressed for a setting input terminal number (B), the direct pattern number selection screen is displayed. However, the selectable direct pattern numbers are limited only for the individual sewing. The direct pattern number to be registered for the input terminal is selected as indicated by (D).

3) Bank function setup

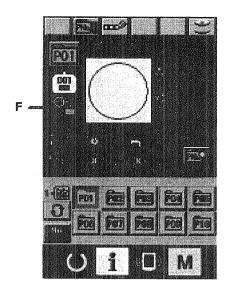
The bank function can be set up through changeover operation of the bank function setup button (E).

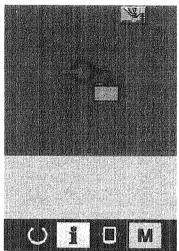


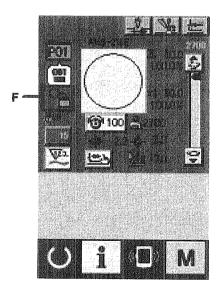
: Bank function turned ON



: Bank function turned OFF







When the bank function setup screen is closed and the data input screen is displayed, a pictograph (F) for indicating the ON status is displayed if the bank function is turned ON.

When the key is pressed, the bank mode screen is displayed.

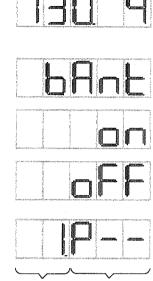
When the presser is lowered, the direct pattern sewing screen is displayed and sewing can be carried out.

For the direct patterns to be displayed on the sewing screen, the pattern numbers are automatically changed over if there is coincidence of an input with the relevant input terminal.

2. CP-20

The bank input terminals 0 to 3 (input Nos. 3 to 6) are assigned to arbitrary input terminals of the memory switches Nos. 300 ~ 331.

- 1) When the M key is continuously pressed for 6 seconds in the state that the sewing LED is unlit, the service setup mode is assumed for the memory switches and the bank mode is set up.
 - → In regard to the method of memory switch setup, refer to the section of memory switch data change of the Instraction Manual.
- 2) Using the +/ and -/ keys, select the bank mode and press the \bigcirc key. The sewing Led is then lit up.
- 3) Make $+/\stackrel{+}{\sqsubseteq}$ and $-/\stackrel{-}{\sqsubseteq}$ key setting for bank mode ON or OFF. Press the $\stackrel{\square}{\smile}$ key.
- 4) Register the direct pattern number for the input terminal. Input terminal changeover is possible with the key. The direct pattern number can be selected with the hard and keys.
- 5) Press the key to register the contents of setup. The sewing LED is unlit and the status of memory number selection is recovered.
- 6) Press the M key to close the memory switch setup mode. The normal status is then recovered.



The upper 2 The lower 3 digdigits denote the the input terminal number.

Relationship between bank input terminals and bank numbers

Input terminal		Input terminal		Input terminal		Input terminal	
3 2 1 0	Bank number	3 2 1 0	Bank number	3 2 1 1 0	Bank number	3 2 1 0	Bank number
HIHIHIH	Bank No. 1	HILIHIH	Bank No. 5	LIHIHIH	Bank No. 9	LiLiHiH	Bank No. 13
H'H'H'L	Bank No. 2	H'L'H'L	Bank No. 6	LHHL	Bank No. 10	L¦L¦H¦L	Bank No. 14
H	Bank No. 3	H'L'L'H	Bank No. 7	L H L H	Bank No. 11	L¦L¦L¦H	Bank No. 15
H	Bank No. 4	H¦L¦L¦L	Bank No. 8	LHLLL	Bank No. 12	L L L L L	Bank No. 16

H: High, L: Low (when bank input active = Low)

(4) Port I/O setup

This sewing machine is provided with the machine control functions that are enabled only by the machine main body through the generation of signal outputs to the outside and the reception of signal inputs from the outside, without the intervention by any appropriative I/O unit and other devices.

By making connections with proper external sequencers (programmable controllers) or using the simplified sequencer functions that are available at the main body, the machine is possible to be modified into a mechanical system of various annex units.

1. Input terminal setup

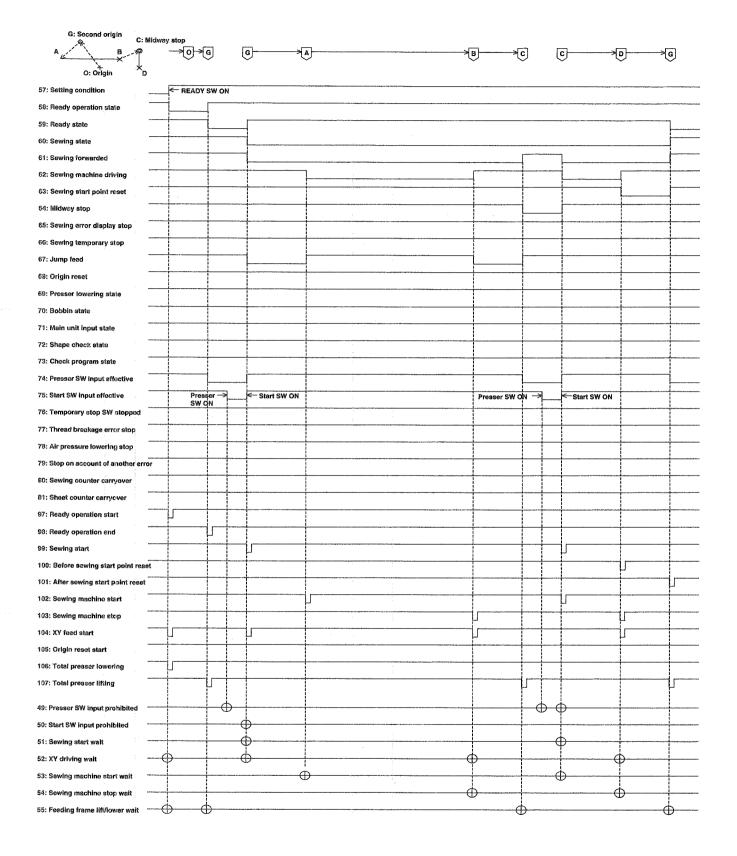
Input No.	Contents	Explanation	
0	Nil	No input	
For the actuat	tor	-	
1	Void		
2	Detection of material end	Detection of material end is enabled with the first Mark 1 command of the pattern data.	
	sensor	When the input terminal becomes active, the section to the second Mark 1 command is skipped.	
3	Bank input 0	Input terminal 0 when the bank function is selected	
4	Bank input 1	Input terminal 1 when the bank function is selected	
5	Bank input 2	Input terminal 2 when the bank function is selected	
6	Bank input 3	Input terminal 3 when the bank function is selected	
For pattern da	ata inputs		
33	External input 0	Sewing is suspended until the input terminal becomes active with the External Input 0 command of the pattern data.	
34	External input 1	Sewing is suspended until the input terminal becomes active with the External Input 1 command of the pattern data.	
35	External input 2	Sewing is suspended until the input terminal becomes active with the External Input 2 command of the pattern data.	
36	External input 3	Sewing is suspended until the input terminal becomes active with the External Input 3 command of the pattern data.	
37	External input 4	Sewing is suspended until the input terminal becomes active with the External Input 4 command of the pattern data.	
38	External input 5	Sewing is suspended until the input terminal becomes active with the External Input 5 command of the pattern data.	
39	External input 6	Sewing is suspended until the input terminal becomes active with the External Input 6 command of the pattern data.	
40	External input 7	Sewing is suspended until the input terminal becomes active with the External Input 7 command of the pattern data.	
41	External input 8	Sewing is suspended until the input terminal becomes active with the External Input 8 command of the pattern data.	
42	External input 9	Sewing is suspended until the input terminal becomes active with the External Input 9 command of the pattern data.	
43	External input 10	Sewing is suspended until the input terminal becomes active with the External Input 10 command of the pattern data.	
44	External input 11	Sewing is suspended until the input terminal becomes active with the External Input 11 command of the pattern data.	
45	External input 12	Sewing is suspended until the input terminal becomes active with the External Input 12 command of the pattern data.	
46	External input 13	Sewing is suspended until the input terminal becomes active with the External Input 13 command of the pattern data.	
47	External input 14	Sewing is suspended until the input terminal becomes active with the External Input 14 command of the pattern data.	
48	External input 15	Sewing is suspended until the input terminal becomes active with the External Input 15 command of the pattern data.	
Operation pro	hibit / weight request		
49	Presser SW input prohibited	Entry of presser switch 1 to 4 inputs is prohibited in active phase.	
50	Start SW input prohibited	Entry of start switch inputs is prohibited in active phase.	
51	Sewing start wait	Start of sewing start switch operation is waited in active phase. Sewing is started in non-active phase. This signal is disregarded in the middle of sewing.	
52	XY motor start wait	Start of XY motor driving is waited in active phase. The XY motor driving is started in non-active phase. This signal is disregarded in the middle of XY motor driving.	
53	Sewing machine start wait	Start of sewing machine head rotation is waited in active phase. Intermediate presser lowering and sewing machine head rotation are started in non-active phase. Upper position reset is not included. This signal is disregarded in the middle of sewing machine head driving.	
54	Sewing machine stop wait	Operation is suspended after the stoppage of sewing machine head rotation and wiper and intermediate presser lifting operation in active phase. Subsequent operation is started in non-active phase. Upper position reset is not included. This signal is disregarded in the middle of sewing machine head driving.	
55	Feeding frame vertical motion wait	Total lifting and lowering of the feeding frame is suspended in active phase. Total lifting and lowering of the feeding frame is performed in non-active phase. Feeding frame lifting and lowering are not included at the time of presser pedal operation.	

2. Output terminal setup

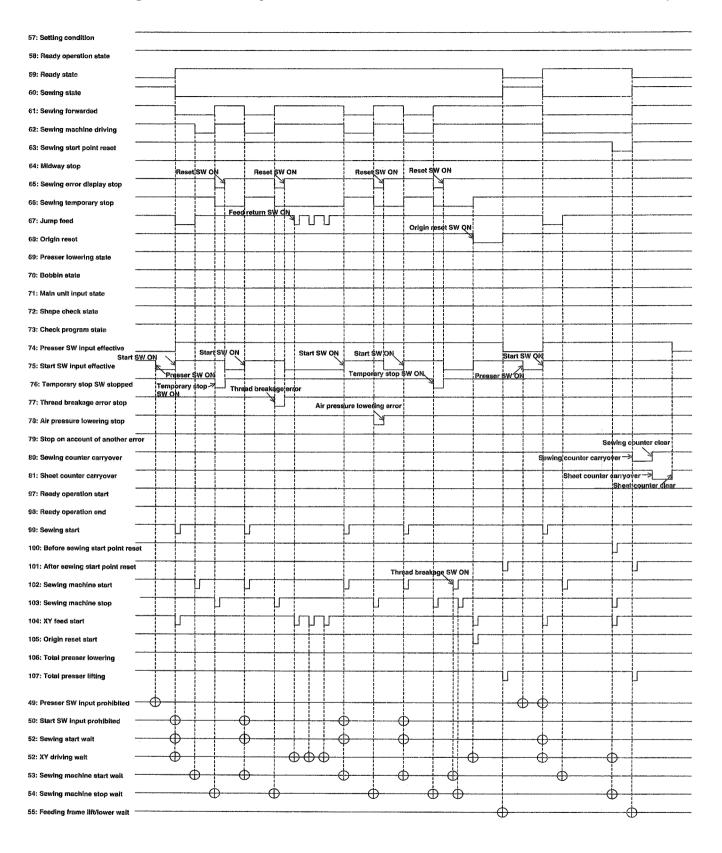
Output No.	Contents	Explanation			
0	Nil	No output			
For the actua					
1	Feeding frame 1	Feeding frame right lifting			
2	Feeding frame 2	Feeding frame left lifting			
3	Feeding frame 3	(Feeding frame right 2-stage stroke)			
4	Feeding frame 4	Feeding frame left 2-stage stroke			
5	(Intermediate presser)	(Signal output)			
6	Void				
7	Reverse shaft	Reverse shaft setting side			
8	Third thread tension	Third thread tension closed			
9	Needle cooler	Needle cooler air output			
or pattern da		Troods cooks all output			
33	External output 0	Reverse signal output with the External Output 0 command of the pattern data			
34	External output 1				
35	External output 2	Reverse signal output with the External Output 1 command of the pattern data			
36		Reverse signal output with the External Output 2 command of the pattern data			
	External output 3	Reverse signal output with the External Output 3 command of the pattern data			
37	External output 4	Reverse signal output with the External Output 4 command of the pattern data			
38	External output 5	Reverse signal output with the External Output 5 command of the pattern data			
39	External output 6	Reverse signal output with the External Output 6 command of the pattern data			
40	External output 7	Reverse signal output with the External Output 7 command of the pattern data			
41	External output 8	Reverse signal output with the External Output 8 command of the pattern data			
42	External output 9	Reverse signal output with the External Output 9 command of the pattern data			
43	External output 10	Reverse signal output with the External Output 10 command of the pattern data			
44	External output 11	Reverse signal output with the External Output 11 command of the pattern data			
45	External output 12	Reverse signal output with the External Output 12 command of the pattern data			
46	External output 13	Reverse signal output with the External Output 13 command of the pattern data			
47	External output 14	Reverse signal output with the External Output 14 command of the pattern data			
48	External output 15	Reverse signal output with the External Output 15 command of the pattern data			
	ring machine head	The verse signal output with the External Output 15 command of the pattern data			
49		Library characters are like as a fine control of the control of th			
50	Needle upper position	Upper stop position 40 to 62° (Always ON shortly after Power ON)			
	Needle lower position	(Internal signal) 80 to 123° (Always OFF shortly after Power ON			
51	Needle upper dead point position	Reverse rotation needle lifting position 5 to 30° (Always OFF shortly after Power ON			
52	Needle lower dead point position	Lower stop position 209 to 239° (Always OFF shortly after Power ON			
53	Thread trimming signal	During thread trimming stop (not used) ON beneath the needle shortly before stoppage - OFF at +70ms above the needle			
54	During rotation	In the middle of sewing machine driving ON at the start of rotation → OFF at +120ms above the needle			
55	Sewing machine brake signal	During sewing machine stop ON beneath the needle shortly before stoppage OFF at +120ms above the needle			
56	Void	OTT ALTIZOTIS ADOVE LITE HEEQIE			
	ing machine unit				
57	Status of setup	In the setup condition			
58		In the setup condition			
	Status of READY operation	Ready key → Origin retrieval → Moving to the sewing start point and thereafter			
59	READY status	In the ready condition			
60	Sewing status	From the start of sewing to the feeding frame lifting after moving to the sewing start poir Feed forward included.			
61	During sewing	From the start of sewing to the end of pattern data. Jump feed included.			
62	Sewing machine in driving	In the middle of sewing machine head driving during sewing. Bobbin and needle lifting res			
63	Resetting to the sewing start point	From the end of pattern data to the reset of the sewing start point.			
64	Sewing being stopped on the way	Stopped with a midway stop command of the pattern data.			
	Stop with sewing error display	Error display being presented because of error stop during sewing.			
65		From stop during sewing or temporary stop after the promotion of attacking due to act			
65 66	Temporary stop of sewing	check, etc.			
65	Temporary stop of sewing XY feeding operation				
65 66	Temporary stop of sewing				

Output No.	Contents	Explanation	
70	Bobbin status	Bobbin key → Bobbin status	
71	Main unit input status	Main unit input key → Main unit input status	
72	Pattern check status	Pattern check, thread tension / intermediate presser height command setup	
73	Last mode status	Last mode status (Sewing machine revolutions / output / XY / presser thread cutter / thread	
		clamp / intermediate presser test mode)	
74	Presser SW input effective	When the presser switch input is effective	
75	Start SW input effective	When the start switch input is effective	
76	Temporary stop SW turned OFF	Temporary stop switch error (E050) being displayed (E050). OFF by reset.	
77	Thread breakage error OFF	Thread breakage error (E052) being displayed. OFF by reset.	
78	Air pressure being lowered	Air pressure low error (E031) being displayed. OFF by reset.	
79	Other errors being present	Errors other than 76 to 78 being displayed. OFF by reset.	
80	Sewing counter carryover	Sewing counter carryover being displayed. OFF by counter reset.	
81	Sheet counter carryover	Sheet counter carryover being displayed. OFF by counter reset.	
For the trigger			
97	READY operation start	When the READY key is accepted. ON for 100ms.	
98	READY operation end	After moving to (READY key \rightarrow) sewing start point. ON for 100ms.	
99	Sewing start	When the Start switch is accepted. (Normal / Midway stop / Temporary stop). ON for 100ms.	
100	Before sewing start point reset	Before sewing start point reset (after pattern data end). ON for 100ms. Origin reset not	
		included.	
101	After sewing start point reset	After sewing start point reset (before feeding frame lifting). ON for 100ms. Origin reset in-	
		cluded.	
102	Before sewing machine start	Before sewing machine head driving (before feeding frame lowering). ON for 100ms.	
103	After sewing machine stop	After sewing machine head stop (after wiper and before feeding lifting). ON for 100ms.	
104	Before jump feed start	Jump feed operation / Feed forward / Return operation. ON for 100ms.	
105	Before origin reset start	When the origin reset key is accepted. ON for 100ms.	
106	Before total presser lowering	At the time of total presser lowering (Ready, threading, bobbin, etc.). ON for 100ms.	
107	Before total presser lifting	At the time of total presser lifting (Ready, threading, bobbin, etc.). ON for 100ms.	

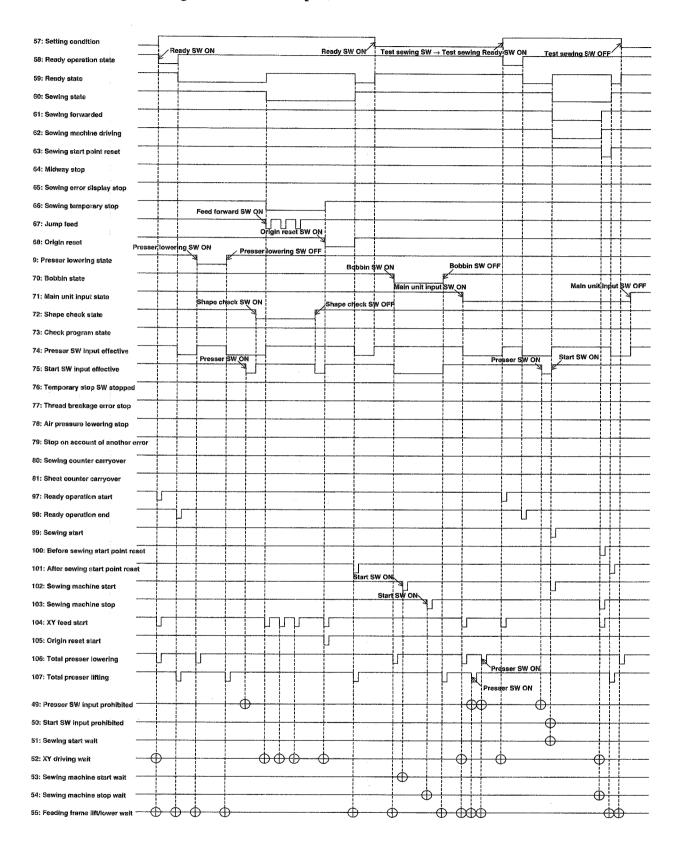
[Normal Status Diagram of the Port I/O]



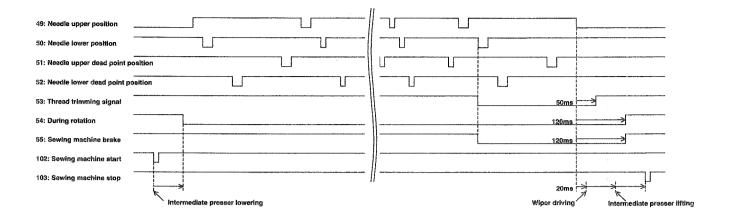
[Error Status Diagram of the Port I/O]



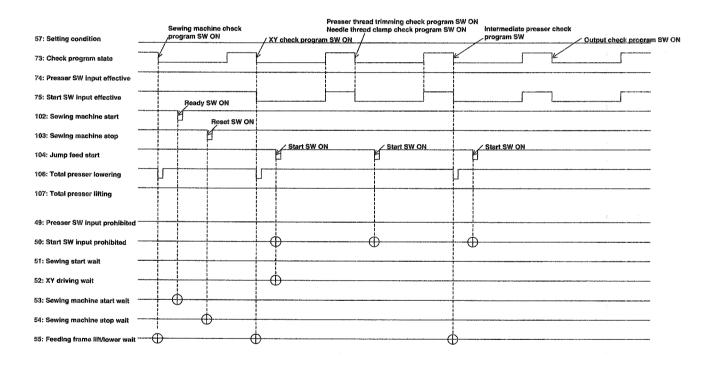
[Miscellaneous Status Diagram of the Port I/O]

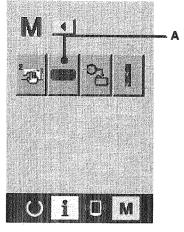


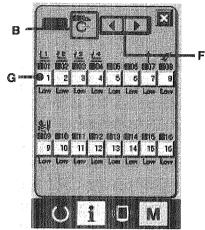
[Sewing Machine Driving Status Diagram of the Port I/O]

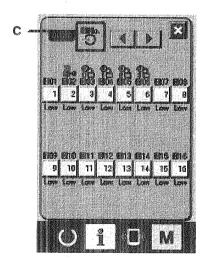


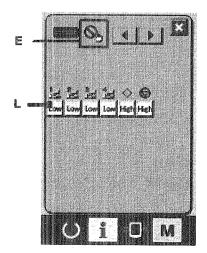
[Check Program Status Diagram of the Port I/O]











3. Setup procedures

(1) IP-400

1) Display of the port I/O screen

When the M switch is continuously pressed for about 6 seconds and the page changeover button is pressed, the port I/O setup button (A) is displayed. When this button is pressed, the port I/O setup screen is displayed.

2) Selection of the port I/O screen

For port I/O setup, four I/O setup screens are available. A required function number can be set on a relevant screen.

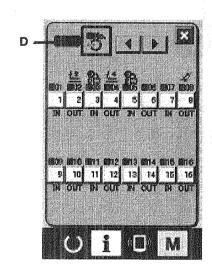
B: Output number setting

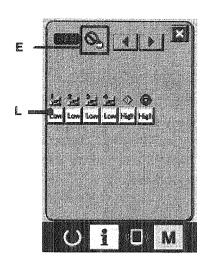
C: Input number setting

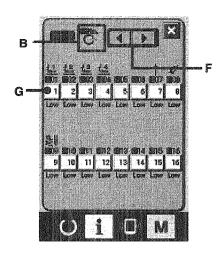
D: Virtual I/O number setting

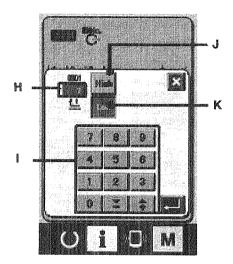
E: Switch operation prohibition setting

Setup screen changeover is possible with the right and left scroll buttons (F) located on the top of each screen.







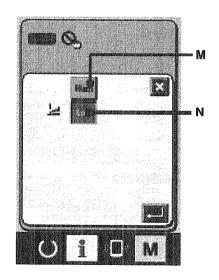


3) Port I/O setup

To make output number setting, input number setting, and virtual I/O number setting, the setup button

(G) is pressed to enter an input of the setting function number (H) in the selected terminal through the ten key (I). The signal type is selected from High (J) and Low (K). In the case of virtual I/O number setting, it is selected from output our and input .

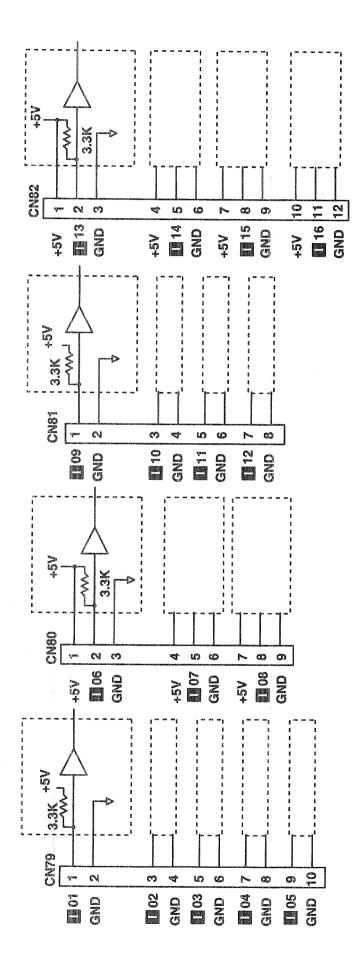
To make switch operation setting, the setup button (L) is pressed to select the signal type from High (M) and Low (N).



(2) CP-20

It is possible to make setting with the memory switches (Level 2) No. 300 to 401.

In regard to the method of input entry, refer to 4. Memory Switches, (2) Function list, • Level 2 (Simplified panel).



CN80, CN81, and CN82 are not integrated at shipment. To use those connectors, mount those first.

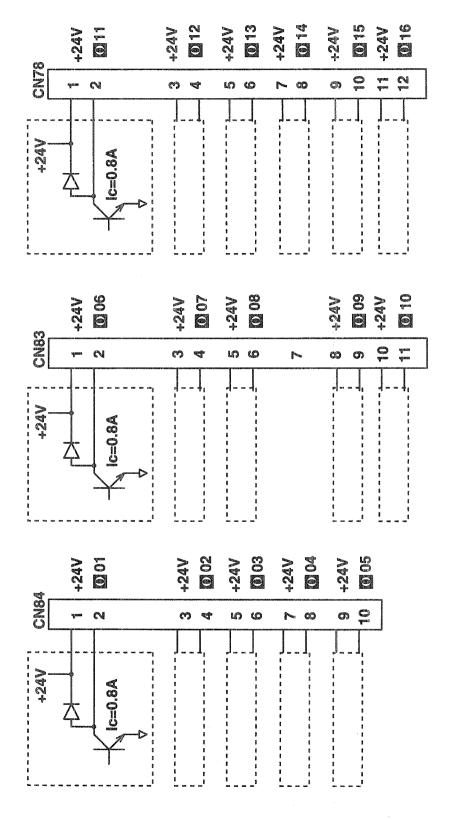
CN80: HK01650009B (ELCO: 00 8263 0912 00 002) CN81: HK01650008B (ELCO: 00 8263 0812 00 002) CN82: HK01650012B (ELCO: 00 8263 1212 00 002)

Cord side

8P housing: HK01651008B (ELCO: 60 8263 3088 15 002) 9P housing: HK01651009B (ELCO: 60 8263 3098 15 002) Pin: HK016540000 (ELCO: 60 8263 0513 00 808)

12P housing: HK01651012B (ELCO: 60 8263 3128 15 002) Use CN79 and CN81 for switch input.

Use CN80 and CN82 for sensor or switch input.



CN83 and CN78 are not integrated at shipment.

CN83: HK01650011A (ELCO: 00 8263 1112 00 001) CN78: HK01650012A (ELCO: 00 8263 1212 00 001) To use those connectors, mount those first.

Cord side

Pin: HK016540000 (ELCO: 60 8263 0513 00 808)

11P housing: HK01651011A (ELCO: 60 8263 3118 15 001) 12P housing: HK01651012A (ELCO: 60 8263 3128 15 001)

It is recommended to use the drive transistor with 0.5 A or less even though the rated current is 0.8 A. Make sure that the total current is equal or less than 1 A.

(5) Simplified program setup

This machine is provided with the simplified program functions, which can make the programming of various additional devices (stacker, unit, etc.) according to sewing machine operation. In conjunction with the port I/O output functions, modification into such additional devices can be carried out in the main unit of the sewing machine.

1. Specifications

- (1) Operation by a maximum of five programs is possible.
- (2) Inputs of a maximum of 99 steps can be entered per program.
- (3) Interactive operation is possible among the five programs.

2. Setting items

The simplified program specifies the following five items per step.

No.	Setting item	Contents
1	Command	The method of step execution is displayed.
2	Output information	Contents of multiple outputs are set up for High and Low of the respective 16 output terminals and 16 virtual I/O ports.
3	Input information	Multiple input conditions are set up for High and Low of the respective 16 output terminals, 16 input terminals, 16 virtual I/O ports, and 6 operation switches.
4	Parameter ①	Skip destination step No. or program No. is set up.
5	Parameter ②	The input conditions of delay time, No. of stitches, No. of repetition times, etc. are set up.

The virtual I/O port is provided for an interface to be used for sewing machine control and simplified program control. In the case of port I/O setup, either an input or output is set up as seen from the sewing machine control side. (Caution) The virtual I/O port is an internal signal of the sewing machine. It cannot be brought out directly to the outside.

3. Control operation

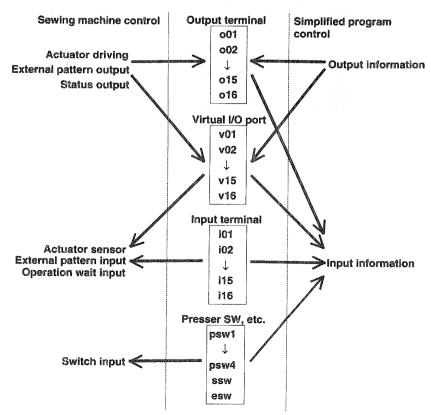
At the start of simplified program execution, operation is sequentially carried out starting from Step No. = 1, at the intervals of 1ms for each step.

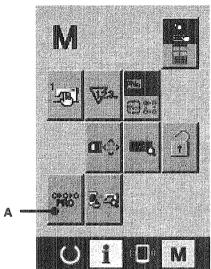
At the beginning of step execution, the contents of output information setup are generated. Operation is suspended (with the execution step No.) until the setup conditions for the input information or Parameter ② have been established. When these conditions are established, operation is forwarded to the next step No. or the skip destination step No. defined by Parameter ①. Such a sequential operation is repeated till the completion command.

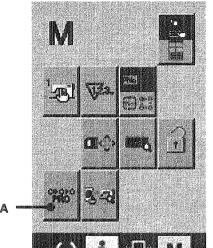
(Caution)

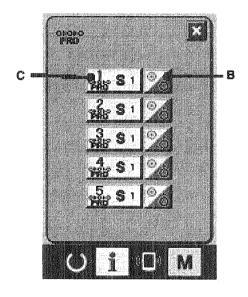
In the simplified program control, the I/O terminals and others are directly controlled based on the output and input information, irrespective of the result of port I/O setup.

In particular, the output data are immediately generated at the beginning of step execution for the output terminals and virtual I/O ports. In regard to I/O mismatching and synchronization for sewing machine control, therefore, programs have to be established carefully on the side of simplified program.









4. Operational Procedures

(1) Simplified program selection screen display

When the key is continuously pressed for 3 seconds, the simplified program button 🛍 (A) is displayed on the mode changeover screen. When this button is pressed, the simplified program selection screen is displayed.

(2) Simplified program effective / ineffective

The simplified program comes in five patterns. In the initial state, all the patterns are set at OFF. When the simplified program setup button (B) is used, each program can be made effective or ineffective.



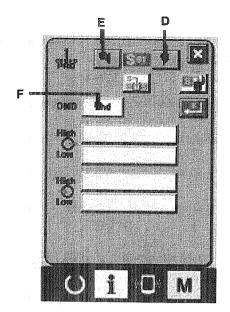
Simplified program effective



: Simplified program ineffective

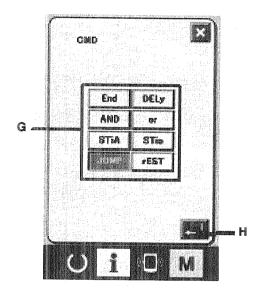
(3) Simplified program editing

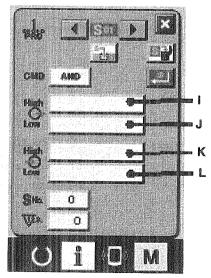
Simplified program No. and the registered number of steps 5 are displayed on the program editing button sign sign (C). When this button is pressed, the simplified program editing screen is displayed, which corresponds to the simplified program editing button.



In the simplified program editing screen, the editing step is selected with the use of the step forwarding button (D) and the step return button (E). For each selected step, it is possible to carry out command port I/O setting and parameter setting.

A maximum of 99 steps can be entered.





1) Command selection

When the command selection button [15] (F) is pressed on the simplified program editing screen, the command selection screen is displayed.

The command that is being selected is displayed on the button.

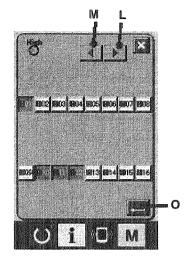
On the command selection screen, the command button (G) is displayed. Press the selecting command button and then press the Enter button (H). In regard to command descriptions, refer to (4) list of simplified program commands.

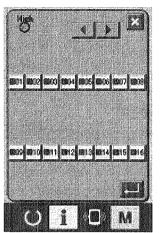
2) Port I/O information setup

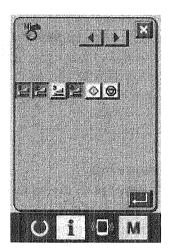
The port status can be set up for the four items as specified below.

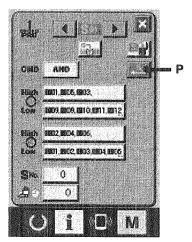
- (I) Output information (High) setup button
- (J) Output information (Low) setup button
- (K) Input information (High) setup button
- (L) Input information (Low) setup button

When the setting button is pressed, the I/O data selection screen is displayed.









On the port setup screen, current setting items are displayed at the top left of the screen.



: Output information (High) setup screen



: Output information (Low) setup screen



: Input information (High) setup screen



: Input information (Low) setup screen

Using the page turning buttons (M, L), the displayed port type can be changed. The port comes in the four types as specified below.

Seg CIT

: Output port No.

E001

: Input port No.

M01

: Virtual I/O port No.

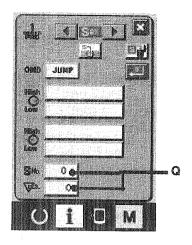


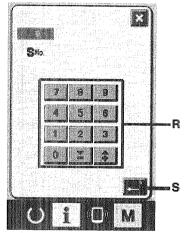
etc.: Presser SW 1 to 4, Start SW, Temporary stop

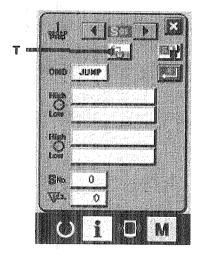
The port No. button is displayed on the screen. Press the button that corresponds to current setting.

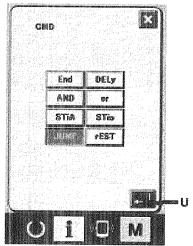
The selection status button is displayed in gray. After selection, press the Enter button (O).

For output setting, press the output button [23] (P) to obtain the item for which the displayed step has been set up. Therefore, this item can be examined.









3) Parameter input

Corresponding to the selected command, the parameter input button is displayed.

When the parameter input button (Q) is pressed, the parameter input screen is displayed.

Enter a numerical input through the ten key (R) and press the Enter button (S).

In regard to the parameters that correspond to the commands, refer to (4) list of simplified program commands.

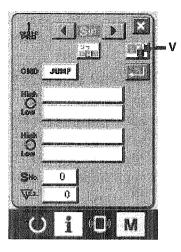
4) Step insertion

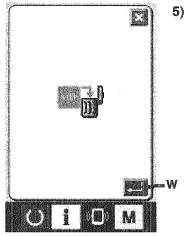
It is possible to insert a step before the displayed step.

When the step insertion button (T) is pressed, the command selection screen is displayed.

Select the command that is required to be inserted,

and press the Enter button (U). Then, the required step is inserted.

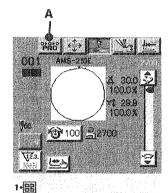


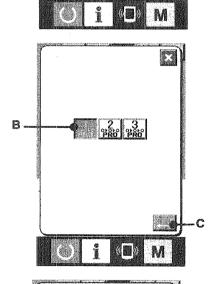


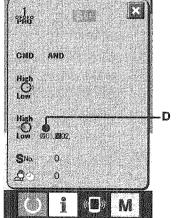
5) Step deletion

It is possible to delete the step that has been displayed.

When the step deletion button (V) is pressed, the deletion check screen is displayed. When the Enter button (W) is pressed, the displayed step is deleted and the step standing behind is shifted forward.







6) Checking the status of the simplified program in the sewing screen

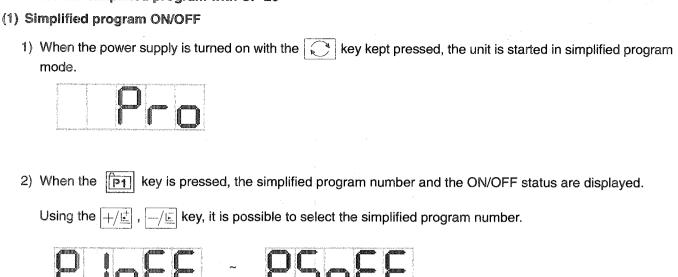
The simplified program button (A) is displayed in the sewing screen if this simplified program is available. The simplified program select screen is presented and the effective simplified program button (B) is displayed.

Select the simplified program number the status of which is being checked, and press the ENTER button (C).

The simplified program confirmation screen is presented and the present step number and the status of I/O are displayed.

The port number without I/O confirmation is displayed in gray (D).

5. To use the simplified program with CP-20



key, ON/OFF changeover is possible.



Upon the completion of modification, turn off the power supply.

(2) Write/read of the simplified program data with the smart media

1) When the power supply is turned on with the key kept pressed, the unit is started in simplified program mode.



2) When the P2 key is pressed, write/read of the simplified program data becomes possible with the smart media.

2. For data writing It is possible to select only the file number	er that is not registered in th	ne smart media.
5) When the key is pressed, reading o indicated in blinking mode. When the Power recovered when the power supply is turned	er OFF is indicated, data wr	data reading or writing, the File No. is riting is finished. Ordinary operation is

3) Select data Write or Read with the ☐ ∜ key.

4) Using the +/± , -/= key, it is possible to select the file number.
1. For data reading

It is possible to select only the file number registered in the smart media.

: Reading

Program Commands
Program
(4) List of Simplified
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				n					
<u>§</u>	Function code	Command	Output information	Output information Input information	Parameter ①	Setting range	Parameter @	Setting range	Remarks
-	End	Complete	Effective	Ineffective	Ineffective	AND THE THE THE THE THE THE THE TENTH TO THE	Ineffective	-	Program execution is finished.
2	DELy	Delay	Effective	Ineffective	Ineffective		Delay time	0 to 9999ms	Moving to the next step after the lapse of a delay time.
m	And	Branch with AND condition	Effective	Effective	Skip destination 1 to 99 steps No.	1 to 99 steps	Delay time	0: Input waiting till the condition established 1 to 9999ms	Moving to the next step when all conditions specified by input setting are satisfactory (AND input). Jumping to the step preset by skip destination No. after the lapse of a delay time as a result of failure in establishing the input conditions.
4	ō	Branch with OR condition	Effective	Effective	Skip destination No.	destination 1 to 99 steps	Delay time	0: Input waiting till the condition established 1 to 9999ms	Moving to the next step when either condition specified by input setting is satisfactory (OR input). umping to the step preset by skip destination No. after the lapse of a delay time as a result of failure in establishing the input conditions.
ഹ	STA	Branch with AND condition for No. of stitches	Effective	Effective	Skip destination No.	destination 1 to 99 steps	Number of stitches	0 to 9999 stitches	Moving to the next step after the lapse of the preset number of stitches. Jumping to the step specified by the skip destination No. within the range of the preset number of stitches when all conditions specified by input setting are satisfactory (AND input).
O	STIO	Branch with OR condition for No. of stitches	Effective	Effective	Skip destination No.	destination 1 to 99 steps	Number of stitches	0 to 9999 stitches	Moving to the next step after the lapse of the preset number of stitches. Jumping to the step specified by the skip destination No. within the range of the preset number of stitches when either condition specified by input setting is satisfactory (OR input).
2	UMMP	Jump repetition counter	Effective	Ineffective	Skip destination No.	destination 1 to 99 steps	Repetition counting value	0: Infinite 1 to 9999 times	Repeated in the range of skip destination steps specified by Jump till repetition counter carryover. Infinite loop is performed when setting is made at 0. Moving to the next step after repetition counter carryover. (Caution) Do not perform nest input of this command.
ω	rEST	Program reset	Effective	Ineffective	Program No.	1 to 5 programs	Ineffective	1	In the case of the step initialization of the specified program number, the specified program steps are forcedly returned to the initial steps.

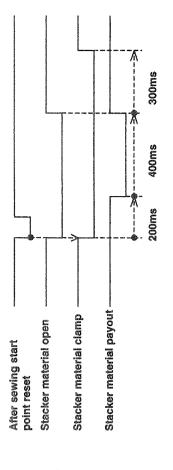
Contents	High output of external output terminals 01 to 16	High output of virtual I/O ports 01 to 16	Low output of external output terminals 01 to 16	Low output of virtual I/O ports 01 to 16	Commence the supplementaries of the Contract o
Input information setup range	001H to 016H	v01H to v16H	001L to 016L	v01L to v16L	

Input information setup range	Contents
001H to 016H	High status input of external output terminals 01 to 16
i01H to i16H	High status input of external input terminals 01 to 16
v01H to v16H	High status input of virtual I/O ports 01 to 16
p1H to p4H,sH,eH	High status input of presser SW1 to 4 (p), Start SW (s), Temporary stop SW (e)
o01L to o16L	Low status input of external output terminals 01 to 16
i01L to i16L	Low status input of external input terminals 01 to 16
v01L to v16L	Low status input of virtual I/O ports 01 to 16
p1L to p4L,sL,eL	Low status input of presser SW1 to 4 (p), Start SW (s), Temporary stop SW (e)

(5) Program sample

1) Simplified stacker program 1

his is an example of program establishment intended to make material stacking, to be done simultaneously with feeding frame lifting after the completion of sewing.



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Terminal	Contents	Remarks
output		
001	1: Feeding frame right	Standard
002	2: Feeding frame left	Standard
003	4: Feeding frame	Standard
	2-step stroke	i di
004	7: Inverting shaft	Standard
905	9: Needle cooler	Standard
900	(Stacker material open) Simplified program output	Simplified program output
007	(Stacker material clamp)	Simplified program output
900	(Stacker material payout) Simplified program output	Simplified program output

THE CHICAGO	<u></u>		٠						!
Remarks									
Contents									
Terminal	output	101	i02	:03	i04	901	90!	107	90i

101: After sewing start point reset							
Output							
v01	v02	v03	v04	v05	90^	70A	۸08
	Output 101: A						

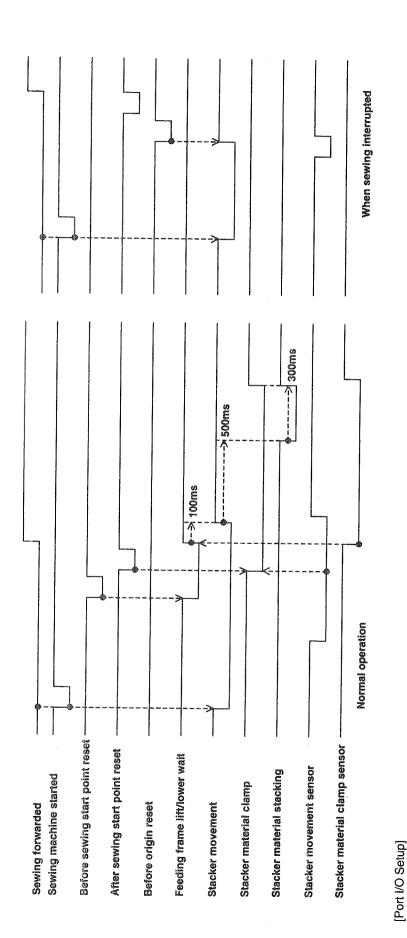
(Caution) For the descriptions in the parentheses () of o06 ~ o08 above, the terminals directly generate outputs with the aid of the simplified program. Port I/O setting is disabled.

[Simplified Program Setup]

Step	End,DELy, And,or, STIA,Stio, JUMP,Rest	001H to 016H v01H to v16H			001L to 016L i01L to i16L v01L to v16L p1L to p4L,sL,eL	Pn. Program No. Sn, Step No	Pn. Program No. c. Number of stitches Sn, Step No r. Repetition counter	Delay time: Unit of 1ms Number of stitches: Unit c
No.	Command	Output information High	Command Output information High Output information Low Input information I	Input information High	High Input information Low Parameter ①	Parameter ①	Parameter ②	Remarks
Τ-	And				v01L		0.b	Waiting till sewing start point reset
2	DELy		o06L,o07L				d.200	Stacker material open / material clamp ON. 200ms delay.
က	DELy		008L				d.400	Stacker material payout ON. 400ms delay.
4	DELy	006H,008H					00E.b	Stacker material open / material payout OFF. 300ms delay.
5	JUMP	HZ00				Sn.1	1.0	Stacker material clamp OFF. To Step 1.
9	End							

2) Stacker program 2

This is an example of program establishment intended to make material stacking, to be done after the material cloth has been clamped before feeding frame lifting at the time of the completion of sewing.



į												
	Contents	v01 Output 61: Sewing forwarded	Outbut 102: Sewing machine started	Output 100: Before coming state and	100. Delore sewing start politi reset	Output 101: After sewing start point reset	Output 105: Before eriain recet	ios. Deloie diigiii leset	Input 55: Feeding frame lift/lower wait			
de principal de la companya de la co	8	Output	- di	of the	Carpa	Output	4) Triban	Input	-		
and the second second second second	Virtual I/O I/O	v01	Š	50%	2	v04	705	3	90^	V07	gQ,	004
THE PROPERTY OF THE PROPERTY O	Remarks								Simplified program input	Simplified program input		
	Contents	STREET, THE STREET							(Stacker movement sensor) Simplified program input	(Stacker material clamp sensor) Simplified program input		THE DOWN THE
	Terminal input	101	20i	103		j04	i05	Ť	90	, 107	80i	The second distribution of the second distributi
1	Remarks	Standard	Standard	Standard		Standard	Standard		Simplified program output	Simplified program output	Simplified program output	Market Control of the

1: Feeding frame right

Terminal output 9 902 93

2: Feeding frame left

4: Feeding frame 2-stage stroke

7: Reverse shaft 9: Needle cooler (Stacker move)

900 005 900 007

(Stacker material clamp)

(Stacker material stack)

900

Remarks

(Caution) For the descriptions in the parentheses () of 006 ~ 008 and i06 ~ i07 above, the terminals directly generate outputs with the aid of the simplified program. Port I/O setting is disabled.

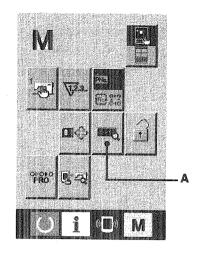
Stacker movement ON. Waiting till sewing start point Feeding frame lifting wait ON. Waiting till sewing start Stacker material clamp ON. Waiting till stacker mate-To Step 11 if there is no sewing start point reset. Stacker material clamp / material stacking OFF. Stacker material stacking ON. 300ms delay. Feeding frame lifting wait ON. 100ms delay. Waiting till stacker movement sensor ON. Stacker movement OFF. 500ms delay. Stacker movement OFF. To Step 1. Number of stitches: Unit of 1 stitch Waiting till sewing machine start. Remarks Delay time: Unit of 1ms rial clamp sensor ON. reset or origin reset. point reset. c. Number of stitches r. Repetition counter Parameter (2) d. Delay time d.100 d.500 d.300 d.0 d.0 d.0 о. Т d.0 о<u>.</u> 6. Pn. Program No. Parameter (1) Sn, Step No Sn.11 Sn.1 Sn.1 Output information High | Output information Low | Input information High | Input information Low 11H to p4H,sH,eH|p1L to p4L,sL,eL i01L to i16L v01L to v16L 001L to 016L v01L, v02L v03L, v05L V03L v04L 90! 107 v01H to v16H 001H to 016H 101H to 116H o01L to o16L v01L to v16L 006L, 907L 008L V06L 001H to 016H v01H to v16H 007H, 008H H900 H900 V06H [Simplified Program Setup] Command And,or, STiA,Stio, JUMP,Rest End, DELy JUMP JUMP DELy DELY DELy And End And And And And ö Step ŝ 12 9 N ന Ŋ ဖ œ O 4

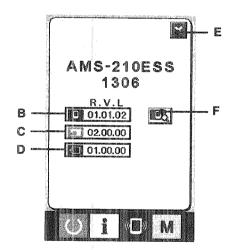
Remarks Contents 0 Virtual I/O V01 v02 v03 **v**04 v05 90^ 408 60^ **V12** <u>~13</u> **V14** v15 416 11 v07 Remarks Terminal Contents input <u> 10</u>2 <u>i03</u> 60! 110 <u>112</u> <u>:13</u> 115 i16 <u>0</u> <u>0</u> 105 90 i07 90 Ξ 114 Remarks (6) Port I/O setup sheet Contents Terminal output 900 012 013 005 903 004 005 800 600 010 014 015 016 001 007 011

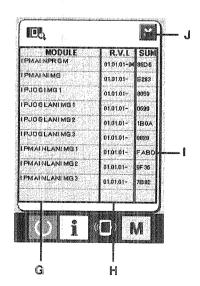
Shoet
Setud
Orogram English

Pn. Program No. c. Number of stitches Sn, Step No	Remarks																				
d. Delay time c. Number of stitches r. Repetition counter	Parameter ②																				
Pn. Program No. Sn, Step No	Parameter (1)																				
001L to 016L i01L to i16L v01L to v16L p1L to p4L,sL,eL	Input information Low																				
001H to 016H i01H to i16H v01H to v16H p1H to p4H;sH,eH	Input information High																				
001L to 016L v01L to v16L	Output information Low																				
End,DELy, o01H to o16H o01L to o16L o01H to o16H o01L to o16L And,or, o01H to o16H o01L to o16L i01H to i16H i01L to i16L STIA,Stio, v01H to v16H v01L to v16L v01H to v16H v01L to v16L JUMP,Rest p1H to p4H,sH,eH p1L to p4L,sL,eL p1.	Output information High													,							
End,DELy, And,or, STIA,Stio, JUMP,Rest	Co. Command															-					
Step		٦	2	3	4	5	9	7	8	9	0	4- -	2	3	4	5	9	7	8	0	0

(6) Version display







1. To display the version information screen:
Hold down the M key for 3 seconds to call up the version information button, (A) on the screen.
Press this button to display the version information screen.

The version information screen shows the version information of your sewing machine.

B: Panel program version

C: Main program version

D: Main shaft program version

Pressing the cancel button, (E) closes the version information screen and calls up the mode screen.

2. To display the detail screen:

Press the detail screen button, (F) to call up the panel program detail screen.

G: Module

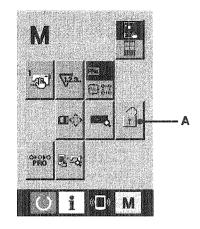
H: RVL

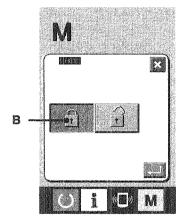
I: Checksum

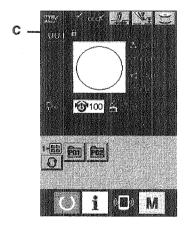
Pressing the cancel button, (J) closes the detail screen and calls up the version information screen. Pressing the (M) key closes the detail screen and calls up the data input screen which you have selected.

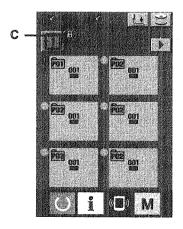
^{*} The check program allows you to see version information on the simplified panel.

(7) Keylock setup









1. To call up the keylock screen:

Hold down the M key for 3 seconds to call up the keylock button, (A) on the screen. Press this button to display the keylock setting screen.

The current status appears on the keylock button.



: Keylock is inactivated.



: Keylock is activated.

2. To select keylock and activate it:

Select the keylock activation button, (B) on the keylock setting screen and press . Then, the keylock setting screen closes and keylock becomes activated.

3. After closing the mode screen and calling up the data input screen:

After closing the mode screen and calling up the data input screen, PICT C indicating that keylock is activated appears on the right of the pattern number. Only available buttons appear when keylock is activated.

* Memory switch No. 17 allows you to activate keylock on the simplified panel.

(8) Communication screens of the maintenance personnel level (Program rewrite)

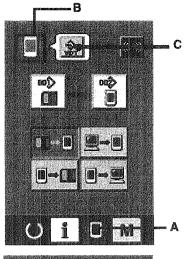
The data types allowed to be handled in the communication screens can differ according to the ordinarily used levels and the specific levels that are used by the maintenance personnel.

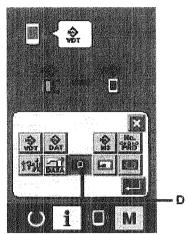
1. Types of data that can be handled

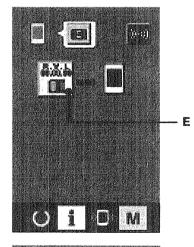
In addition to the four ordinary data types, the five more data types can be used for the maintenance personnel level. Each data type is as specified below.

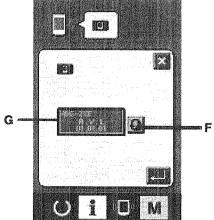
Data name	Pict	Extension	Contents of data
Adjustment data	írm	Model name +00XXX.MSW Example) AMS00001.MSW	Data of the memory switches 1 and 2
All sewing machine data	DATA	Model name +00XXX.MSP Example) AMS00001.MSP	All data maintained by the sewing machine
Panel program data		IP + RVL (6 digits).HED IP + RVL (6 digits).PXX IM + RVL (6 digits).IXX	Program data and display data of the panel
Main program data		MA + RVL (6 digits).PRG	Main program data
Servo program data	4	MT + RVL (6 digits).PRG	Servo program data

XXX: File No.









2. Reading/Writing of adjustment data and all sewing machine data (For the IP-400)

(1) Display of the communication screen of the maintenance personnel level

When the key (A) is continuously pressed for 3 seconds, the top left image is turned into the orange color (B) and a communication screen of the maintenance personnel level is displayed.

(C) is pressed in a communication screen of the maintenance personnel level, the data selection screen is displayed.

In this state, it becomes possible to select the adjusting data and all sewing machine data.

3. Program rewriting (For the IP-400)

(1) Selection of the data type

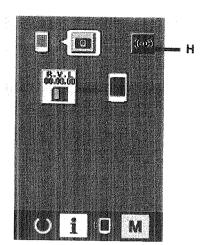
When the data classification button (C) is pressed in a communication screen of the maintenance personnel level, the data selection screen is displayed.

In this state, select the panel program data (D).

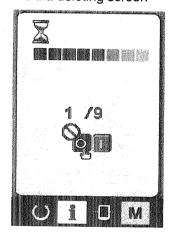
(2) Selection of a file

When the file selection button (E) is pressed in a communication screen, the file selection screen is displayed.

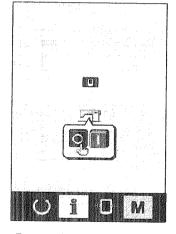
Press the file retrieval button (F) to select the download program (G), and press the button.



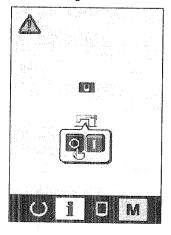
Data deleting screen



Ending screen



Data writing error screen

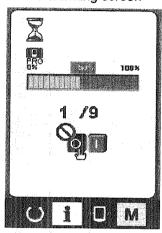


(3) Program rewrite start

When the start of communication button pressed, program rewriting is started. (H) is

(Caution) Never turn off the power or open/shut the smart media cover during the work. Otherwise, the main body can be destroyed.

Data writing screen



When the ending screen is displayed, the replacement work for the application software has been completed.

If any data writing error screen should be displayed, immediately turn off the power supply and check the [checking items] specified below. Then, take the setup actions again.

[Checking items]

- 1) Did you open the smart media cover in the middle of data communication from the smart media card.
- 2) Data of the smart media card are incorrect, or there is no data file.
- The contact point of the smart media card is contaminated, or suffering from poor contact.

4. Reading/Writing of the adjustment data and all sewing machine data in the smart media (For the CP-20)
(1) When the power is turned on with the key kept pressed, the adjustment data mode is started. When the adjustment data mode is started, the pattern number LED is lit up.
When the power is turned on with the key kept pressed, the all sewing machine data mode is started. When
the all sewing machine data mode is started, the X scale LED is lit up.
: Adjustment data mode : All sewing machine data mode
(2) Select data reading or writing with the key
: Reading : Writing
(3) Select the fine number with the/ <u>t</u> and/ <u>t</u> keys.
 For reading Selection is made possible only for the file number that is registered in the smart media.
2) For writing
Selection is made possible only for the file number that is not registered in the smart media.
H. 1 to H. 999
(4) When the key is pressed, reading or writing of each data block is started. In the middle of data reading or
writing, the file number is displayed in the blinking mode. When Power OFF is displayed, reading or writing has
been completed.
(5) When the power supply is turned on again, normal operation is recovered.

5. Program rewriting (For the CP-20)

(1) When the power is turned on with the key kept pressed, the rewriting mode of the simplified panel program is started. When the rewriting mode of the simplified panel program is started, the Y scale LED is lit up. When the power is turned on with the key kept pressed, the rewriting mode of the main program is started. When the rewriting mode of the main program is started, the max. number of rotation LED is lit up. When the power is turned on with the Es key kept pressed, the rewriting mode of the servo program is started. When the rewriting mode of the servo program is started, the tension LED is lit up.



: Panel program





: Servo program

(2) Using the key, select the program file for the panel, which is kept in the smart media. In regard to the file display, the be used for changeover between the RVL display and the model code display.



: RVL display



: Model code display

For RVL display, five digits of R (1 digit), V (2 digits), and L (2 digits) are displayed. The non-display portion (RVL + α) can be displayed with the use of the $+/\underline{\underline{t}}$ and $-/\underline{\underline{t}}$

Example) RVL 01-03-02



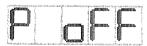
For model code display, the five continued characters from the head are displayed.

The model code of the non-display portion can be displayed with the use of the +/+

Example) AMS-210E



(3) When the \textsup \textsup key is pressed, writing of the simplified panel program is started. When Power OFF is displayed, writing has been completed.

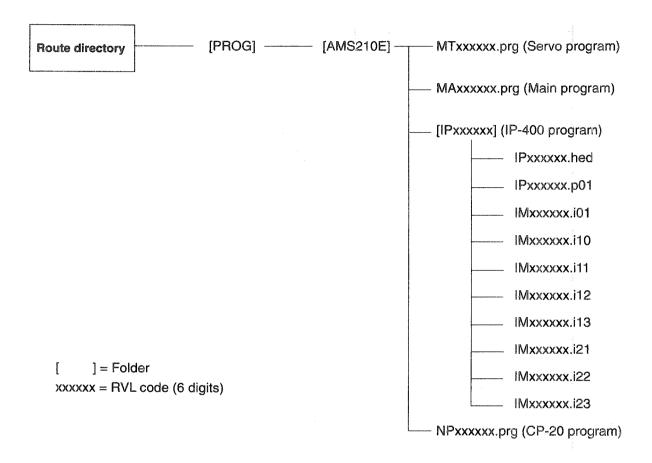


When the power supply is turned on again, normal operation is recovered.

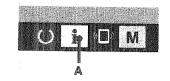
6. Use of smart media other than those packed together

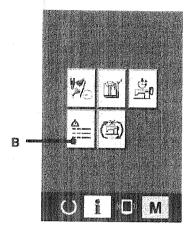
When the contents of the smart media card packed together are going to be copied on another smart media card, the smart media card of the copying destination should be formatted with IP400. Since then, the following directory configuration should be established with a personal computer.

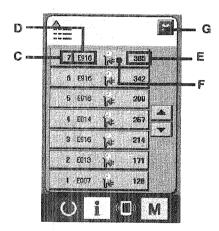
Information about the method of smart media card formatting is obtainable from the Instruction Manual, [2-25. How to Use the Communication Functions].

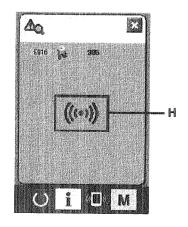


(9) Information screen at the maintenance personnel level









1. Error history

(1) To display the information screen at the maintenance personnel level:

Hold down the information key, (A) for approx. 3 seconds in the switch sheet section on the data input screen to call up the information screen at the maintenance personnel level. On the information screen at the maintenance personnel level, the color of PICT at the upper left changes from blue to orange, and there are 5 buttons.

(2) To call up the error history screen:

Press the error history button, (B) on the information screen to call up the error history screen.

The error history screen shows the error history of your sewing machine.

C: Chronological recording number

D: Error code

E: Cumulative energizing time during error (hour)

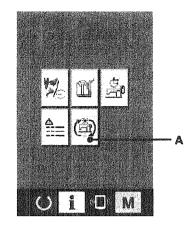
Pressing the cancel button, (G) closes the error history screen and calls up the information screen.

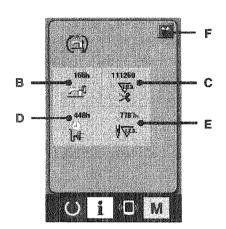
(3) To display details:

For detailed information about errors, press the error button, [7 1916 1/4 365] (F) that you would like to see to call up the error detail screen.

PICT (H) in response to error codes appears on the error detail screen.

→ Refer to the "11. ERROR CODE LIST".





2. Cumulative operating information

(1) To call up the information screen at the maintenance personnel level:

Hold down the information key i, i for approx. 3 seconds in the switch sheet section on the data input screen to call up the information screen at the maintenance personnel level. On the information screen at the maintenance personnel level, the color of PICT at the upper left changes from blue to orange, and there are 5 buttons.

(2) To display cumulative operating information:

Press the cumulative operating information button,

(A) on the information screen to call up the cumulative operating information screen.

The following 4 items are indicated on the cumulative operating information screen.

B: Cumulative operating time (hour)

C: Cumulative thread trimming count

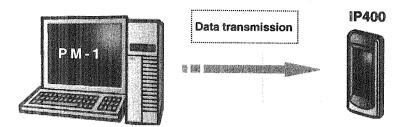
D: Cumulative energizing time (hour)

E: Cumulative stitch count (x1000 stitches)

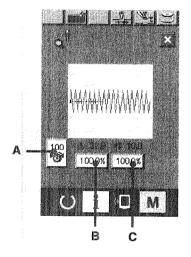
Pressing the cancel button, (F) closes the cumulative operating information screen and calls up the information screen.

(10) Test sewing function

Connecting your PC to the sewing machine allows you to perform test sewing based on data created with PM-1 (sewing data creating and editing software).



Connect your PC and transmit data to the sewing machine after creating it with PM-1, and IP-400 automatically shows the test sewing screen when the data input screen is called up. Refer to the help screen or the like for how to operate PM-1.



1. To perform test sewing:

(1) Reception of data for test sewing from PM-1

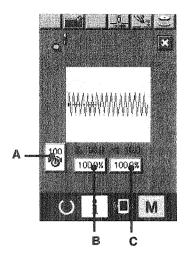
When data (vector type) for test sewing is transmitted from PM-1, the screen shown at right appears, and a needle positioning drawing of transmitted data appears in the center of the screen.

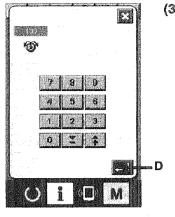
The color of the needle positioning drawing changes depending on thread tension. If the stitch count of transmitted data is too large, a needle positioning drawing does not appear.

(2) Edit of vector parameter

The following 3 items are configurable on data transmitted from PM-1.

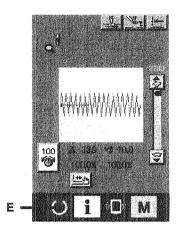
- A: Thread tension
- B: X-axial enlargement/reduction ratio or actual value
- C: Y-axial enlargement/reduction ratio or actual value
- * The memory switch, U64, provides selection between an enlargement/reduction ratio and an actual value.





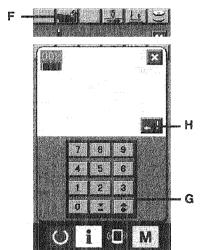
(3) Modification to data

Press the button, A, B, or C to be changed to call up the numeric keypad. Enter a new value and press the enter button (D).



(4) Test sewing

Press the ready-to-go switch **O** (E) to call up the test sewing screen. Test sewing is ready.

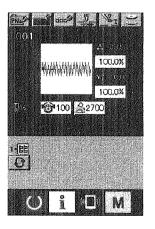


(5) Data registration to user pattern

To register test sewing data to the sewing machine, press the registration button (F) shown on the test sewing screen to call up the registration screen. Enter the user pattern number to which the test sewing data is registered with the numeric keypad (G).

(6) Confirmation of data registration

Press the enter button (H) to close the registration screen, and registration is completed.



(7) data entry screen

After data registration, the data entry screen automatically appears.

2. Color chart indicating thread tension values

An indicated needle positioning drawing varies with thread tensions adjusted for needle entry positions. The following chart shows the colors of lines for thread tensions.

Thread tension	Color						
0 to 20		: Gray					
21 to 40		: Purple					
41 to 60		: Blue					
61 to 80		: Light blue					
81 to 100		: Green					
101 to 120		: Yellowish green					
121 to 140		: Orange					
141 to 160		: Red					
161 to 180		: Pink					
181 to 200		: Black					

6. Test mode

(1) Start (CP-20)

5. Select the check program number with the $+/\underline{\mathbb{L}}$ and $-/\underline{\mathbb{L}}$ keys.

W	hen the check program is started, maintenance and inspection can be carried out.	Colores Colore
1)	Check program start	
Ann.	When the M key is continuously pressed for 3 seconds in the state that the sewing LED is unlit, a buzzer sound is heard and the user setup mode is assumed for the memory switch. In this state, icheck program startî can be selected. (Caution) The check program cannot be selected unless this key is continuously pressed for 3 seconds.	
2.	Change the memory switch number with the +/ and -/ keys to select the check program.	
3.	Press the \(\bigcup \) key to move to the check program. Start the display output test. Refer to the next page in regard to the contents of the display output test.	
4.	Press the key to complete the display output test. Move to the selection of another test function.	

Check program number	Check program	Contents
	Input signal check	The status of the switch and sensor inputs is displayed at LED.
CP 2	XY motor / origin sensor check	The status of inching operation of the X/Y motor, operation of origin retrieval, and the X/Y origin sensors is displayed.
	Continuous operation	After the conditions of continuous operation have been et up, the operational mode moves to the continuous operation mode.
	Main motor rpm check	The sewing machine is started at the preset rpm level nd the measured rpm number is displayed.

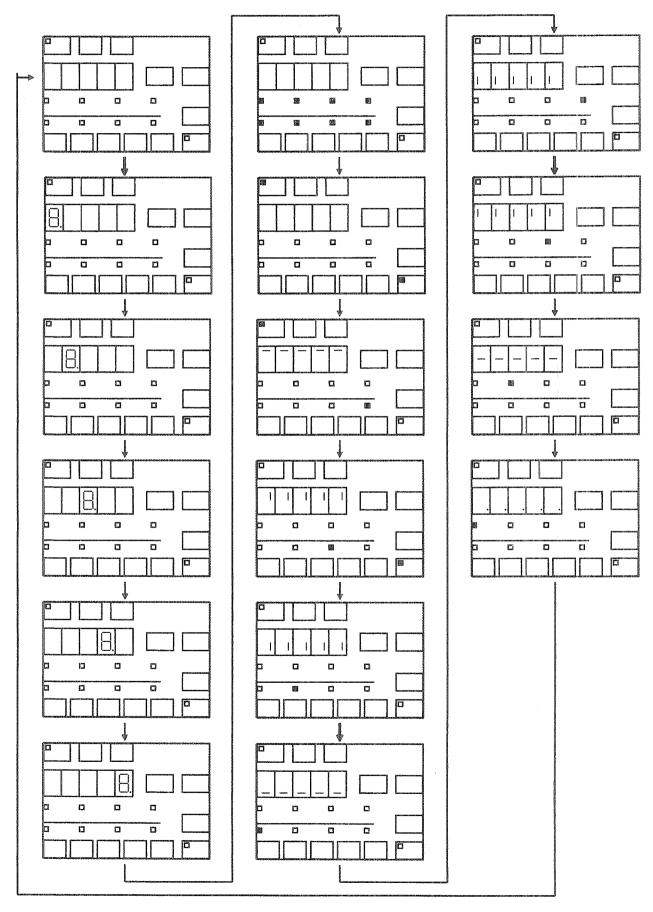
Check program number	Check program	Contents
Output check		The wiper and air outputs are generated.
Presser, thread cutter motor/ origin sensor check		The status of inching operation of the presser and thread trimmer motor, operation of origin retrieval, and he presser origin / presser sensors is displayed.
	Needle thread clamp motor/ origin sensor check	The status of inching operation of the needle thread clamp motor, operation of origin retrieval, and the needle thread clamp origin and needle thread clamp sensors is displayed.
E P	Intermediate presser adjustment	The status of inching operation of the intermediate presser motor, operation of origin retrieval, and the intermediate presser origin sensors is displayed.
CP B	Software version display	The software versions of the MAIN and SDC boards are displayed.

- 6. Press the key to define the check program number.
- 7. When the M key is pressed for each check program, the current check program is completed and the status of 5. is recovered.

Once the continuous operation mode is started, it cannot be canceled. To complete it, however, it is necessary to turn the power supply OFF.

(2) Display output test (CP-20)

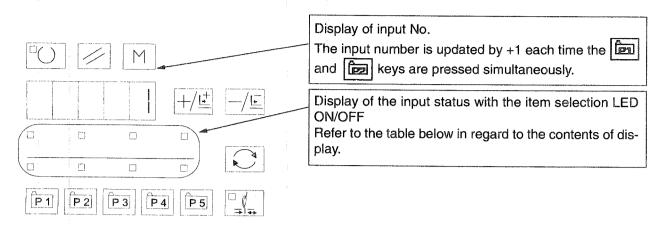
After the movement to a check program, the display output test is started. The following LEDs are lit at the intervals of one second.



(3) Method of confirmation according to each test program No. (CP-20)

1) CP-1 (Input signal check)

It is possible to check the input status of the operation panel keys, pedal switches, and various sensors.



Contents of Display for each Input No.

	Pattern LED	X enlarge LED	Y enlarge LED	Speed LED	Counter LED	Bobbin LED	Threading LED	Thread tension LED	Ready LED	Thread clamp LED
contemnities this section content continue			Key	□○ Key	_/⊑ Key	+/ <u>□</u> Key	Key	Key		
2		-	M	P 5	[Ea]	Fe		(en)		
3	DIPSW2	DIPSW2 -2	Key DIPSW2 -3	Key DIPSW2 -4	Key Start SW	Key Presser 1SW	Key Presser 2SW	Key Presser 3SW	Presser 4SW	Temporary stop
4	AUDET Sensor	ADDET Sensor	DDET Sensor	UDET Sensor	TG Sensor	PDET Sensor	SDET Sensor		Air pressure SW	SW X motor origin Sensor
5	Y motor origin sensor	Presser motor origin sensor	Thread clamp motor origin sensor	Intermediate presser motor origin sensor	Presser motor sensor	Thread clamp motor sensor	External input 1	External input 2	External input 3	External input 4
6	External input 5	External input 6	External input 7	External input 8	External input 9	External input 10	External input 11	External input 12	External input 13	External input 14
7	External input 15	External input 16	,, I				-	-	•	•
8	gymnolomia diku skolovoj kanisti sisi vii oso vaip o pyysik	a 1974 de California de la companya	AVM00-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-							

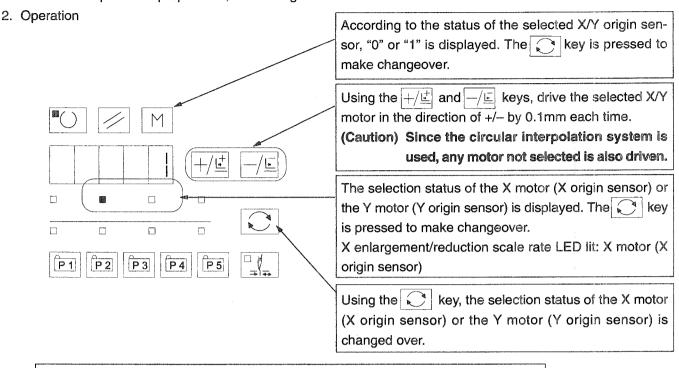
DIPSW2 is a dip switch located on the MAIN board.

2) CP-2 (XY motor / origin sensor check)

The status of inching operation of the X/Y motor, operation of origin retrieval, and the X/Y origin sensors is displayed.

1. In the first place, press the () key to carry out needle thread clamping and origin retrieval for the presser and thread trimmer motor. The presser assumes the lowering condition.

After the completion of preparation, the sewing LED is lit.



Using the Start SW, origin retrieval of the X/Y motors is effected for both shafts.

3) CP-3 (Continuous operation)

After the conditions of continuous operation have been set, the operational mode moves to the continuous operation mode. To cancel the continuous operation mode, it is necessary to turn the power supply OFF.

1.	Rest	time	setting

(Initial value 2000ms)

Press the +/ $\stackrel{\square}{=}$ and -/ $\stackrel{\square}{=}$ keys to set up the rest time. Setting is possible within the range of 0 to 9900ms in the unit of 100ms.

After the completion of setting, press the

2. Setting for the presence of origin retrieval at the end of sewing

Press the $+/\stackrel{!}{=}$ and $|-/\stackrel{!}{=}|$ keys to set up the presence of origin retrieval at the end of sewing.

A0: Ineffective (Initial value) A1: Every 100 sewing cycles A2: Every sewing cycle



3.	Presser lifting, Lowering frequency vertical times setup
	Press the $+/$ $\stackrel{\square}{=}$ and $-/$ $\stackrel{\square}{=}$ keys to set up the presser vertical times.

B0: Ineffective (Initial value) B1 ~ B10: 1 to 10 times

After setting, press the [key. The ordinary display is recovered.

4. Continuous operation

After the completion of setting, regular operation like pattern number setup and others should be carried out. At the end of sewing, origin retrieval of each motor is carried out for the X/Y / presser and thread trimmer / needle thread clamp if "origin retrieval effective" has been selected as per 2. Then, automatic sewing is restarted after the lapse of the rest time preset as per 1. above.

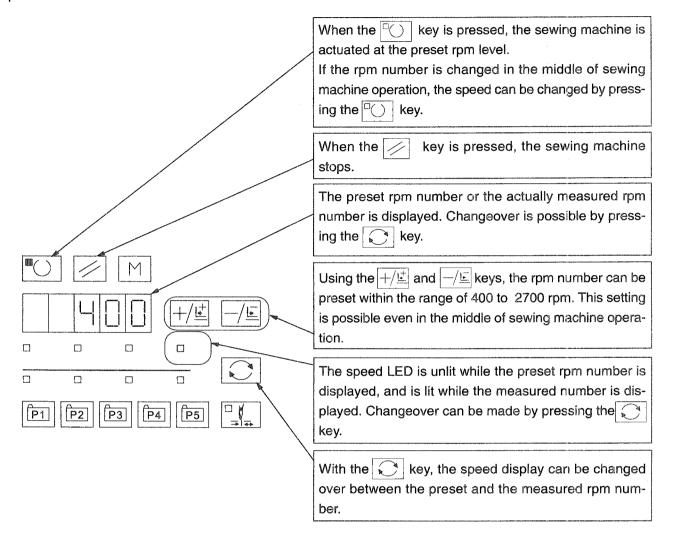
To stop continuous operation, the start switch should be turned ON during the rest time. [E 50] is displayed and the machine is stopped.

4) CP-4 (Main motor rpm check)

Set up the rpm number of the sewing machine, drive only the main motor of the sewing machine at the preset rpm level, and display the measured rpm number.

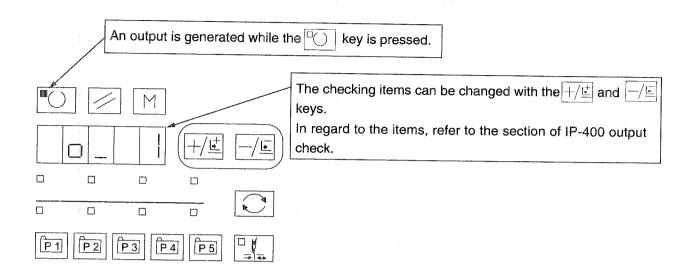
1. READY operation
In the first place, press the key for the origin retrieval of the needle thread clamp and the presser and thread trimmer motor. After operation for preparation, the sewing LED is lit.

2. Operation



5) CP-5 (Output check)

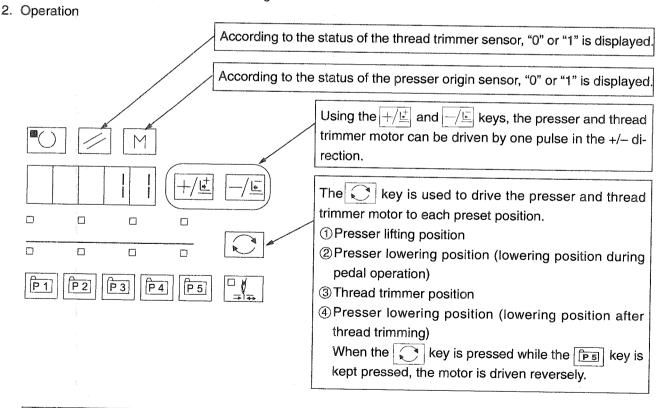
1. Operation



6) CP-6 (Presser and thread trimmer motor / origin sensor check)

The status of inching operation of the presser and thread trimmer motor, operation of origin retrieval, and the presser origin and thread trimmer sensors is displayed.

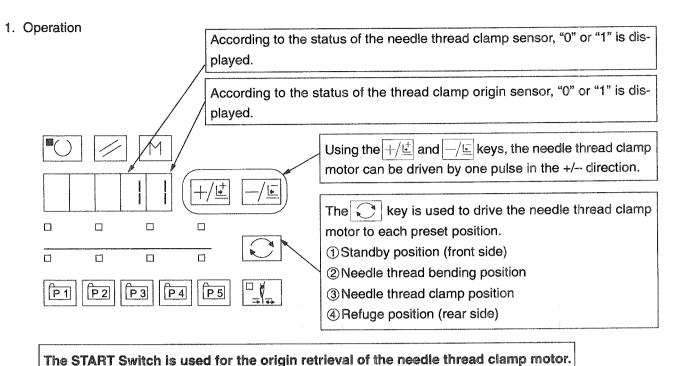
READY operation
 In the first place, press the key for the origin retrieval of the needle thread clamp.
 After operation for preparation, the sewing LED is lit.



The START Switch is used for the origin retrieval of the presser and thread trimmer motor.

7) CP-7 (Needle thread clamp motor / origin sensor check)

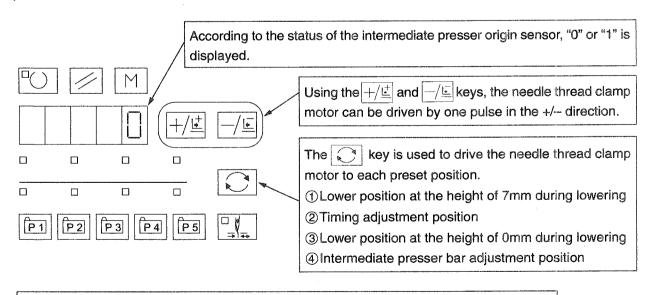
The status of inching operation of the needle thread clamp motor, operation of origin retrieval, and the thread clamp origin and needle thread clamp sensors is displayed.



8) CP-8 (Intermediate presser adjustment)

The status of inching operation of the intermediate presser motor, operation of origin retrieval, and the thread clamp origin and intermediate presser origin sensor is displayed.

1. Operation

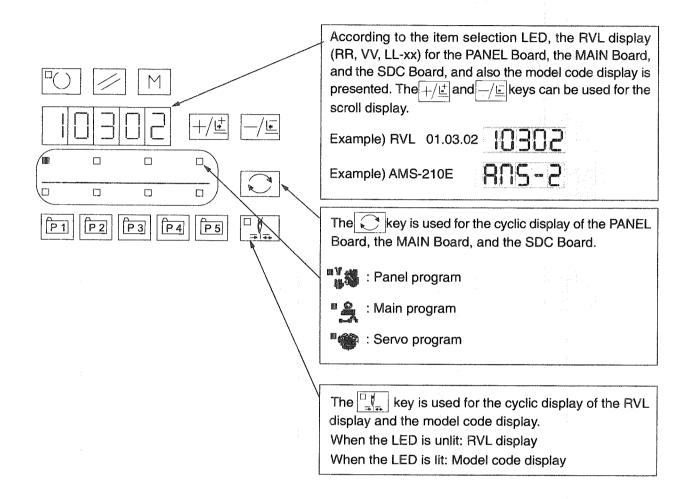


The START Switch is used for the origin retrieval of the intermediate presser motor.

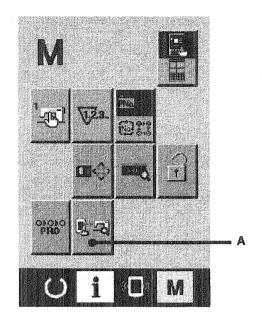
9) CP-9 (Software version display)

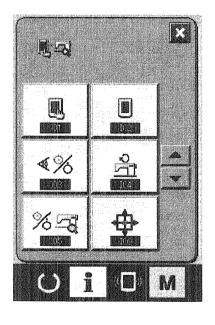
The software versions of the PANEL Board, the MAIN Board, and the SDC Board are displayed. Each version is expressed in a format of RR, VV, LL-xx. xx is used to indicate the specifications for special orders, etc. Therefore, it is not indicated usually.

1. Operation



(4) For IP-400





1) Display of the check program screen

When the key is continuously pressed for 3 seconds, the check program (A) is displayed on the screen. When this button is depressed, the check program screen is displayed.

The check program comes in the ten items as specified below.

Touch panel correction screen

→ The touch panel and button display positions are corrected.

LCD check

→ Presence of any dot missing is checked for the liquid crystal display.

Input signal check

→ The status of switches and sensor inputs is displayed.

Main motor rpm check

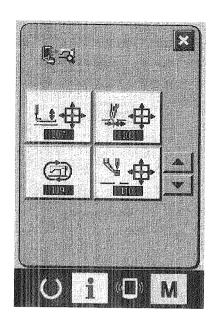
→ When the sewing machine is started at the preset rpm level, the measured rpm value is displayed.

Output check

→ Wiper and air output check is carried out.

XY motor / origin sensor check

→ The status of inching operation of the X/Y motor, operation of origin retrieval, and the X/Y origin sensor is displayed.



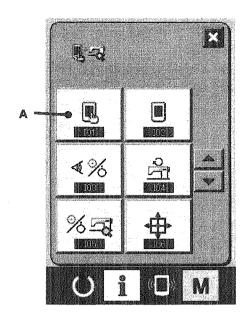
- Presser and thread trimmer motor / origin sensor check
- The status of inching operation of the presser and thread trimmer motor, operation of origin retrieval, and the presser origin and presser sensor is displayed.
- Needle thread clamp motor / origin sensor check
- The status of inching operation of the needle thread clamp motor, operation of origin retrieval, and the needle thread clamp origin and needle thread clamp sensor is displayed.

Continuous operation

When the conditions of continuous operation have been set up, the continuous operation mode is assumed.

Intermediate presser adjustment

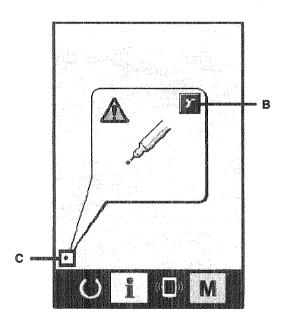
→ The status of inching operation of the intermediate presser motor, operation of origin retrieval, and the intermediate presser origin sensor is displayed.





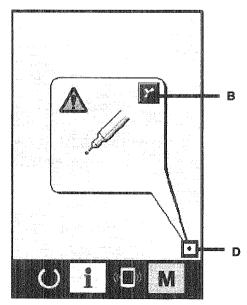
1. Display of the touch panel correction screen

When the touch panel correction button (A) of
the check program screen is pressed, the touch panel
correction screen is displayed.



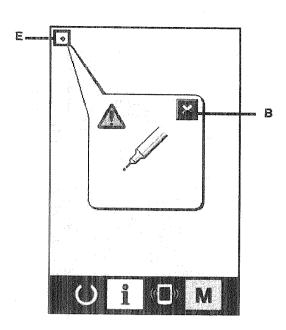
2. Pressing the bottom left position

Press the red circle (C) located at the bottom left of the screen. To complete correction, press the cancel button (B).



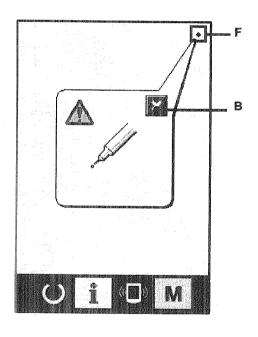
3. Pressing the bottom right position

Press the red circle (D) located at the bottom right of the screen. To complete correction, press the cancel button (B).



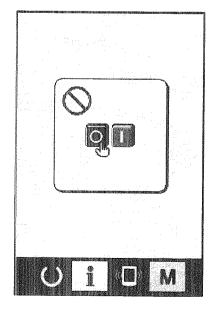
4. Pressing the top left position

Press the red circle (E) located at the top left of the screen. To complete correction, press the cancel button (B).



5. Pressing the top right position

Press the red circle \P (F) located at the top left of the screen. To complete correction, press the cancel button (B).



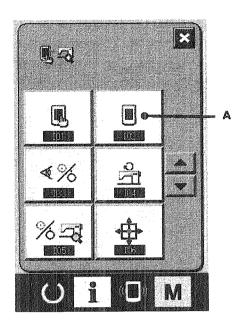
6. Data saving

When all the four points have been pressed, the correction data are saved. At that time, the Power OFF Prohibition screen is displayed.

The power supply must not be turned off while the above-mentioned screen is displayed.

If the power supply is carelessly turned off, no correction data are saved.

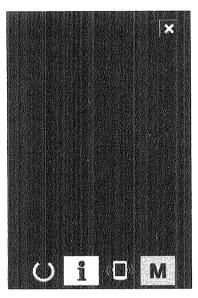
After data saving, the check program screen is automatically displayed.





1. Display of the LCD check screen

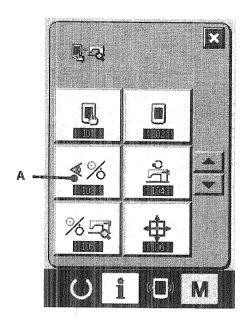
When the LCD check button (A) is pressed on the check program screen, the LCD check screen is displayed.

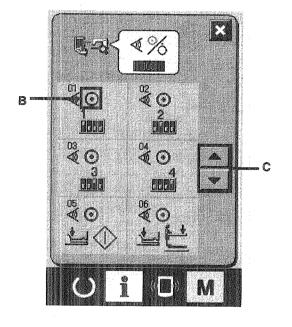


2. Confirmation of LCD dot missing

The LCD check screen is displayed only in one color. In this state, the LCD should be checked to freedom from dot missing.

After this confirmation, press a proper position on the screen. The LCD check screen is closed and the check program screen is displayed.





4) Method of input signal check

1. Display of the input signal check screen

When the input signal check button (A) is pressed on the check program screen, the sensor check screen is displayed.

2. Input signal check

In the input signal check screen, the input conditions of various sensors can be confirmed.

For each sensor, the input status is displayed as indicated by B.

The ON/OFF conditions are displayed as shown below.

(3)

: ON condition

Ô

: OFF condition

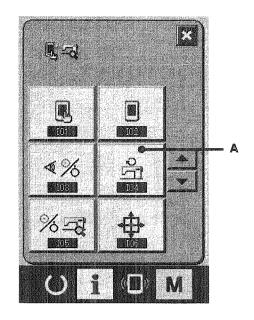
Using the UP-DOWN buttons (C), display the sensor that has been confirmed.

The sensors provide the following 43 types of conditions:

No.	Pictograph	Contents of sensor	No.	Pictograph	Contents of sensor
01 40	1	DIPSW2-1	17	SDET	SDET sensor
02 √Q	2 .5.a	DIPSW2-2	18 • Q		Head fall SW
03 40	3 8.58	DIPSW2-3	19 4		Air pressure SW
04. < 00	4 666	DIPSW2-4	20 • Q	# 4	Thread breakage sensor SW
05 40	₩◊	Start SW (Pedal)	21 -{(X motor origin sensor
06 √ 0		Presser 1 SW (Pedal)	22 40	-	Y motor origin sensor
07 40		Presser 2 SW (Pedal)	23 4		Presser motor origin senso
08 <u>.</u> √§	3(6)	Presser 3 SW (Pedal)	24 ()	*	Needle thread clamp motor origin sensor
09 √Q	4	Presser 4 SW (Pedal)	25 4	\$	Intermediate presser motor origin sensor
10 40		Temporary stop SW	26 <0		Presser motor sensor
11 40	AUDET	AUDET sensor	27 4		Needle thread clamp motor sensor
12 √Q	ADDET	ADDET sensor	28 ≪(1	External input 1
18 √Q	DDET	DDET sensor	29 < 0	2	External input 2
14 •Q	UDET	UDET sensor	30 ((€) 3	External input 3
15 < 0	TG .	TG sensor	31 <0	•••	External input 4
16 √0(PDET	PDET sensor	32. < ℚ	-© 5	External input 5

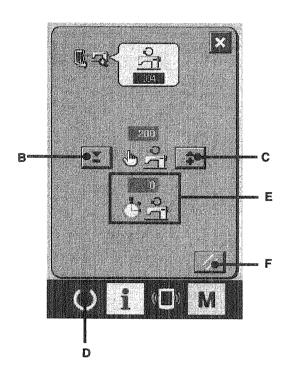
The DIPSW2 is the DIPSW located on the MAIN Board.

No.	Pictograph	Contents of sensor	No.	Pictograph	Contents of sensor
33 - √(6	External input 6	39 √ €	12	External input 12
34 √ 0		External input 7	40 ≪@	- O 18	External input 13
35 4 €		External input 8	41 40	-0 14	External input 14
36 ∢≬	5 9	External input 9	42 Q	2	External input 15
37 4 0	- <u>0</u> 10	External input 10	43 -{q	16	External input 16
38 ∢∮	•0 11	External input 11			



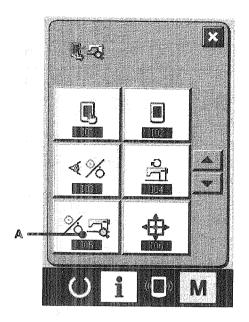
- 5) Main motor rpm check
- 1. Display of the main motor rpm check screen

 When the main motor rpm check button (A) is pressed on the check program screen, the main motor rpm check screen is displayed.



2. Main motor operation and measured rpm value check

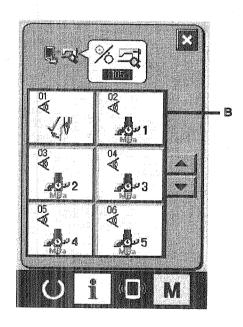
Using the -/+ buttons (B, C), the rpm number can be set up. When the button (D) is pressed, the sewing machine is operated at the preset speed. At that time, the measured rpm value is displayed at (E). When the SET button (F) is pressed, the sewing machine is stopped.



6) Method of output check

1. Display of the output check screen

When the output check button (A) is pressed on the check program screen, the output check screen is displayed.

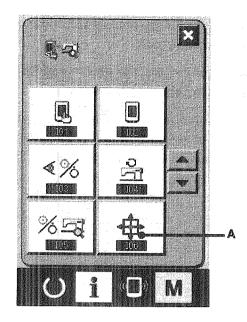


2. Output check

The output check screen can be used for the output check of each position. Try to press the output check button (B). While this button is pressed, the ON-status output is kept generated.

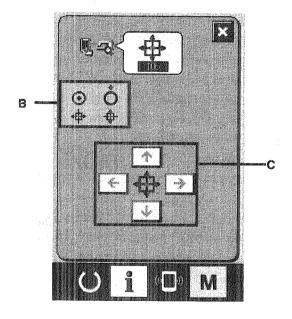
The output check display provides the following 17 types of positions:

	No.	Pictograph	Contents		No.	Pictograph	Contents
01 Ø	6.0	1/A	Wiper	10 √(9	9-9	Air output 9
02 Q		2 3-1	Air output 1	11 ≪((0_10	10 جي	Air output 10
03 √ €	6.2	≥ 0±2	Air output 2	12 4 0		2-11	Air output 11
04 Ø		30 3	Air output 3	13 √ (€	6.12	20-12	Air output 12
05 Q	O_ H	acr4	Air output 4	14 ≪(6120	A9-13	Air output 13
06 √ (€	0_ 5	2025	Air output 5	15 √ (€		14	Air output 14
07	o_ 6	€0 2°6	Air output 6	16 √Q	02:15	40-15	Air output 15
08 √Q	ا ا ا ا	7 سام الم	Air output 7	17 •Q	o_ 16	20-16	Air output 16
09 ⊲€	0_8	₹0n 8	Air output 8				



- 7) Method of XY motor / origin sensor check
- 1. Display of the XY motor / origin sensor check screen

When the XY motor / origin sensor check button
(A) is pressed on the check program screen,
the XY motor / origin sensor check screen is displayed.

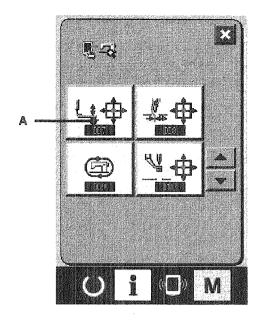


2. XY motor / origin sensor check

According to the status of the X/Y origin sensor, the ON/OFF condition of the sensor is displayed in the position of B.

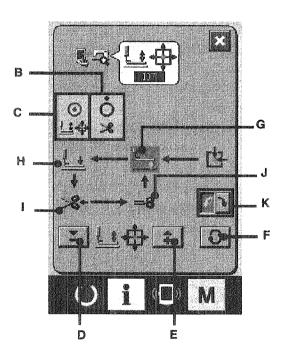
When the Arrow-Mark button (C) is pressed, the X/Y motor can be driven by 0.05mm in the +/-direction.

(Caution) 1. Using the Start SW, origin retrieval of the X/Y motors is effected for both shafts.



- 8) Method of presser and thread trimmer motor / origin sensor check
- 1. Display of the presser and thread trimmer motor / origin sensor check screen

When the presser and thread trimmer motor / origin sensor check button (A) is pressed on the check program screen, the presser and thread trimmer motor / origin sensor check screen is displayed.



2. Presser and thread trimmer motor / origin sensor check

According to the status of the thread trimmer sensor, the ON/OFF condition of the thread trimmer sensor is displayed in the position of B.

According to the status of the presser origin sensor, the ON/OFF condition of the presser origin sensor is displayed in the position of C.

Using the [+] and [-] keys (D, E), the presser / thread trimmer motor can be driven by one pulse.

When the fixed position moving button (F) is pressed, the presser / thread trimmer motor is driven to any of the following fixed positions. A pictograph indicating this position is displayed in gray.

G: Presser lifting position

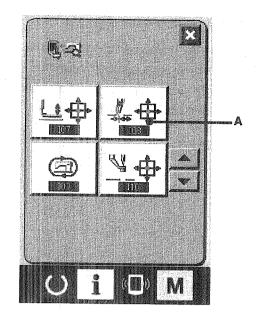
H: Presser lowering position (lowering position during pedal operation)

1 : Thread trimmer position

J: Presser lowering position (lowering position after thread trimming)

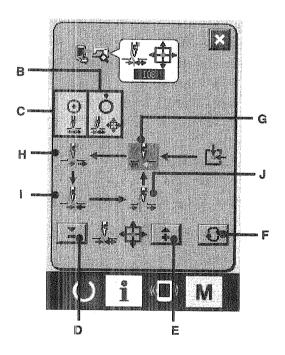
When the reverse rotation button (K) is pressed, driving is conducted in reverse direction. Using the Start SW, origin retrieval of the presser / thread trimmer motor is effected.

(Caution) The Start Switch becomes effective after the completion of origin retrieval for the presser / thread trimmer motor.



- Method of needle thread clamp motor / origin sensor check
- 1. Display of the needle thread clamp motor / origin sensor check screen is displayed.

When the needle thread clamp motor / origin sensor check button (A) is pressed on the check program screen, the needle thread clamp motor / origin sensor check screen is displayed.



2. Needle thread clamp motor / origin sensor check According to the status of the needle thread clamp sensor, the ON/OFF condition of the needle thread clamp origin sensor is displayed in the position of C. According to the status of the needle thread clamp origin sensor, the ON/OFF condition of the needle thread clamp sensor is displayed in the position of

Using the [+] and [-] buttons (D, E), the needle thread clamp motor can be driven by one pulse.

When the fixed position moving button (F) is pressed, the needle thread clamp motor is driven to any of the following fixed positions. A pictograph indicating this position is reversed and displayed.

G: Standby position (front side)

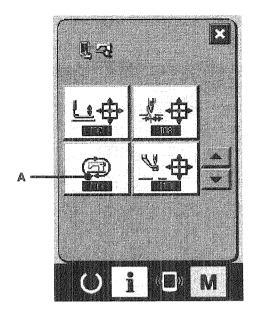
H: Needle thread bending position

I: Needle thread clamp position

J: Refuge position (rear side)

Using the Start SW, origin retrieval of the needle thread clamp motor is effected.

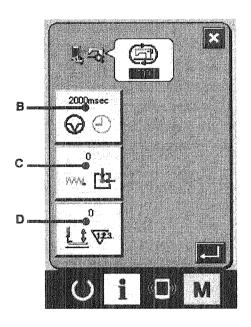
(Caution) The Start Switch becomes effective after the completion of origin retrieval for the needle thread clamp motor.



10) Method of continuous operation

1. Display of the continuous operation screen

When the continuous operation button (A) is pressed on the check program screen, the continuous operation screen is displayed.



2. Continuous operation

In the continuous operation screen, the continuous operation mode is set up.

B: Intervals of operation (rest time)

C: Origin retrieval at the end of sewing

0:No

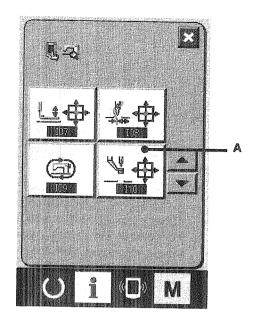
1: Every 100 runs

2: Every time

D: Presser lifting, lowering (frequency)

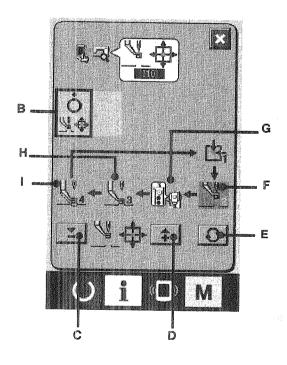
When the READY key is turned ON, continuous operation is started.

If the READY key is turned ON again in the middle of continuous operation, continuous operation is stopped.



- 11) Method of intermediate presser motor / origin sensor check
- 1. Display of the intermediate presser motor / origin sensor check screen

When the intermediate presser motor / origin sensor check button (A) is pressed on the check program screen, the intermediate presser motor / origin sensor check screen is displayed.



Intermediate presser motor / origin sensor check According to the status of the intermediate presser

origin sensor, the ON/OFF condition of the intermediate presser origin sensor is displayed in the position of B.

When the fixed position moving button (E) is pressed, the intermediate presser motor is driven to any of the following fixed positions. A pictograph indicating this position is reversed and displayed.

F: Lower position at the height of 7mm during lowering

G: Timing adjustment position

H: Lower position at the height of 0mm during lowering

I : Intermediate presser bar adjustment position

The START Switch is used for the origin retrieval of the intermediate presser motor.

7. Printed wiring board and dip switch

(1) Various printed wiring boards

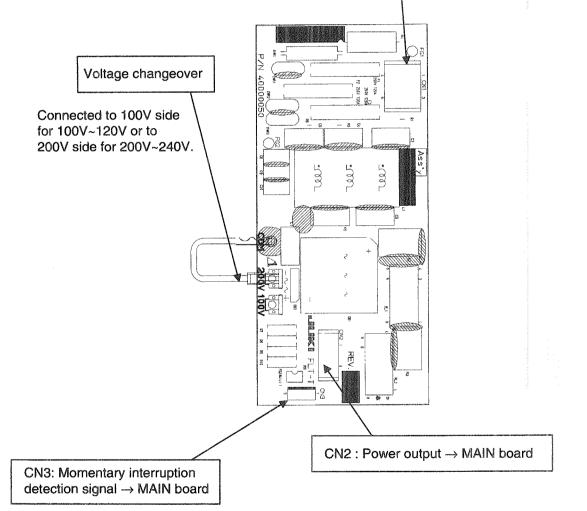
1) FLT-T board

Single-phase 100V~120V 3-phase 200V~240V

Pulse generation is carried out for the purposes of power supply rectification, noise reduction, and the detection of a momentary interruption

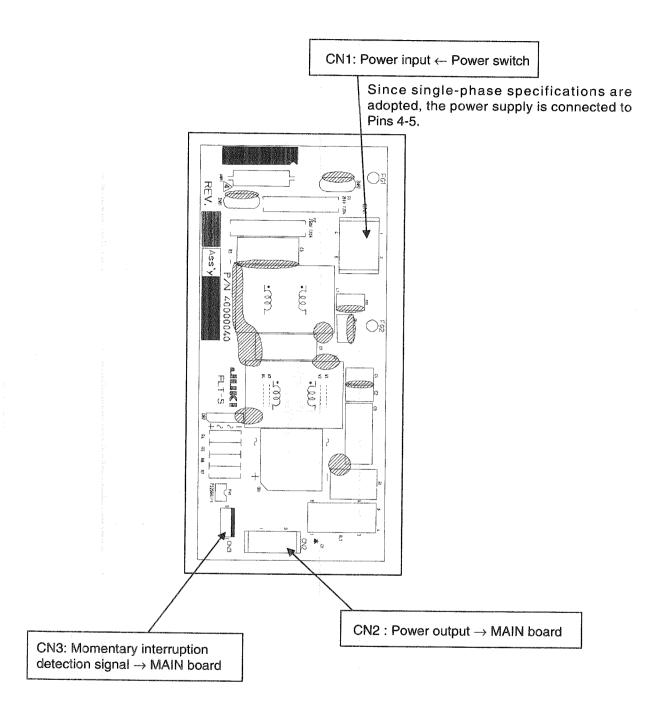
CN1 : Power input ← Power switch

In the signal-phase mode, the power supply is connected to Pins 4-5. In the 3-phase mode, the power supply is connected to Pins 4-5-6.

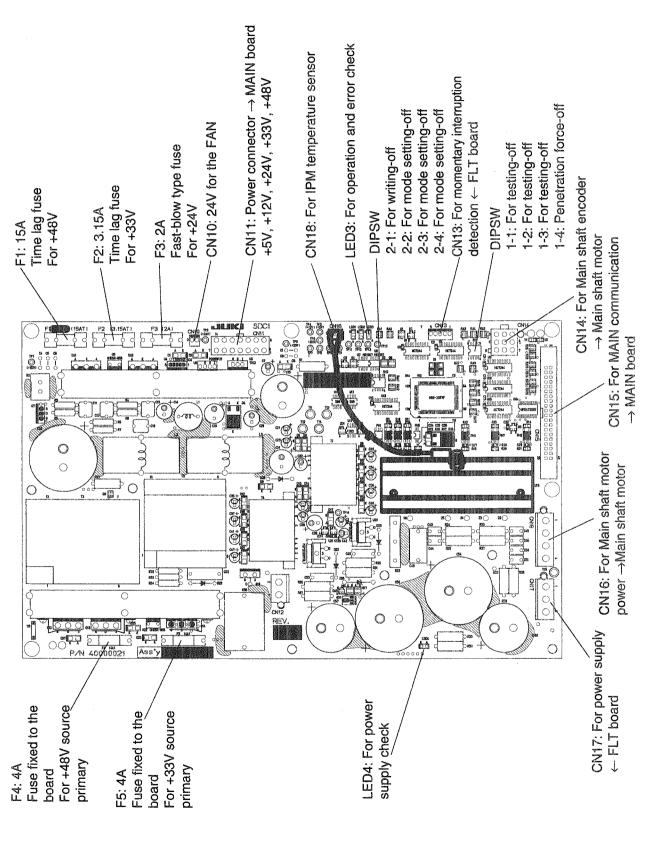


2) FLT-S board Single-phase 200V~240V

Pulse generation is carried out for the purposes of power supply rectification, noise reduction, and the detection of a momentary interruption



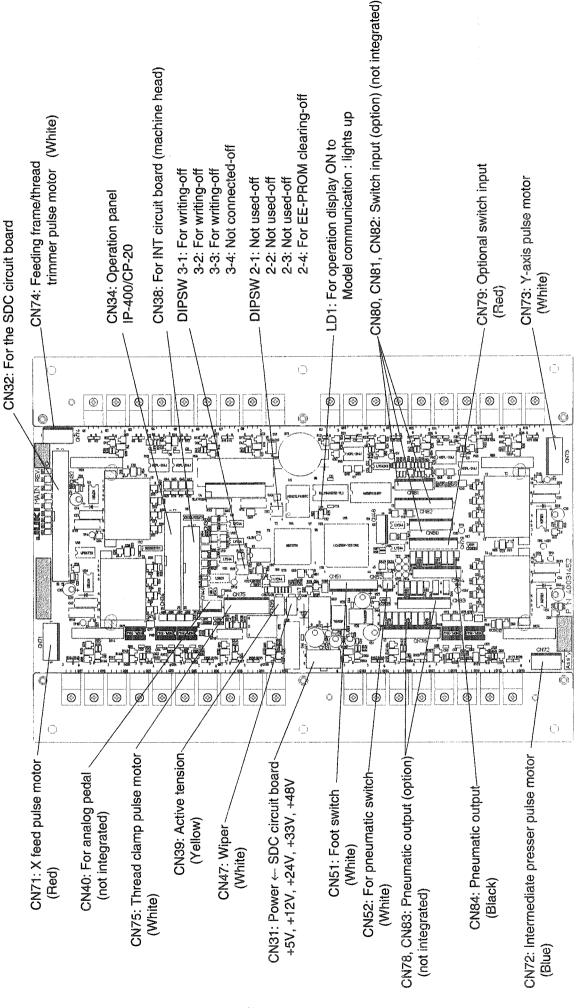
The power supply is generated and error check is carried out. Main shaft control is effected, receiving the commands from the MAIN board.



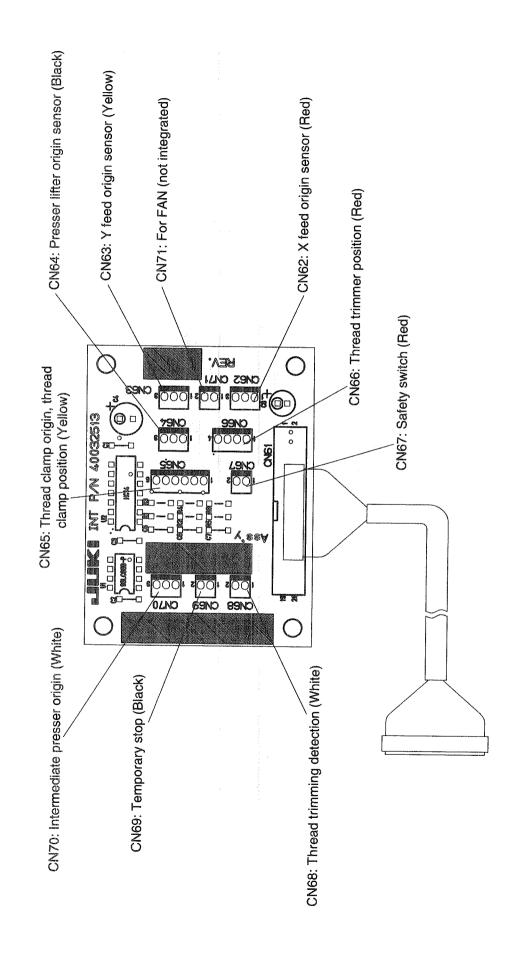
4) LED3 for SDC board error check

No. of LED3 flashes	Error description	Display of operation panel	Remarks
Turn on	Nil		Dimly turn on in ordinary state
1	Main shaft motor lock	E007	Failure in revolving for 2 seconds
2	Error in phase Z	E303	Failure in phase Z detection About 1.5 turns
3	Error in phases A and B	E730	Failure in phases A and B detection About 0.5 turns
4	Motor position sensor error	E731	Logical error in U, V, W
5	IPM error	E901	Error output generation from IPM
6	Undervoltage	E813	Source voltage -20% or more
7	Motor reverse rotation	E733	Irregular motor revolutions
8	Overvoltage	E811	Source voltage +20% or more
9	Power interruption	Display disabled	Power interruption of 40ms or more
10	Not used	·	
11	+85V power system error	E903	SDC board fuse F1 blow-off
12	+33V power system error	E904	SDC board fuse F2 blow-off
13	Overheasting	E905	Radiator panel of SDC boaed heated at 85°C or higher
14	Not used		
15	Communication erroe	E916	Failure in comminication with the MAIN board

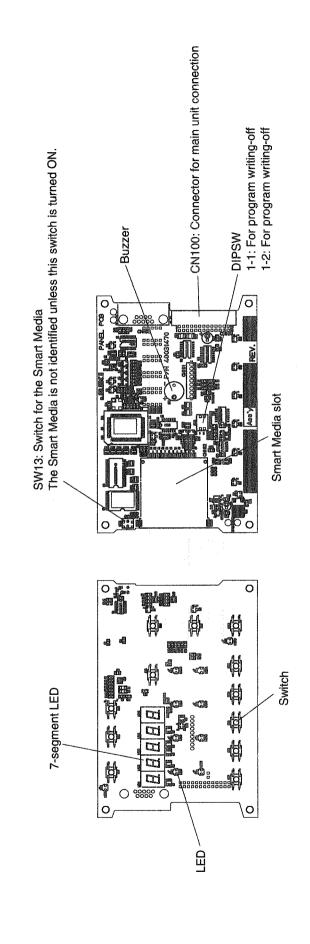
The board controls pulse motors, active tension, wipers, etc. for 5-axis separately and memory switch and other functions totally. 5) MAIN board



6) INT board
 The board relays head sensor signals and transmits head model information to the MAIN board.

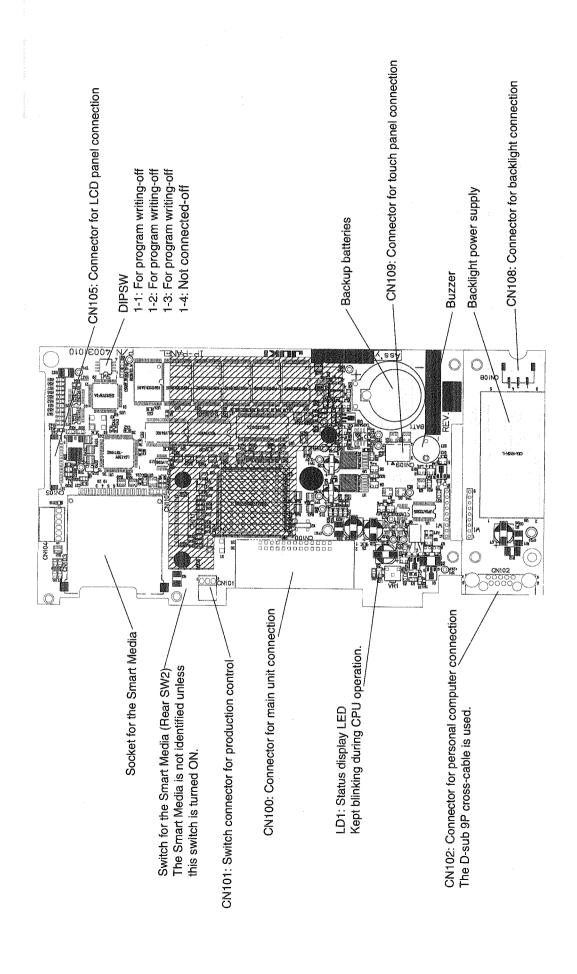


The Panel board accommodates the display LEDs, switch buzzer, etc. together with the Smart Media sockets.

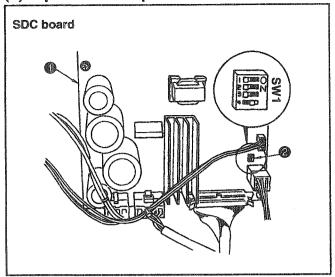


The Panel board is provided with the color LCD driver circuit, backlight power supply, CPU memories, etc., intended to support input and production control.

8) IP-400 Panel Board

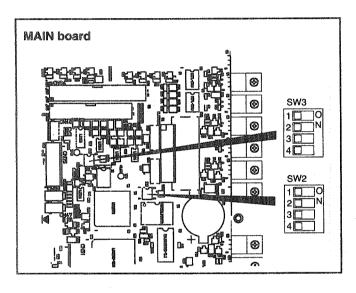


(2) Dipswitch setup



- The penetration force is increased when "4" of Dipswitch SW1 @ is turned ON on the SDC board
- 2. If the penetration force is insufficient for thick materials, this switch should be turned ON.
- 3. All other dipswitches should be turned OFF.

(Caution) Dipswitch changeover should be done after the power supply has been turned off.



4. All dipswitches on the MAIN board are turned OFF.

8. Table of exchanging gauge parts according to sewing specifications and needle size used

In accordance with the sewing condition, exchange the gauges referring to the following table.

Sewing spec. and needle size used Gauge	S type when delivered. #11 to #14	Knit. foundation garment	H type when delivered #16 to #20	#21 to #22	#00 A- #00	When thick needle like MR
	#11 10 #14	gament		#21 to #22	#23 to #26	type is used.
Needle hole guide	B242621000A ø1.6	B242621000C ø1.6 (For knit)	B242621000B ø2.0	B242621000D ø2.4	21000F 3.0 21000G 3.0 punter bore)	
Shuttle race ring						
			3352 uard 1.3 mm		14103659 Needle guard 1.7 mm	B1817210DAD Needle guard 1.9 mm
Shuttle	4001	4964	· :	40014965		
Intermediate presser	40023632 ø2.2		,	B1601210D0B B1601210 Ø2.7 Ø3.5		
				:		
Tension controller No.2 asm.					:	· .
	40010	40010508			9411	
Thread trimmer lever (small) asm.			B24152	800A0		
				700		
Needle bar thread guide	40026 2-ho	1		40026 One		

9. Option list

Name of parts	Туре	Part No	Size (mm)
1. needle hole guide	Needle hole guide (A) for light- weight material Needle hole guide (B) for medium-	B242621000A B242621000B	øA=1.6 øA=2.0
	weight material Needle hole guide (C) for knitwear Needle hole guide (D) for heavy-	B242621000C B242621000D	øA=1.6 øA=2.4
	weight material Needle hole guide (F) for heavy- weight material	B242621000F	øA=3.0
ØA	Needle hole guide (G) for heavy- weight material	B242621000G	øA=3.0 (With counter bore)
	Needle hole guide (H) for heavy- weight material Needle hole guide (H) (Counterme- asures against stitch skipping)	B242621000H	øA=3.0 (Eccentric)
	Move the needle hole to have an eccentricity of 0.5mm behind the center in order to make the clearance		
	narrower in front of the needle and wider behind it so that a loop can be established easily.		
Work clamp blank for preventing slipping	Rubber sheet for work clamp	B2591220000	Ax Bxt 250 x 200 x1.5
**	Sponge sheet for work clamp Work clamp material (A)	B2564215000 B2587220000	A x B x t 300 x 200 x 1.5 A x B x t
B	Work clamp material (B)	B2588220000	380 x 240 x 1 A x B x t 380 x 240 x 1.5
Feed plate blank for processing	Feed plate blank with knurl	B2556210D0A	ℓ 1x ℓ 2x t 168 x 131 x 1.2
l l			
	Feed plate blank without knurl	B2556210D0B	ℓ 1x ℓ 2x t 168 x 131 x 1.2
4. Intermediate presser	Intermediate presser (A)	40023632	øA x øB x ℓ x L
A PA	Intermediate presser (B)	B1601210D0BA	2.2 x 3.6 x 6 x 29.5 ØA x ØB x ℓ x L 2.7 x 4.1 x 6 x 29.5
M	Intermediate presser (C)	B1601210D0CA	ØA x ØB x ℓ x L 3.5 x 5.5 x 6 x 29.5
	Intermediate presser (E)	B1601210D0E	ØA x ØB x ℓ x L 1.6 x 2.6 x 6 x 29.5
øB	Intermediate presser (F)	B1601210D0FA	ØA x ØB x ℓ x L 2.2 x 3.6 x 9 x 29.5

Name of parts	Туре	Part No	Size (mm)
5. Feed plate blank	Sheet A for work clamp (Velboren) (Velboren)	B259522000A	A x B x t 1,000 x 675 x 1
1	Sheet B for work clamp (Velboren)	B259522000B	A x B x t 1,000 x 675 x 3
B	Sheet C for work clamp (Velboren)	B259522000C	A x B x t 1,000 x 675 x 2
A B	Plastic feed plate inner plate	GMU12038000	A x B x t 140.8 x 72.5 x1
B	Aluminum feed plate inner plate	GMU12037000	A x B x t 140.6 x 72.5 x 1
6. Cassette holder	Cassette holder installing base	B2593210DA0	
	Cassette holder assy	B2594210DA0	
7. Feeding frame blank	Plastic blank	B2557210DA0	
	Aluminum blank	GMU120350A0	

Name of parts	Туре	Part No	Size (mm)
8. Blank for processing	Separated type right blank of outer frame with knurl	40035609	A x B x t 97 x 81.5 x 4
t A	Separated type outer frame blank without knurl (Left and right are common.)	40035608	A x B x t 97 x 81.5 x 4
A to	Separated type left blank of outer frame with knurl	40035610	A x B x t 97 x 81.5 x 4
	Presser blank of outer frame with knurl	40035606	A x B x t 97 x 164 x 4
B	Presser blank of outer frame without knurl	40035607	A x B x t 97 x 164 x 4
9. Shuttle race ring compl.	A	14103253	A=0.8
	B (Standard) C D	14103352 14103659 B1817210DAD	A=1.3 A=1.7 A=1.9

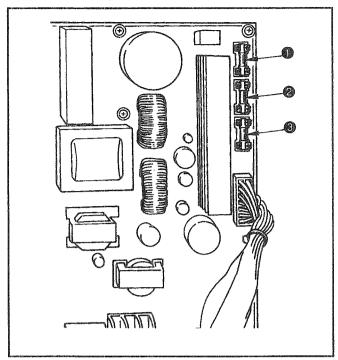
Name of parts	Туре	Part No	Size (mm)
10. Compressor unit		CU-01	
11. Economy type presser milling unit		MU-12	
12. Inverting clamp unit	(Caution) For the head of S type, it is necessary to provide for the AMS-210E air set separately.	FU-05 40036596	
13. One-touch clamp device	For S type For L type	B2585210DB0 B2586210DB0	
14. Inverting intermediate presser blank	Metal Plastic	B43172100X0 162371T3	A x B x t 135 x 58 x 3.2 A x B x t 100 x 50 x4

Name of parts	Туре	Part No	Size (mm)
15. Inverting intermediate presser installing base	Without bearing	D431421WJ0B	A x B 5 x 24
_		D430121XB00	A x B 7 x 20
		D431421WZ00	A x B 7 x 24
B		D431421WK00	A x B 8 x 24
A		D431421YF00	A x B 10 x 20
		D4314210000	A x B : 10 x 24
		Installing base B4314210A00	
		Bearing SB304000200	
0 0 0		Washer B4328210000	ni e enekin
16. Wiper			:
	Side-sweeping wiper assy	40035867	
De la companya della companya della companya de la companya della	Side-sweeping wiper repeater cable assy	40036668	
			:

Name of parts	Туре	Part No	Size (mm)
17. Pedal switch	3-step pedal (PK47)	GPK470010AB	
	Relay cable for 3-step pedal	40033875	
	2-step pedal (PK78)	40033831	
18. Needle cooler	(Caution) For the head of S type, it is necessary to provide for the AMS-210E air set separately.	40035692	
19. AMS-210E air set	To be exclusively used for Type S	40035693	

10. Maintenance

(1) Replacing the fuse



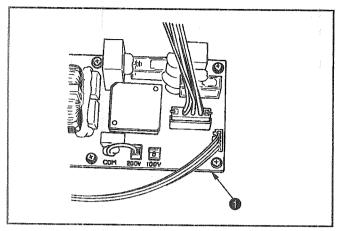
The machine uses the following three fuses: (SDC Board)

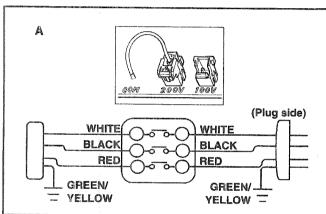
- For pulse motor power supply protection 15A(time-lag fuse)
- For solenoid and pulse motor power supply protection
 - 3.15A (time-lag fuse)
- For control power supply protection2A (fast-blow type fuse)

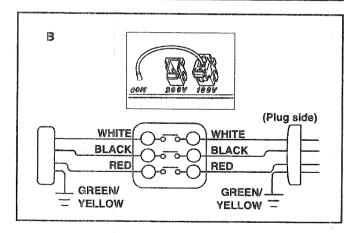
(2) Changing the voltage specification

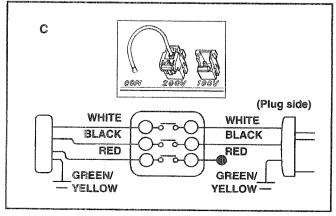
It is adaptable to the voltage of single phase 100V to 120V/3-phase 200V to 240V by changing the voltage changeover connector mounted on FLT-T p.c.b.

(Caution) When the changing procedure is wrong, the control box will be broken. So, be very careful.









Changing procedure of the changeover connector

- 1. Turn OFF the power source with the power switch after confirming that the sewing machine has stopped.
- 2. Draw out the power cord from the power plug socket after confirming that the power switch is turned OFF. Then wait for five minutes or more.
- 3. Remove the front cover.
- 4. Remove four screws fixing the rear cover of the control box and slowly open the rear cover.

A. In case of using with 3-phase 200V to 240V

- Changing the changeover connector
 Connect to 200V the 100/200V changeover connector of FLT-T p.c.b. located on the side of the Box Side of the control box.
- Connect the crimp style terminal of AC input cord to the power plug as shown in the figure.

B. In case of using with single phase 100V to 120V

- Changing the changeover connector
 Connect to 100V the 100/200V changeover connector of FLT-T p.c.b. located on the side of the Box Side of the control box.
- Connect the crimp style terminal of AC input cord to the power plug as shown in the figure.
- (Caution) Securely perform the insulation treatment to the red terminal which is not used with insulation tape or the like. (When the insulation is insufficient, there is a danger of electric shock or leakage current.)

C. In case of using with single phase 200V to 240V

- Changing the changeover connector
 Connect to 200V the 100/200V changeover connector of FLT-T p.c.b. located on the side of the Box Side of the control box.
- Connect the crimp style terminal of AC input cord to the power plug as shown in the figure.
- (Caution) Securely perform the insulation treatment to the red terminal which is not used with insulation tape or the like. (When the insulation is insufficient, there is a danger of electric shock or leakage current.)
- 5. Check that the change has been performed without fail before closing the rear cover.
- Be careful that the cord is not pinched between the rear cover and the control box main unit.
 Close the rear cover while pressing the lower side of rear cover, and tighten four screws.

(3) Greasing • lock-tight parts

- 1. When the parts for greasing and grease sealing-in are disassembled and the operational frequency seems to be higher than usual around these parts, grease should be replenished once every two years.
- 2. Recommendable grease

This sewing machine uses four types of grease as specified below. The recommendable brands of grease are listed in (4) Parts to which grease lock-tight is applied. According to this information, replenish the most applicable grease to these parts.

- * Use ① Lithium Type consistency No. 2 for the parts where "Grease" is simply specified in (4) Parts to which grease-lock-tight is applied.
 - 1 Penetration No. 2 lithium grease

This type of grease is used in general sliding parts.

Maker name	Brand name
Esso:	Listan 2, Beacon 2
Shell:	Albania
Nippon Oil Co., Ltd.:	Multinok 2, Epinok 2
Kyodo Oil Co., Ltd.:	Lisonix 2
Idemitsu Petrochemical Co., Ltd.:	Coronex 2

② Templex N2 (Grease D) •••• Used for the feeding gear block.

10g tube JUKI Part No.: 13525506

③ JUKI Grease A •••• Used for high-speed sliding parts and their peripheral parts.

10g tube JUKI Part No.: 40006323 500g (IE-22) JUKI Part No.: 23640204

4 JUKI Grease B •••• Used, in particular, for the specific areas with highly loaded parts. Important: this grease must be replenished at the specified intervals of period, according to "(5) Grease-up procedures for the specified position."

10g tube JUKI Part No.: 40013640

3. Method of greasing

If no grease pump is available, fill a plastic oilcan with grease. Otherwise, an injector without a needle can be conveniently used.

4. Miscellaneous

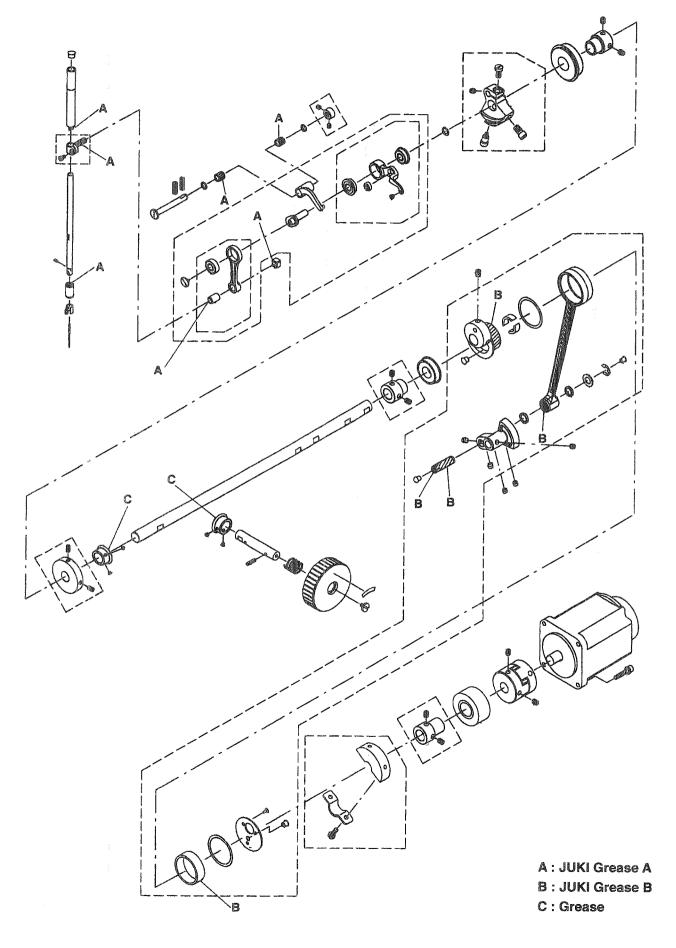
An injector to be used exclusively for coating / JUKI Part No. : GDS01007000

5. Application of Lock Tight

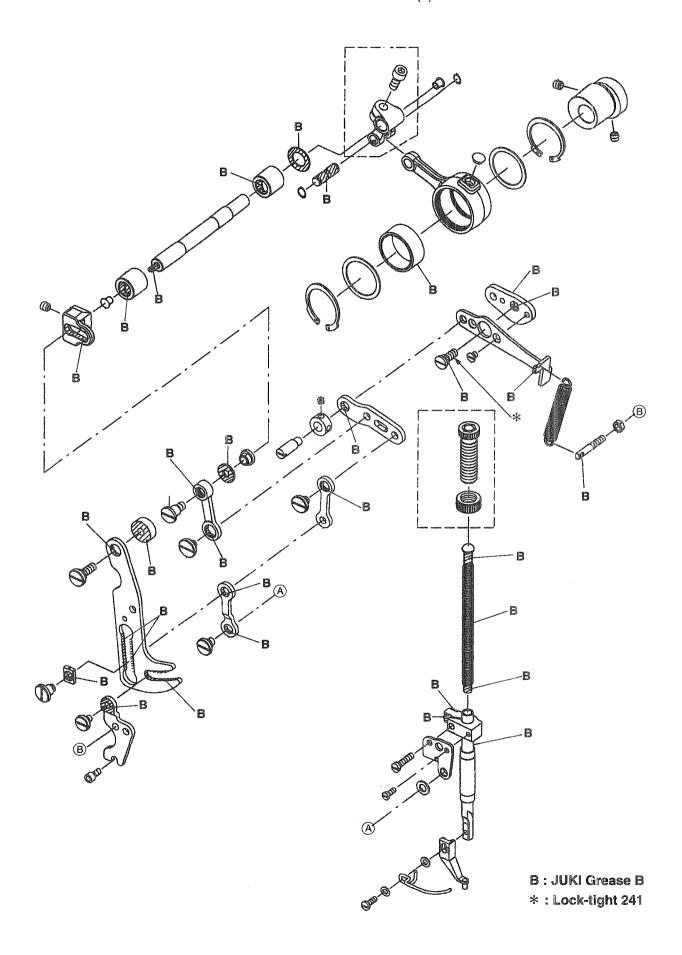
Apply Lock Tight 241 to section with the asterisk* .

(4) Parts to which grease • lock-tight is applied

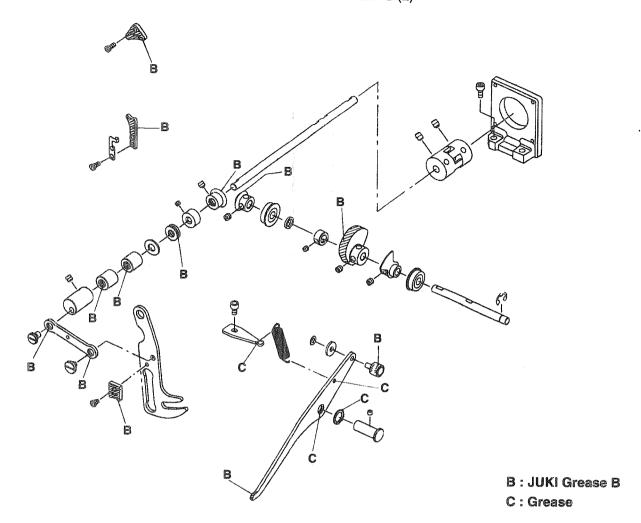
o MAIN SHAFT & NEEDLE BAR COMPONENTS



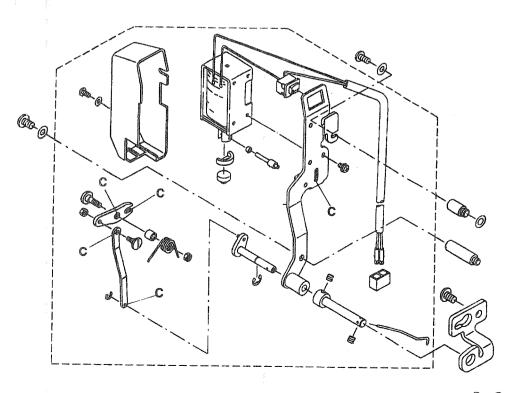
o PRESSER MECHANISM & PRESSER VARIABLE COMPONENTS (1)



o PRESSER MECHANISM & PRESSER VARIABLE COMPONENTS (2)

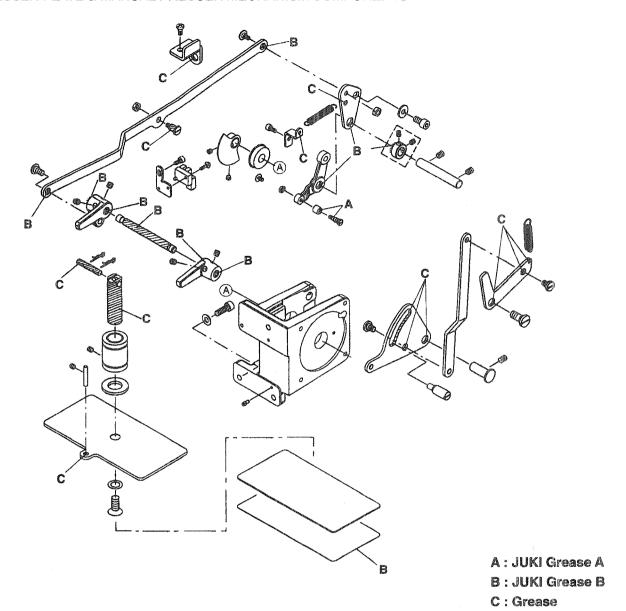


o WIPER MECHANISM COMPONENTS

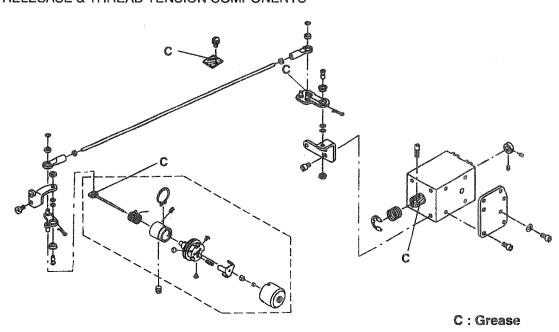


C : Grease

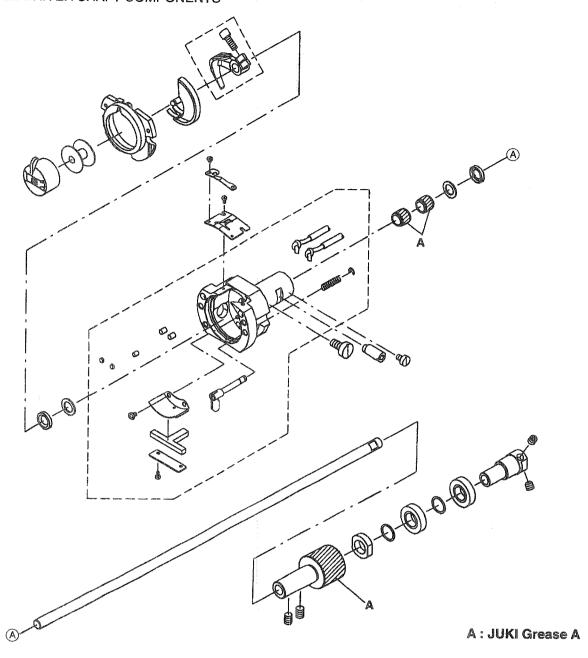
o PRESSER PLATE & MANUAL PRESSER MECHANISM COMPONENTS



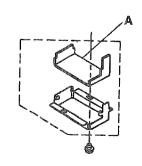
o TENSION RELESASE & THREAD TENSION COMPONENTS



o SHUTTLE DRIVER SHAFT COMPONENTS

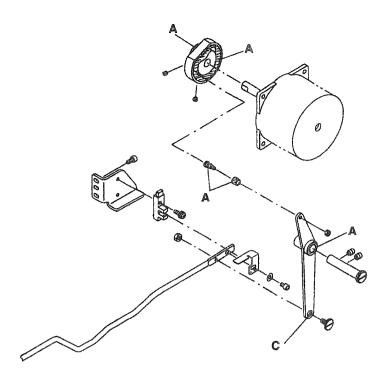


o FRAME & MISCELLANEOUS COVER COMPONENTS (2)



A: JUKI Grease A

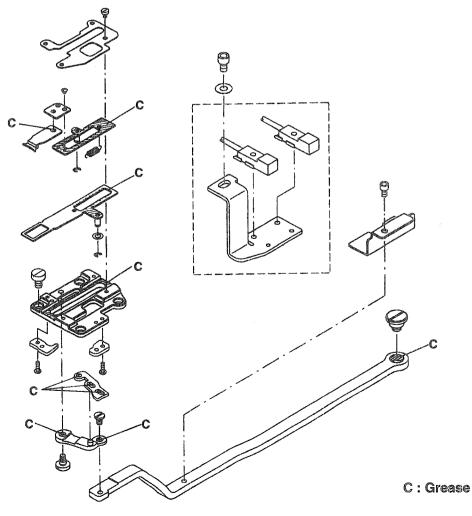
o TENSION RELEASE & THREAD TRIMMER MECHANISM COMPONENTS

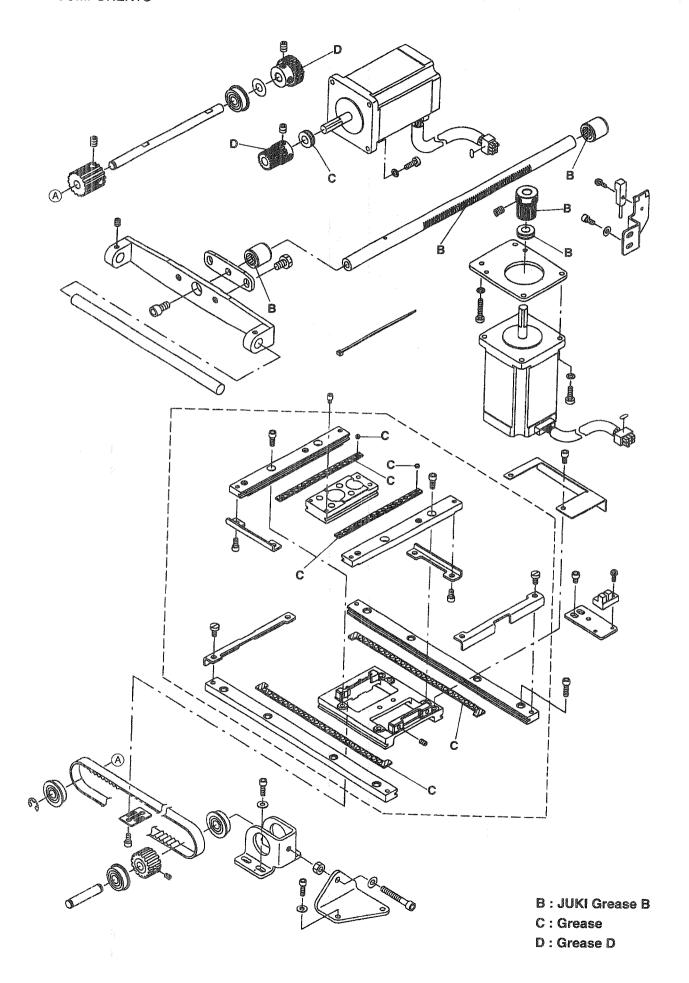


A: JUKI Grease A

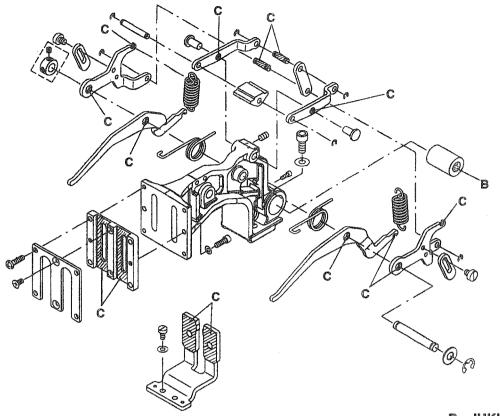
C : Grease

o THREAD CLAMP COMPONENTS





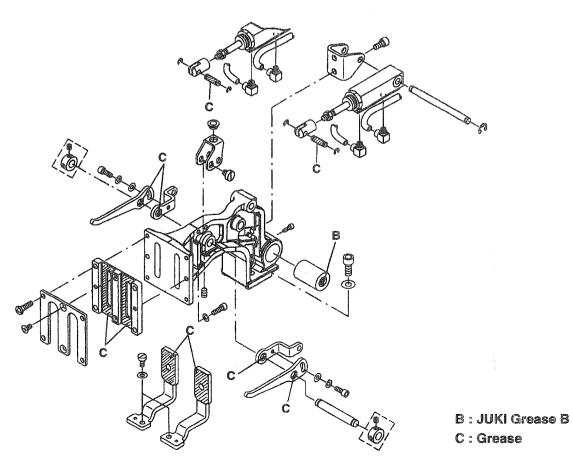
o CLOTH FEED MECHANISM COMPONENTS (FOR AMS-210EHS, ESS)



B: JUKI Grease B

C : Grease

o CLOTH FEED MECHANISM COMPONENTS (FOR AMS-210EHL, ESL)



(5) Replenishing the designated places with grease

* Perform grease supplement when the errors below are displayed or once a year (either one which is earlier). After performing grease supplement, call memory switch No. 245 and set the value to i0i with the reset key.

When the sewing machine has been used for a certain number or times of sewing, error code No. E220 is displayed on the operation panel at the time of turning ON the power. This display informs the operator of the time of replenishing the designated places with grease. Be sure to replenish the places with the grease below. Then call the memory switch No. 245 and set it to i0i with the RESET key.

Even after the display of the error No. E220, when the RESET key is pressed, the error is released, and the sewing machine can be continuously used. Afterwards, however, the error No. E220 is displayed every time the power is turned ON.

In addition, when the sewing machine is used further for a certain period of time after the display of error No. E220, the error No. E221 is displayed and the sewing machine fails to operate since the error cannot be released even when the RESET key is pressed.

When the error No. E221 is displayed, be sure to replenish the designated places below with grease.

Then start up the memory switch and set No. 245 to "0" with the RESET key.

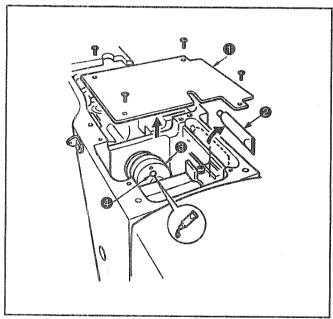
- (Caution) 1. After replenishing the places with grease, the error No. E220 or No. E221 is displayed again unless the memory switch No. 245 is changed to "0".
 - 2. Use grease tube (JUKI grease B Part No. : 40013640) supplied as accessories to replenish the designated places below with grease. If grease other than the designated one is replenished, damage of components will be caused.



WARNING:

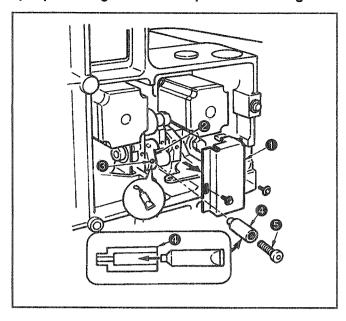
Turn OFF the power before starting the work so as to prevent accidents caused by abrupt start of the sewing machine.

1) Replenishing the eccentric cam section with grease



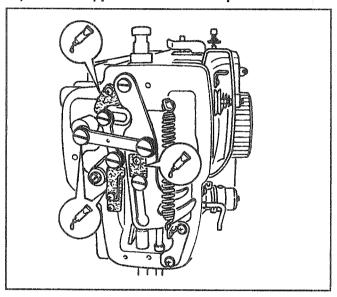
- 1. Open the upside cover (1) and remove the JUKI grease B (2).
- 2. Remove rubber cap ② located on the side of eccentric cam ③ . Then replenish there with JUKI grease B ②.

2) Replenishing the oscillator pin section with grease



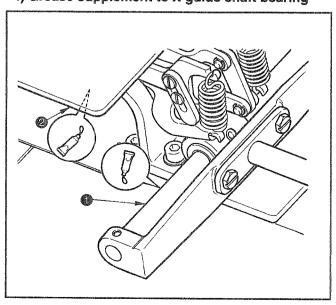
- 1. Tilt the machine head and remove the grease cover ••.
- 2. Fill joint **(a)** supplied as an accessory with JUKI Grease B.
- 3. Remove setscrew (3) in oscillator gear (2) and screw in joint (4) into the screw hole.
- 4. Screw in screw supplied as accessories to the joint and replenish there with JUKI grease B.
- 5. Securely tighten setscrew (3) which has been removed after replenishing with the grease.

3) Grease supplement to the face plate section



- 1. Open the face plate cover.
- 2. Supplement JUKI grease B to the felt section (3 places) and the hinge screws around them.

4) Grease supplement to X guide shaft bearing



1. At the same time, apply JUKI grease B to the rear faces of X guide shaft and presser plate .

11. Error code list

Error code	Pict	Description of error	How to recover	Place of recovery
E001		Data is initializes (EEPROM of MAIN CPU)	Turn OFF the power	
E007		Main shaft motor-lock When large needle resistance sewing product is sewn	Turn OFF the power	
E008	TYPE	Head connector abnormality Memory of machine head cannot be read.	Turn OFF the power	
E010	Slogh.	Pattern No. error Pattern No. which is backed up is not registered to data ROM,or setting of reading inoperative is performed.	Possible to re-enter after reset.	Previous screen
E011		External media not inserted External media is not inserted.	Possible to re-enter after reset.	Previous screen
E012	× 疆	Read error Data read from external media cannot be performed.	Possible to re-start after reset.	Previous screen
E013		Write error Data write from external media cannot be performed.	Possible to re-start after reset.	Previous screen
E014	and the second s	Write protect External media is in the write prohibition state	Possible to re-start after reset.	Previous screen
E015		Format error Format cannot be performed.	Possible to re-start after reset.	Previous screen
E016		External media capacity over Capacity of external media is short.	Possible to re-start after reset.	Previous screen

Error code	Pict	Description of error	How to recover	Place of recovery
E017		EEP-ROM capacity over When the mounted EEP-ROM is different in type.	Possible to re-start after reset.	Previous screen
E018	TYPE	Type of EEP-ROM is different. When the mounted EEP-ROM is different in type.		Previous screen
E019		File size over Pattern data size over	Possible to re-start after reset.	Previous screen
E022	Ra.	File No. error There is no designated file in the server or external media.	Possible to re-start after reset.	Previous screen
E024		Pattern data size over When sewing cannot be performed since the size of downloaded sewing data is too large.	Possible to re-start after reset.	Data input screen
E027		Read error Data read from server cannot be performed.	Possible to re-start after reset.	Previous screen
E028	89	Write error Data write to the server cannot be performed.	Possible to re-start after reset.	Previous screen
E029		Smart media slot release error Lid of smart media slot is open.	Possible to re-start after reset.	Previous screen
E030		Needle bar upper position failure Turn hand pulley to bring needle bar to its UP position	Turn hand pulley to bring needle bar to its UP position.	Data input screen
E031	*	Air pressure drop When the air pressure is lowered.	Possible to re-start after reset.	Data input screen

Error code	Pict	Description of error	How to recover	Place of recovery
E032	AD S	File interchanging error File cannot be read.	Possible to re-start after reset.	Data input screen
E040	E	Sewing area over When the sewing area is exceeded	Possible to re-start after reset.	Sewing screen
E042	No.	Operation cannot be performed.	Possible to re-start after reset.	Previous screen
E043	11.7 P	Enlarging error Sewing pitch exceeds Max. pitch.	Possible to re-start after reset.	Data input screen
E045		Pattern data error These pattern data are not applicable.	Possible to re-start after reset.	Data input screen
E050	②	Stop switch When stop switch is pressed during machine running.	Possible to re-start after reset.	Step screen
E052	¥%.	Thread breakage detection error When thread breakage is detected.	Possible to re-start after reset.	Step screen
E061	4B1	Memory switch data error Memory switch data is broken or revision is old.	Turn OFF the power.	
E063	IYPE LI	Head discrimination error Head discrimination and the kind of control box are different.	Turn OFF the power.	
E220	TORROGEO DE	Grease-up warning At the time of operation of 100 million stitches → Refer to "10(5) Replenishing the designated places with grease".	1	Data input screen
E221 :	issinging Ayea	Grease-up error At he time of operation of 120 million stitches The sewing machine is put in the sewing-impossible status. It is possible to clear with memory switch → Refer to "10(5) Replenishing the designated places with grease".		Data input screen

Error code	Pict	Description of error	How to recover	Place of recovery
E302	é P	Confirmation of tilt of machine head When tilt of machine head sensor is OFF.	Possible to re-start after reset.	Previous screen
E303	To a section of the s	Phase Z detection error Detection of the upper dead point is impossible for the sewing machine.	Turn OFF the power.	
E305	>8≪	Thread trimmer knife position error The thread trimmer knife is not in the regular position.	Turn OFF the power.	Data input screen
E306	#4	Thread clamp position error Thread clamp unit is not in the regular position.	Turn OFF the power	
E307	ZI,	External input command time out error Input is not performed for a fixed period of time with the external input command of vector data.	Possible to re-start after reset.	Data input screen
E308	₹ 700°	Time-out error of wait terminal There is no input to wait terminal for a certain period of time.	Turn OFF the power	
E431		Outer presser is rising.	Possible to re-start after reset.	Previous screen
E432	E	Proper operation has not been performed.	Possible to re-start after reset.	Previous screen
E433	V2.52	Number of stitches has exceeded the limit.	Possible to re-start after reset.	Previous screen
E434	The second secon	Hadware error has occurred.	Possible to re-start after reset.	Previous screen
E437		Function cannot be selected.	Possible to re-start after reset.	Previous screen

Error code	Pict	Description of error	How to recover	Place of recovery
E438	3	Execution cannot be performed.	Possible to re-start after reset.	Previous screen
E441		Back-up data does not exist.	Possible to re-start after reset.	Previous screen
E703	TYPE	Panel is connected to the machine other than supposed. (Machine type error) When machine type code of system is improper in case of initial communication.	Possible to rewrite program after pressing down communication switch.	Commnunication screen
E704	R-Y-L CIEC	Inconsistency of system version When version of system software is improper in case of initial communication.	Possible to rewrite program down communication switch.	Commnunication screen
E730		Main shaft motor encoder defectiveness or phase-out When encoder of sewing machine motor is abnormal.	Turn OFF the power	
E731		Main motor hole sensor defectiveness or position sensor defectiveness When hole sensor or position sensor of sewing machine is defective.	Turn OFF the power.	
E733	E Company	Reverse rotation of main shaft motor When sewing machine motor rotates in reverse direction.	Turn OFF the power.	
E802		Power instantaneous cut detection When input power is instantaneously OFF.	Turn OFF the power.	
E811	Figure 1 and	Over voltage When input power is more than the specified value.	Turn OFF the power.	
E813		Low voltage When input voltage is 150V or less.	Turn OFF the power.	
E901		Abnormality of main shaft motor IPM When IPM of servo control p.c.b. is abnormal.	Turn OFF the power.	

Error code	Pict	Description of error	How to recover	Place of recovery
E903		Abnormality of stepping motor power When stepping motor power of servo control p.c.b. fluctuates ±15% or more.	Turn OFF the power.	
E904	c (131)	Abnormality of solenoid power When solenoid power of servo control p.c.b. fluctuates ±15% or more.	Turn OFF the power.	
E905		Heat sink temperature for SERVO CONTROL p.c.b. fabnormality Turn ON the power again after taking overheat time of SERVO CONTROL p.c.b.	Turn OFF the power.	
E907	少中	X feed motor origin retrieval error When origin sensor signal is not inputted at the time of origin retrieval motion.	Turn OFF the power.	
E908	<u> </u>	Y-feed motor origin retrieval error When origin sensor signal is not inputted at the time of origin retrieval motion.	Turn OFF the power.	
E910	<u> </u>	Presser motor origin retrieval error When origin sensor signal is not inputted at the time of origin retrieval motion.	Turn OFF the power.	
E913	华中	Thread clamp origin retrieval error When origin sensor signal is not inputted at the time of origin retrieval motion.	Turn OFF the power.	
E914	+==-	Feed defective error Timing lag between feed and main shaft occurs.	Turn OFF the power.	
E915	(((-3))	Abnormality of communication between operation panel and main CPU When abnormality occurs in data communication.	Turn OFF the power.	
E916	(((**)))	Abnormality of communication between main CPU and main shaft CPU When abnormality occurs in data communication.	Turn OFF the power.	
E917	(((*)))	Failure of communication between operation panel and personal computer When abnormality occurs in data communication.	Possible to re-start after reset.	

Error code	Pict	Description of error	How to recover	Place of recovery
E918		MAIN board overheat Overheat of MAIN board Turn ON the power again after taking time.	Turn OFF the power.	
E925	似由	Intermediate presser motor origin retrieval error Origin sensor of intermediate presser motor does not change at the time of origin retrieval.	Turn OFF the power.	
E943	(×);	MAIN EEP-ROM trouble When data writing to EEP-ROM cannot be performed.	Turn OFF the power.	
E946	×E	Defective EEP-ROM writing of HEAD RELAY board When data writing to EEP-ROM cannot be performed.	Turn OFF the power.	
E948	×B	F-ROM abnormality When erase or writing of program cannot be performed at the time of downloading program.	Turn OFF the power.	

12. Troubles and corrective measures (1) Mechanical parts

		menementer en			
		Cause (1)	Cause (2)	Check and corrective measures	
_	1. Sewing machine locked	1-1) Large needle compared with the hole diameter of the needle hole guide		Replace the needle hole guide.	
	2. Deformation in sewn patterns	2-1)X timing belt tension is maladjusted.		Adjust the X timing belt tension.	
		2-2) Backlash of the X feed motor gear is maladjusted.		Adjust the position of X feed motor.	
		2-3) Backlash of the Y feed motor gear is maladjusted.		Adjust the position of Y feed motor.	
		2-4) Traveling torque in X direction or Y direction is excessive.	4-A) Pressure of the X-Y table is too high.	Adjust the pressure of the X-Y table.	
201			4-B) Height or horizontality is inadequate for the needle bar auxiliary cover.	Adjust the height or the horizontality of the needle bar auxiliary cover.	
		2-5) Pressing pressure is too low.	5-A)Regulator is maladjusted.	Adjust the regulator.	
		(Air specification)	5-B) Supply air pressure is too low.	Adjust the supply air pressure.	
	3. There is no coincidence between the input origin and the sewing origin.	3-1) Inadequate adjustment of the X origin sensor		Adjust the position of X origin sensor.	
-		3-2) Inadequate adjustment of the Y origin sensor		Adjust the position of Y origin sensor.	
	4 Feeding action does not stop even after exceeding the sewing range.	4-1) Inadequate adjustment of the X origin sensor		Adjust the position of X origin sensor.	
•		4-2) Inadequate adjustment of the Y origin sensor		Adjust the position of Y origin sensor.	
	5. The amount of lifting is small for the outer frame of the cloth presser.	5-1) Inadequate adjustment of the height of the presser		Adjust the height of the presser.	
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Trouble 6. The outer frame of the cloth presser	Cause (1)	Cause (2)	Check and corrective measures
cannot be lifted or lowered.	screw is loose. (Motor specification only)		Decide the position of the thread trimmer cam screw and fix it.
	6-2) Presser pulse motor malfunction (motor specifications only)	2-A) The presser pulse motor is out of order.	Replace the presser pulse motor.
		2-B) Connection of presser pulse motor is improper.	Check the connector connections.
	6-3) Defective board	3-A) The board is out of order.	Replace the board.
		3-B) Connector connections are improper.	Check the connector connections.
	6-4) There are inadequate fitting conditions among the work feed		Examine the positions for greasing.
	bar, the link, and the face plate.		The sewing material is not pressed completely by the outer frame as a whole.
	6-5) Supply air pressure is too low. (Air specification only)		Adjust the supply air pressure.
	6-6) Inadequate adjustment of the regulator (air specifications only)		Adjust the regulator.
	6-7) Solenoid valve malfunction (air specifications only		Reolace the solenoid valve.
·	6-8) Inadequate adjustment of the speed controller (air specifications only)		Adjust the speed controller.
7. The intermediate presser does not rise after sewing.	7-1) There are some inadequate fitting conditions in the intermediate presser link mechanism.		Check for the inadequate fitting and rattling conditions in the link mechanism. Examine the positions for greasing.
	7-2) Intermediate presser variable is maladjusted.		Adjust the intermediate presser variable.
	7-3) Intermediate presser pulse motor malfunction	3-A) Intermediate presser pulse motor is out of order.	Replace the intermediate presser pulse motor.
		3-B) Connection of intermediate presser pulse motor is improper.	Check the connector connections.
	7-4) Defective board	4-A) The board is out of order.	Replace the board.
		4-B) Connector connections are improper.	Check the connector connections.

Check and corrective measures	Check for the inadequate fitting and rattling conditions in the link mechanism. Examine the positions for greasing.	Intermediate presser variable adjustments.	e Replace the intermediate presser pulse motor.	te Check the connector connections.	Replace the board.	e Check the connector connections.	Adjust the intermediate presser variable stroke.	Adjust the clearance between the inner hook and the driver.	Adjust the intermediate presser adjusting arm.	Adjust the height of the intermediate presser.	Adjust the presser.	Intermediate presser variable adjustments.	Replace the intermediate presser pulse motor.	te Check the connector connections.	Replace the board.	re Check the connector connections.
Cause (2)			3-A) Intermediate presser pulse motor is out of order.	3-B) Connection of intermediate presser pulse motor is improper.	4-A) The board is out of order.	4-B) Connector connections are improper.				3-A) Inadequate adjustment of the height of the intermediate presser			6-A) Intermediate presser pulse motor is out of order.	6-B) Connection of intermediate presser pulse motor is improper.	7-A) The board is out of order.	7-B) Connector connections are improper.
Cause (1)	8-1) There are some inadequate fitting conditions in the intermediate presser link mechanism.	8-2) Intermediate presser variable is maladjusted.	8-3) Intermediate presser pulse motor malfunction		8-4) Defective board		8-5) The intermediate presser stroke has decreased to 0mm.	9-1) The clearance is too much between the inner hook and the driver.	9-2) The intermediate presser bar connection comes in contact with the lower metal of the intermediate presser needle bar.	9-3) The intermediate presser comes in contact with the throat plate.	9-4) The intermediate presser comes in contact with the cloth presser.	9-5) Intermediate presser variable is maladjusted.	9-6) Intermediate presser pulse motor malfunction		9-7) Defective board	
Trouble	8. The intermediate presser does not work during sewing.							9. Unusual sound is generated from the face section.								

	Trouble	Cause (1)	Cause (2)	Check and corrective measures
	10. Even when the sewing machine is started, it goes to stop soon.	10-1) The needle thread is not hooked.		Pass the needle thread.
		10-2) Position of the thread breakage detecting plate is wrong.		Adjust the position of the thread breakage detecting plate.
	11. Even though the needle thread is broken, the sewing machine does not stop.	11-1) Position of the thread breakage detecting plate is wrong.		Adjust the position of the thread breakage detecting plate.
	12. Wiper cannot spread a thread	12-1) Interference between wiper and needle	1-A) Wiper mounting position is inadequate.	Adjust the wiper position.
		12-2) Interference between wiper and intermediate presser	2-A) Inadequate adjustment of the height of the intermediate presser	Adjust the height of the intermediate presser.
	, , ,		2-B) Wiper mounting position is inadequate.	Adjust the wiper position.
- 204 -		12-3) There is no clearance between the needle and intermediate presser to pass the wiper.	3-A) The cloth thickness permitting the use of a wiper is exceeded.	Use the lower wipe-out sequence.
		12-4) The wiper does not move after thread trimming.	4-A) The wiper switch is turned OFF.	Turn the wiper switch ON.
	13. Severe vibration	13-1) Position of the crank balancer is wrong.		Define the correct crank balancer position.

1-1) Stitch skipping at the start of recedite and hook. Sewing 1-2) Stitch skipping at the start of recedite and hook. Sewing 1-2) Length of thread remaining at the start of thread remaining at the needle is not sufficient. 2-B) Floating of the AT thread at thr	(2) Sewing conditions	(8)		
sewing 1-2) Length of thread remaining 1-2) Penetration registance of the thread remaining an excessive training is not sufficient. 2-6) Floating of the AT thread thread take-up spring an excessive training is not sufficient. 2-6) The thread thread take-up spring thread take-up spring is excessively high. 2-7) The thread thread take-up spring thread to between the needle hole guide and the counter knife is excessively high. 2-7) Thread spreading section of the meadle hole guide and the needle hole guide and the counter knife is excessively high. 2-6) Thread spreading section of the maining is not sufficient. 2-6) Thread spreading section of the meadle hole guide has scratches. 3-6) Thread spreading section of the needle hole guide has scratches. 3-6) Thread spreading section of the moving knife has scratches. 3-7) Thread spreading section of the moving knife has scratches. 3-6) Thread spreading section of the moving knife has scratches. 3-7) Thread spreading section of the moving knife has scratches. 3-7) Thread spreading section of the moving knife has scratches. 3-8) Lower face of the needle hole guide and the counter knife is excessively high. 3-8) Thread spreading section of the moving knife has scratches. 3-9) Shuttle upper spring has scratches. 3-6) Thread spreading section of the moving knife has scratches. 3-7) Thread spreading section of the moving knife has scratches. 3-7) Thread spreading section of the moving knife has scratches. 3-7) Thread spreading section of the moving knife has scratches. 3-7) Thread spreading section of the moving knife has scratches. 3-7) Thread spreading section of the moving knife has scratches.	Trouble	Cause (1)	Cause (2)	Check and corrective measures
1-8) Penetration registance of the thread remaining at the needle is not sufficient. 2-A) Tension or controller No. 1 provides and the reason disc is insufficient. 2-C) Stroke of the thread take-up spring is excessive insufficient. 2-C) Stroke of the thread take-up spring is excessively right. 2-C) Thread take-up pring is excessively right. 2-C) Thread is excessively right. 2-C) Thread is excessively right. 2-C) Thread spreading section of the media hole guide and the counter fivile is excessively right. 2-C) Thread spreading section of the maining is not sufficient. 3-A) Level difference between the counter fivile is excessively right. 3-A) Level difference between the counter fivile is excessively right. 3-C) Thread spreading section of the media hole guide and the counter fivile is excessively right. 3-C) Thread spreading section of the maining is not sufficient. 3-C) Thread spreading section of the media hole guide and the counter fivile is excessively right. 3-C) Thread spreading section of the media hole guide and the counter fivile is excessively right. 3-C) Thread spreading section of the media hole guide and the counter fivile is excessively right. 3-C) Thread spreading section of the media hole guide and the counter fivile is excessively right. 3-C) Thread spreading section of the media hole guide and the counter fivile is excessively right. 3-C) Thread spreading section of the media hole guide and the counter fivile is excessively right. 3-C) Thread spreading section of the media hole guide and the counter fivile is excessively right. 3-C) Thread spreading section of the media hole guide and the counter fivile is a scratches.	1. Thread comes off at the start of	1-1) Stitch skipping at the start of	1-A) Too much clearance between	Set the clearance at 0.05 to 0.1mm between the needle and the hook.
the against the cloth is small. 2-A) Tension controller No. 1 provides an excessive tension. 2-B) Floating of the AT thread take-up spring is excessive. 2-C) Stroke of the thread take-up spring is excessive. 2-D) The thread take-up spring tension is insufficient. 2-E) Level difference between the needle hole guide and the counter knife is excessively high. 2-F) Needle thread is excessively high. 2-F) Needle thread is excessively high. 2-G) Thread spreading section of the moving knife has scratches. 3-A) Level difference between the needle hole guide and the counter knife is excessively high. 3-B) Lower face of the needle hole guide and the counter knife is excessively high. 3-B) Lower face of the needle hole guide and the counter knife is excessively high. 3-B) Shuttle upper spring has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section is excessively high. 3-B) Lower face of the needle hole guide and the counter knife is excessively high. 3-B) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches.	fi maps	BILLMOO	300000000000000000000000000000000000000	Set up "soft start" at the beginning of sewing.
2-B) Floating of the AT thread the needle is not sufficient. 2-B) Floating of the AT thread tension disc is insufficient. 2-C) Stroke of the thread take-up spring is excessive. 2-C) Stroke of the thread take-up spring is excessive. 2-D) The thread take-up spring tension is insufficient. 2-E) Level difference between the counter knife is excessively high. 2-F) Needle thread tension is high and the thread is excessively high. 2-F) Needle thread spreading section of the moving knife has scratches. 3-A) Level difference between the needle hole guide and the counter knife is excessively high. 3-A) Level difference between the needle hole guide and the counter knife is excessively high. 3-B) Lower face of the needle hole guide has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section is excessively high. 3-B) Lower face of the needle hole scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches.			1-B) Penetration registance of the thread against the cloth is small.	Use a thinner needle. (Lower the needle count to be used.)
2-C) Stroke of the AT thread tension disc is insufficient. 2-C) Stroke of the thread take-up spring sexcessive. 2-D) The thread take-up spring tension is insufficient. 2-E) Level difference between the needle hole guide and the counter knife is excessively high. 2-F) Needle thread tension is high and the thread is excessively stretched. 2-G) Thread spreading section of the needle hole guide and the counter knife is excessively high. 3-B) Lower face of the needle hole guide and the needle hole guide has scratches. 3-B) Lower face of the needle hole guide has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-D) Shuttle upper spring has scratches. 3-C) Thread spreading section is excessively high. 3-C) Thread spreading section of the moving knife has scratches. 3-D) Shuttle upper spring has scratches.		1-2) Length of thread remaining at the needle is not sufficient.	2-A) Tension controller No. 1 provides an excessive tension.	Properly adjust the tension controller No. 1.
2-C) Stroke of the thread take-up spring is excessive. 2-E) The thread take-up spring tension is insufficient. 2-E) Level difference between the needle hole guide and the counter knife is excessively high. 2-F) Needle thread is excessively high. 2-F) Needle thread tension is high and the thread is excessively stretched. 2-G) Thread spreading section of the needle hole guide has scratches. 3-A) Level difference between the needle hole guide has scratches. 3-A) Level difference between the needle hole guide has scratches. 3-B) Lower face of the needle hole guide has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-D) Shuttle upper spring has scratches. 3-D) Shuttle upper spring has scratches. 3-E) The bobbin thread tension is excessive.				Adjust the amount of AT thread tension floating.
2-E) The thread take-up spring tension is insufficient. 2-E) Level difference between the needle hole guide and the counter knife is excessively high. 2-F) Needle thread tension is high and the thread is excessively stretched. 2-G) Thread spreading section of the moving knife has scratches. 3-A) Level difference between the needle hole guide and the counter knife is excessively high. 3-B) Lower face of the needle hole guide and the counter knife is excessively high. 3-B) Lower face of the needle hole guide and the counter knife is excessively high. 3-B) Lower face of the needle hole guide and the counter knife is excessively high. 3-B) Lower face of the needle hole guide and the counter knife is excessively high. 3-B) Thread spreading section of the moving knife has scratches. 3-D) Shuttle upper spring has scratches. 3-D) Shuttle upper spring has scratches. 3-D) Shuttle upper spring has scratches. 3-D) The bobbin case has scratches.			2-C) Stroke of the thread take-up spring is excessive.	Adjust the stroke of the thread take-up spring.
2-E) Level difference between the needle hole guide and the needle hole guide and the needle hole guide and the scoessively high. 2-F) Needle thread tension is high and the thread is excessively high. 2-G) Thread spreading section of the moving knife has scratches. 3-A) Level difference between the needle hole guide has scratches. 3-B) Lower face of the needle hole guide has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-F) The bobbin thread tension is excessive.			2-D) The thread take-up spring tension is insufficient.	Adjust the thread take-up spring tension.
ength of bobbin thread re- ainling is not sufficient. 3-6) Thread spreading section of the moving knife has scratches. 3-6) Level difference between the needle hole guide and the counter knife is excessively high. 3-7) Thread spreading section of the moving knife has scratches. 3-7) Thread spreading section of the moving knife has scratches. 3-7) Thread spreading section of the moving knife has scratches. 3-7) Thread spreading section of the moving knife has scratches. 3-7) Thread spreading section of the moving knife has scratches. 3-7) The bobbin thread tension is excessive.			2-E) Level difference between the needle hole guide and the counter knife is excessively high.	Adjust the height of the counter knife.
ength of bobbin thread reading is not sufficient. 3-A) Level difference between the needle hole guide and the counter knife is excessively high. 3-B) Lower face of the needle hole guide has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Thread spreading section of the scratches. 3-D) Shuttle upper spring has scratches. 3-D) The bobbin thread tension is excessive.			2-F) Needle thread tension is high and the thread is excessively stretched.	Adjust the needle thread tension.
anity of bobbin thread re- laining is not sufficient. 3-A) Level difference between the counter knife is excessively high. 3-B) Lower face of the needle hole guide has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-C) Shuttle upper spring has scratches. 3-D) Shuttle upper spring has scratches. 3-E) The bobbin thread tension is excessive.			2-G) Thread spreading section of the moving knife has scratches.	Polish the thread spreading section of the moving knife with buff or replace the knife.
3-B) Lower face of the needle hole guide has scratches. 3-C) Thread spreading section of the moving knife has scratches. 3-D) Shuttle upper spring has scratches. 3-E) The bobbin thread tension is excessive.		1-3) Length of bobbin thread remaining is not sufficient.	3-A) Level difference between the needle hole guide and the counter knife is excessively high.	Adjust the height of the counter knife. (Otherwise, widen the gap.)
3-C) Thread spreading section of the moving knife has scratches. 3-D) Shuttle upper spring has scratches. 3-E) The bobbin thread tension is excessive. 3-F) The bobbin or bobbin case has scratches.			3-B) Lower face of the needle hole guide has scratches.	Polish the needle hole guide with a buff or replace it.
3-D) Shuttle upper spring has scratches. 3-E) The bobbin thread tension is excessive. 3-F) The bobbin or bobbin case has scratches.			3-C) Thread spreading section of the moving knife has scratches.	Polish the thread spreading section of the moving knife with buff or replace the knife.
3-E) The bobbin thread tension is excessive. 3-F) The bobbin or bobbin case has scratches.			3-D) Shuttle upper spring has scratches.	Polish the shuttle upper race with a buff or replace it.
3-F) The bobbin case has scratches.			3-E) The bobbin thread tension is excessive.	Adjust the bobbin thread tension.
	To the	▼ next page	3-F) The bobbin or bobbin case has scratches.	Polish it with a buff or replace it.

Check and corrective measures		Remove the slack of the material to be sewn.	Increase the needle thread clamp needle number to 3~4 stitches.	Lower the speed of the first stitch. (600 ~ 1000rpm)	Lower the needle thread tension of the first stitch.	Increase the pitch of the first stitch.	Refer to the item "Threading the needle bar thread Guide".	Use a stronger idling prevention spring.	Adjust the initial position of the moving knife.	Adjust the clearance between needle and shuttle driver.	Adjust the clearance between the needle and the	Change the feed timing by the use of the memory switch.	Adjust the moving knife position.	Adjust the wiper position.	Adjust the tension to a proper level.	Change the needle No. to the suitable one to the material.	Adjust the work clamp foot (feed bracket) position.
Cause (2)			5-A) Thread tends to be extended or sliding efficiency is worse.		5-B) Pitch of the first stitch is too small.				7-A) Initial positioning of the moving knife is inadequate.	attention to the control of the cont		3-A) Too late feed timing for cloth			6-A) The needle thread tension is too high.		
Cause (1)	From the previous page	1-4) Material to be sewn is not properly stretched.	1-5) Unstable needle thread clamp				1-6) Threading the needle bar thread guide is wrong.	1-7) Bobbin runs idle and the bobbin thread is drawn out		2-1) Inadequate clearance between the shuttle driver and the needle	2-2) Inadequate clearance between	2-3) Feed timing is defective	2-4) Needle coming in contact with the moving knife	2-5) Needle coming in contact with the wiper	2-6) Needle is bent	2-7) Needle is too thin.	2-8) Interference between work clamp foot and needle
Trouble	From the									2. Needle breakage							

Check and corrective measures	Adjust the clearance between needle and inner hook.	Adjust timing for the needle and the inner hook.	Adjust the clearance between needle and shuttle driver.	tween Adjust the work clamp foot height.	Remove the slackness of the sewing object.	Replace the needle.	Attach the needle with the long groove orienting slightly to the right. (Approximately 20°)	t. Change the feed timing by the use of the memory switch.	After polishing the blade point of the inner hook with oilstone, polish it with polishing powder. Properly adjust the clearance between the needle and the inner hook.	After polishing the blade point of the inner hook, polish it with polishing powder.	After polishing the blade point of the inner hook, polish it with polishing powder.	After polishing the blade point of the inner hook, polish it with polishing powder.	pper Properly adjust the position of the shuttle upper spring.	of the Replace the inner hook.	wrong. Properly adjust the position od the shuttle. too low.	
Cause (2)				4-A) Too much clearance between	sewing object			6-A) Feed timing is too fast.	1-A) Scratches on section (3) (Contact of the inner hook with the needle)	1-B) Scratches on section (a) (Scratches occur when the needle is bent or broken.)	1-C) Scratches on section (**) (Needle scratches the inner hook when removing the inner hook.)	1-D) Scratches on section	2-A) Position of the shuttle upper spring is wrong.	2-B) Blade point section (3) of the shuttle is round.	2-C) Position of the shuttle is wrong. 2-D) Needle thread tension is too low.	To the next page
Cause (1)	3-1) Too much clearance between the needle and the inner hook.	3-2) Inadequate timing adjustment for the needle and the inner hook.	3-3) Inadequate clearance between the shuttle driver and the needle	3-4) Material to be sewn is not	proporty street ear.	3-5) Needle is bent or blunt.	3-6) Loop of the needle thread falls down.		4-1) Stratches on the inner hook				4-2) Thread enters into the shuttle.	:		To the next page
Trouble	3. Stitch Skipping								4. Needle thread breakage							- OI

Check and corrective measures		Adjust the thread take-up spring. Properly adjust the tension controller No. 1.		Remove the scratches and polish with buff, or replace the shuttle driver.	Properly adjust the clearance between the shuttle driver and the inner hook.	Remove the scratches and polish with buff, or replace the needle hole guide.	Replace the needle.	Properly adjust the thread take-up spring.	Properly adjust the thread take-up spring.	Remove the inner hook and remove the thread waste.	Supply oil to the shuttle components.	Adjust the needle thread length and turn the needle thread clamp device ON.	Use of silicone oil Use of needle coated with fluoro carbon resin
Cause (2)	From the previous page	2-E) Thread take-up spring tension is too low. 2-F) Length of the remaining needle thread is too long.	2-G) The specified inner hook and shuttle driver are not used.					7-A) Stroke of the thread take-up spring is too large.	7-B) Thread take-up spring tension is too high.	8-A) Race face of the shuttle is clogged with thread waste.	8-B) Oil amount is insufficient.	9-A) Needle thread length is inadequate.	
Cause (1)	From the previous page From the r			4-3) Soratches on the shuttle driver.	4-4) Clearance between the shuttle driver and the inner hook is too small.	4-5) Scratches on the needle hole guide.	4-6) Finish of the needle hole is rough.	4-7) Thread take-up spring is maladjusted.		4-8) Rotation of the inner hook is defective.		4-9) Needle thread clamp device OFF	4-10) Chemical fiber thread is melted with heat from the needle.
Trouble	From the pr											,	-

Check and corrective measures	Adjust the amount of AT thread tension floating.	Paying attention to the blade section, polish with polishing powder.	Remove the scratches.	Properly adjust the position of counter knife.	Properly adjust the position of counter knife.	Remove the scratches and polish with buff, or replace the needle hole guide.	Adjust initial positions of the presser origin sensor, thread trimmer, and the moving knife.	Adjust the thread take-up spring.	Eliminate the scratch.
Cause (2)	1-A) Floating of the AT thread tension disk is insufficient.			4-A) Thread is cut before trimming with the blade section of the moving knife.	5-A) Thread is cut before trimming with the blade section of the moving knife.	6-A) Thread is cut with the needle hole guide.			
Cause (1)	5-1) Thread release timing is defective.	5-2) Thread spreading section of the moving knife has scratches.	5-3) Shuttle upper spring has scratches.	5-4) Level difference between the needle hole guide and the counter knife is too high.	5-5) Clearance between the needle hole guide and the counter knife is too small.	5-6) Lower face of the needle hole guide has scratches.	5-7) Thread spreading timing of the moving knife is defective.	5-8) Thread take-up spring tension is too low.	5-9) Scratched bobbin thread holder
Trouble	5. Thread breakage at the time of thread trimming.								

Check and corrective measures	Replace the moving and counter knives.	Properly adjust the heigh and position of the moving and counter knives.	Properly adjust the parallel of the blade section of counter knife.	Property adjust the attaching position of counter knife.	Paying attention to the blade section, polish with polishing power, or replace the moving knife.		Remove the scratches.	Adjust the initial position of the moving knife.	Adjust the thread trimmer cam position.	Adjust the position of shuttle upper spring.	Adjust the timing and the clearance.	Let the biginning of stitch come closer to the presser by moving the pattern.	Attach the needle with the long groove orienting slightly to the right (approximately 20°)	Streng then the bobbin thread tension.	Replace the needle hole guide with a new one having a smaller hole diameter.
Cause (2)	1-A) Abrasion of moving and counter knives.	1-B) Engagement of the moving and counter knives is defective.	1-C) Parallel of the blade section of counter knife is defective.	1-D) Attaching position of the counter knife is defective.	2-A) There is a burr on thread spreading section (2) of the moving knife. The shape of the thread trimmed becomes and	thread waste remains.	2-B) Shuttle upper spring has scratches. (The shape of the thread trimmed becomes —, and thread waste remains.)	3-A) Initial position of the moving knife is maladjusted.	3-B) Thread trimmer cam position is inadequate.	3-C) Position of the shuttle upper spring is defective.	4-A) Timing of the needle to the inner hook and the clearance between them are defective.	4-B) Work clamp foot big.	4-C)Loop of the needle thread falls down.	5-A) Bobbin thread tension is low.	5-B) Needle hole size of the needle hole guide is large.
Cause (1)	6-1) Sharpness of the knife is difective				6-2) Double cutting for the needle thread. (Thread waste remains inside the cylinder arm cap.)		÷	6-3) Moving knife does not spread threads.			6-4) Stitch skipping at the final stitch			6-5) Bobbin thread cannot be cut.	
Error	6. Defective thread trimming														

Trouble	Cause (1)	Cause (2)	Check and corrective measures
7. Poorly tense stitches	7-1) Tension controller AT is maladjusted.	1-A) Tension of the tension controller AT is low.	Properly adjust the tension of tension controller AT.
	7-2) Tension controller AT is floating.		Adjust the thread tension releasing mechanism.
	7-3) Thread take-up spring is maladjusted.		Adjust thread take-up spring tension and stroke.
	7-4) Clearance between the inner hook and the shuttle driver is defective.	4-A) The clearance between the inner hook and the shuttle driver is too small.	Properly adjust the clearance of inner hook and shuttle driver.
	7-5) Selection of the needle to be used is improper.	5-A) Needle to be used is thin.	Replace the needle with a thicker one.
	7-6) Selection of the needle hole guide is improper.	6-A) Hole diameter of the needle hole guide to the needle to be used and thread is small.	Replace the needle hole guide with a new one having a larger needle hole.
	7-7) Shape of the feed plate is defective.	7-A) Material to be sewn is stiff and closely contacted with the throat plate, and there is no clearance between them to pass the thread.	Raise the material to be sewn by means of the feed plate.
		7-B) Material to be sewn is highly elastic and closely contacted with the throat plate, and there is no clearance between them to pass the thread.	Raise the material to be sewn by means of the feed plate.
ana.ad	7-8) Feed timing is defective	8-A) Feed timing is too fast.	Use the memory switch to change the feed timing.

	Trouble	Cause (1)	Cause (2)	Check and corrective measures
	8. Defective stitches with the synthetic thread	8-1) Thread breakage due to heat	1-A) The sewing speed is too fast.	Slow down the maximum speed.
			1-B) The needle used is too thick.	Use a thin needle or a super needle for the synthetic thread.
		TAYON WE WANTED THE TOTAL PROPERTY.	A Company of the Comp	Use silicon.
			_	Use a needle cooler.
		8-2) Thread makes burrs.	2-A) Thread path is defective.	Polish the thread path of each component with polishing powder.
			2-B) Finish of the needle hole is defective.	Replace the needle.
			2-C) Loop of the needle thread falls down.	Move the machine arm thread guide A to the left.
		8-3) Thread floating occurs at the	3-A) Penetration registance of the	Use a thinner needle. (Lower the number of needle to be used.)
			smeau against the cities too	Needle thread clamp device ON.
		8-4) Stitch skipping due to the heat.	4-A) Sewing speed is too fast.	Change the maximum speed (electrical components.)
			4-B) Needle is too thin.	Use a thicker needle. (Raise the number of needle to be used.)
212 –			4-C) Loop of the needle thread falls down.	Attach the needle with the long groove orienting slightly to the right (approximately 20°).
	_	8-5) Uneven stitch tightness due	5-A) Sewing speed is too fast.	Reduce the speed by means of the speed variable resistor.
			5-B) Tension of the tension controller AT is excessive.	Decrease the tension of tension controller AT.
	9. Thread chips generated in the shuttle	9-1) Long needle thread at the beginning of stitches	1-A) The thread trimmer is used for cutting.	Needle thread clamp device OFF
				Adjust the needle thread length to 32 ~ 36mm Increase the sewing length to more than 10mm.

1. No display at the operation panel. 1. No display at the operation panel. 1. Supply, (si availal of the SDC supply, (si	1-B) B)	Check and corrective measures
1-1) DC power (+5 V, +24V) is not supplied.		
1-G) The FLT supply. 1-C) The SDC supply. (is availal of the S supply. (is available. (is availab	1-B) The FLT board has no power supply.	Examine if a power supply is available at the power switch.
1-C) The SDO supply. (is availal of the S of the S of the S supply.) 1-D) The MAIP supply.		Check whether an AC voltage is available between Pins 4-5 of CN1 in the FLT board. If no voltage is found, check the connections around the power switch or the power plug.
savailal of the S of the S of the S supply. 1-D) The Malf supply. 1-E) The ope power si	1-C) The SDC board has no power	Check the connection of CN1 of SDC board.
1-D) The MAII supply.	supply. (The power supply is is available so long as LED4 of the SDC board is lit.)	Check the connection between CN17 of the SDC board and CN2 of the FLT board.
1-D) The MAll supply.		Confirm that the inrush protection resistor is normal in the FLT board. FLT-T board R2, R3 FLT-S board R1
1-E) The oper supposed suppose	1-D) The MAIN board has no power supply.	Check the CN31 power supply of the MAIN board.
1-E) The open power states and the states of		3: +24V 4: +5V 5: +33V
1-E) The open supposed the power supposed the supposed th		6, 7, 8: GND Check the output voltage in the SDC board unit.
1-E) The open supposed to the power supposed		System for the MAIN board.
	1-E) The operation panel has no power supply.	Check if there is shortcircuiting in the +5V power system for the operation panel.
		Check the connection between CN34 of the MAIN board and the panel.
omentary 2-A) s SDC board 2-A)	2-A) No momentary interruption sensor signal input is entered in the SDC board.	Check the connection between CN3 of the FLT board and CN13 of the SDC board.
Plashing 9 times 2-B) No AC v between the FLT FLT bc	2-B) No AC voltage is available between Pins 4-5 of CN1 in the FLT board. (In case of FLT-T board)	When a sewing machine for 3-phase specifications is used in a 1-phase system, connect the power supply to black and white of the power cord led from the box.

2-2) CP-20: The Panel CPU does 2-2) CP-20: The Panel CPU does 3-1) The main shaft motor of the sewing machine cannot rotate. 3-1) The switch signal is not received. 4-1) The switch signal is not received. 5-1) It cannot stop in upper position. 1-A) The servo lock is not effective. 1-B) The servo lock is not effective. 1-C) The driver circuit is out of order. 1-D) The motor is out of order. 1-D) The motor is out of order. 1-D) The motor is out of order. 1-D) The air sensor switch is not is not pressure variation or drop 6-1) The air sensor switch is not in the servo lock is not effective. 1-B) Switch defective.	Trouble	Cause (1)	Cause (2)	Check and corrective measures
2-2/OP-20. The Panel OPU does 2-2/OP-20. The Panel OPU does 3-1) The main shaft motor of the sewing machine cannot rotate. 1-6) The driver circuit is out of order. 3-1) The switch signal is not received. 1-6) The motor is out of order. 1-7) The motor is out of order. 1-8) The mechanism is locked. 1-9) The motor is out of order. 1-9) The motor is out of order. 1-1) The switch signal is not received. 3-1) It cannot stop in upper position. 1-4) The servo lock is not effective. 1-1) The air sensor switch is not in the servo lock is not effective. 1-1) The air sensor switch is not in the servo lock is not effective. 1-8) Switch defective.	2. Key malfunction on the operation panel It does not function so effectively.	2-1) IP-400: There is no signal from the touch panel.	1-A) Connector connection defective	Check the connection between the touch panel and CN109 of the Panel board.
2-2) CP-20. The Panel CPU does accept the key. 3-1) The main shaft motor of the sewing machine cannot rotate. 3-1) The main shaft motor of the sewing machine cannot rotate. 1-6) The driver circuit is out of order. 1-7) The switch signal is not received. 1-7) The switch signal is not received. 1-7) The servo lock is not effective. 1-7) The servo lock is not effective. 1-8) Switch defective			1-B) The switch position of the touch panel is displaced.	Start the Check Program 1_01 and readjust the switch position.
2-2) CP-20: The Panel CPU does Choosed: Flashing 1 times 3-1) The main shaft motor of the sewing machine cannot rotate. 3-1) The main shaft motor of the sewing machine cannot rotate. 1-B) The mechanism is locked. 1-B) The mechanism is locked. 1-D) The driver circuit is out of order. 1-D) The motor is out of order. 1-D) The motor is out of order. 1-D) The motor is out of order. 1-D) The anit sensor switch is not pressure variation or drop e drop 6-1) The air sensor switch is not anit is not pressure variation or drop the same of the service of t			1-C) Touch panel fault	Replacement of the LCD assembly (40034529)
Sewing machine carnot rotate. Sewing machine carnot rotate. 1-B) The mechanism is locked. 1-C) The driver circuit is out of order. 1-D) The motor is out of order. 1-D) The driver diruit is out of order. 1-D) The motor is out of order.			2-A) The circuit is out of order.	Replace the PANEL board (40031471).
In solution a solution or dependent of the mechanism is locked. 1-C) The driver circuit is out of order. 1-D) The motor is out of order. 1-D) The air sensor switch is not pressed. 1-A) The servo lock is not effective. 1-B) Switch defective	3. Error E007 Machine lock LED3 on SDC board: Flashing 1 times	3-1) The main shaft motor of the sewing machine cannot rotate.	1-A) No power is fed to the motor.	Check the connection of CN16 of SDC board.
ila slot open error 4-1) The switch signal is not received. 1-D) The motor is out of order. 1-D) The motor is out of order. 1-A) The slot OPEN-OFF switch is not pressed. 5-1) It cannot stop in upper position. 6-1) The air sensor switch is not in the servo lock is not effective. 6-1) The air sensor switch is not in the servo lock is not effective. 1-A) The servo lock is not effective.			1-B) The mechanism is locked.	Turn it by hand in the state that the power supply is turned OFF. Confirm whether the upper shaft is locked. If there is any abnormality, remove it.
ila slot open error 4-1) The switch signal is not received. 1-A) The motor is out of order. 1-A) The slot OPEN-OFF switch is not pressed. 5-1) it cannot stop in upper position. 1-A) The servo lock is not effective. 6-1) The air sensor switch is not treceived. 1-A) The servo lock is not effective.			1-C) The driver circuit is out of order.	Replace the SDC board.
lia slot open error 4-1) The switch signal is not received. 1-A) The slot OPEN-OFF switch lis not pressed.			1-D) The motor is out of order.	Measure the resistance of the motor winding. If there is any abnormality, replace the motor.
upper position and stop in upper position. 6-1) It cannot stop in upper position. 1-A) The servo lock is not effective. 6-1) The air sensor switch is not turned ON. 1-B) Switch defective	4. Error E029 Smart media slot open error	4-1) The switch signal is not received.	1-A) The slot OPEN-OFF switch is not pressed.	Check the cover to examine whether the switch pin can be pressed. If there is any abnormality, replace the cover.
upper position upper position. 1-A) The servo lock is not effective. 1				Confirm the switch pin whether it is normal. If there is any abnormality, replace the board.
e drop turned ON. 1-A) Air pressure variation or drop turned ON. 1-B) Switch defective	5. Error E030 Needle bar upper position displacement	5-1) It cannot stop in upper position.	1-A) The servo lock is not effective.	Turn it by hand in the state that the power supply is turned OFF. Confirm if there are large variations in the load.
e drop turned ON. 1-A) Air pressure variation or drop turned ON. 1-B) Switch defective				Replace the SDC board.
1-B) Switch defective	3. Error E031 Air pressure drop		1-A) Air pressure variation or drop	Check the air pressure and the air source.
				Check the pressure setup value of the air sensor (0.34MPa)
			1-B) Switch defective	Check the air switch by means of a circuit tester.

Trouble	Cause (1)	Cause (2)	Check and corrective measures
7. Error E050 Temporary eton equitor	7-1) The switch contact point is	1-A) Connector connection defective	Check CN69 of INT board.
Terriporary stop switch	obes:	1-B) Switch defective or disconnection	Confirm the condition of the switch by using the tester (Normal closure)
8. Error E220 Grease up alarm	8-1) The number of stitches saved in the INT board has exceeded 100 million stitches.	1-A) 100 million stitches have been exceeded.	After grease supplement, clear the memory with the memory switch U245.
9. Error E221 Grease up error	9-1) The number of stitches saved in the INT board has exceeded 120 million stitches.	1-A) 120 million stitches have been exceeded.	After grease supplement, clear the memory with the memory switch U245.
10. Error E302 Head tilt error	10-1)Detector switch contact open	1-A) Connector contact is defective.	Check CN67 of INT board.
		1-B) Disconnection	Check it by means of a circuit tester. Replace the switch.
		1-C) Switch is defective.	Check it by means of a circuit tester. Replace the switch.
		1-D) Switch fails to properly work.	Check the switch mounting conditions.
11. Error E303 Upper shaft motor Phase Z sensor error LED3 on SDC board: Flashing 2 times	11-1)Phase Z signal (upper shaft motor) is not received.	1-A) The encoder cord is broken or the motor encoder circuit is out of order.	Confirm whether each signal is delivered to CN14 of the SDC board. CN14_9: Phase Z CN14_2: GND Replace the motor if there is no signal change as a result of manual turning.
		1-B) The detector circuit is out of order.	Replace the SDC board.
12. Error E305 Thread trimmer knife position	12-1)Presser lifter/thread trimmer pulse motor fails to properly	1-A) The cam phase of the mechanical block is not in good order.	Check the operation with the check program I_07.
	WOR.	1-B) The driver circuit is out of order.	Replace the MAIN board.
		1-C) Motor defective	Measure the resistance of the motor winding by means of a circuit tester.
	12-2)The sensor is not turned ON.	2-A) Sensor defective/Mounting inadequate	Check the sensor with the check program I_03.
		2-B) Disconnection of connector	Check CN66 of INT board.

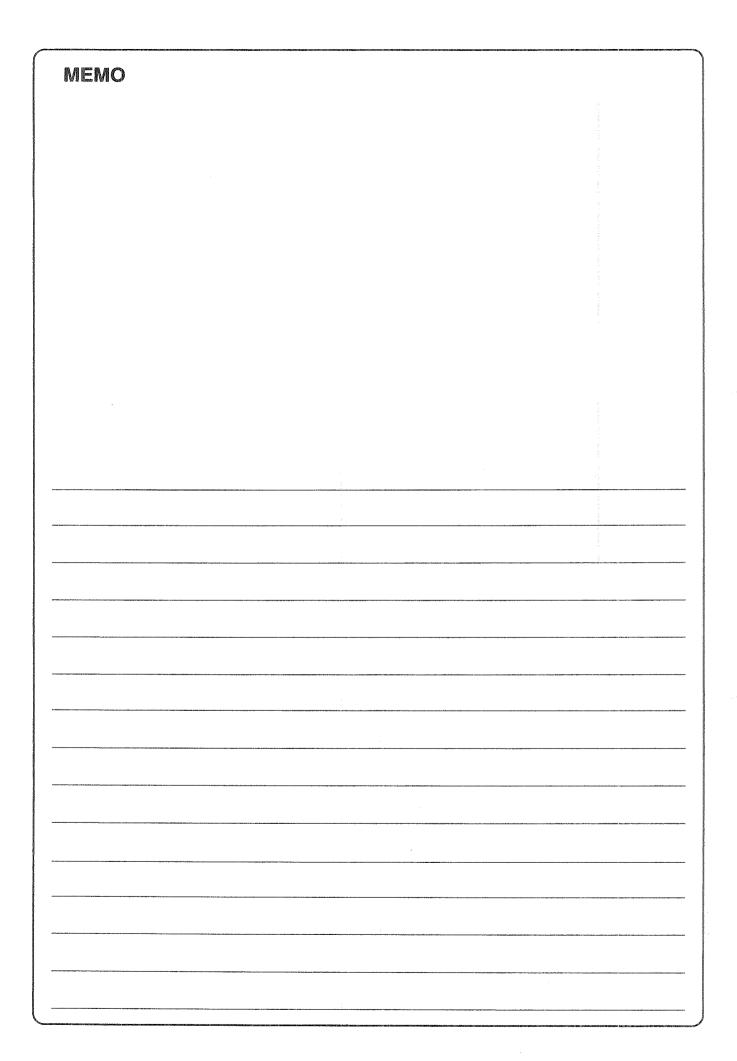
			Check and corrective measures
13.Error E306 Needle thread clamp position error	13-1)Needle thread clamp pulse motor fails to properly work.	1-A) There is a certain obstacle in the mechanical block.	Check the mechanical block to see if there is any position with a heavy load or any section caught by something.
		1-B) The driver circuit is out of order.	Replace the MAIN board.
		I-C) MOTOR DEFECTIVE	Measure the resistance of the motor winding by means of a circuit tester.
	13-2) The sensor is not turned ON.	2-A) Sensor defective	Check the sensor with the check program I_03.
		2-B) Disconnection of connector	Check CN66 of INT board.
		2-C) Sensor mounting inadequate	Check the operation with the check program I_08.
14. Error E730 Main shaft motor encoder error A LED3 on SDC board: Flashing 3 times	14-1)Main shaft motor: No signal entry in Phase A and Phase B.	1-A) The motor is out of order.	Confirm whether each signal is delivered to CN14 of the SDC board. CN14_6: Phase A CN14_7: Phase B CN14_2: GND Replace the motor if there is no signal change as a result of manual turning.
		1-B) The signal input circuit is out of order.	Replace the SDC board.
15. Error E731 Main shaft motor encoder error B LED3 on SDC board: Flashing 4 times	15-1)Main shaft motor: No signal entry in Phase U, Phase V, and Phase W.	1-A) The motor is out of order.	Confirm whether each signal is delivered to CN14 of the SDC board. CN14_3: Phase U CN14_4: Phase V CN14_5: Phase W CN14_2: GND Replace the motor if there is no signal change as a result of manual turning.
		1-B) The signal input circuit is out of order.	Replace the SDC board.
16. Error E733 Main shaft motor reverse turn error LED3 on SDC board: Flashing 7 times	16-1)The main shaft motor is reversing.	1-A) Motor revolutions are unstable.	Check whether coupling for connection of main shaft and motor is loose.
17. Error E811 Overvoltage error LED3 on SDC board: Flashing	17-1)Power source voltage is beyond 280 V AC.	1-A) There are variations or unusual rise in the AC input power line.	Check the AC input power line.

	Trouble	Cause (1)	Cause (2)	Check and corrective measures
	18.Error E813 Low voltage error	18-1)The source voltage is 160V AC or below.	1-A) There are variations or unusual drop in the AC input power line.	Check the AC input power line.
	6 times		1-B) A 100V input is entered where the FLT-T board has been set for 200V.	Check the preset voltage for the FLT-T board.
	19.Error E901 IPM Error	19-1)Error output generation from	1-A) IPM control voltage drop	Replace the SDC board.
	LED3 on SDC board: Flashing 5 times		1-B) IPM overcurrent is detected.	Replace the SDC board.
				Replace the main shaft motor.
1	20.Error E903 Pulse motor power source error LED3 on SDC board: Flashing	20-1)No +48V power output of the SDC board available	1-A) Blown-out of the F1 fuse of the SDC board.	Check if there is shortcircuiting in the +48V power system for the MAIN board. Replace the MAIN board.
1			1-B) Blown-out of the F4 fuse of the SDC board.	Replace the SDC board.
-217	21.Error E904 Abnormal solenoid power LED3 on SDC board: Flashing	21-1)No +33V power output of the SDC board available	1-A) Blown-out of the F2 fuse of the SDC board.	Check if there is shortcircuiting in the +33V power system for the MAIN board. Replace the MAIN board.
	Name of the second of the seco		1-B) Blown-out of the F5 fuse of the SDC board.	Replace the SDC board.
L	22.Error E905 Thermal error in SDC board LED3 on SDC board: Flashing	22-1)Heat sink temperature for power supply has exceeded 85°C.	1-A) Cooling is not effective.	Check for any clogging at the suction port or examine the conditions in the fan, etc.
	601111	22-2)Temperature of main shaft IPM has exceeded 90°C.	2-A) Cooling is not effective.	Check for any clogging at the suction port or examine the conditions in the fan, etc.
			2-B) Sensor connection defective	Check CN18 of SDC board.
			2-C) The main shaft motor is out of order.	Measure the resistance of the upper shaft motor winding. Replace the motor.

Cause (1) Cause (2) Check and corrective measures	23-1)Irregular motor rotations 1-A) There are irregularities in the mechanism and look for the section that mechanism, such as overloading, etc.	1-B) Motor leads are broken. Check the resistance of the motor winding. Replace the motor, as required.	1-C) The driver circuit is out of order. Heplace the MAIN board.	23-2)No sensor signal entry 2-A) The sensor is out of order or broken.	2-B) Connector connection defective Check CN62 of INT board.	2-C) Input circuit is out of order. Replace the MAIN board.	24-1)Irregular motor rotations 1-A) There are irregularities in the mechanism and look for the section that is any holdup or overloading, etc. Check the mechanism and look for the section that is any holdup or overloading, etc.	1-B) Motor leads are broken. Check the resistance of the motor winding. The motor is out of order. Replace the motor, as required.	1-C) The driver circuit is out of order. Replace the MAIN board.	24-2)No sensor signal entry 2-A) The sensor is out of order or broken.	2-B) Connector connection defective Check CN63 of INT board.	2-C)Input circuit is out of order. Replace the MAIN board.	25-1)Irregular motor rotations 1-A) There are irregularities in the mechanism and look for the section that mechanism, such as overloading, etc. Check the mechanism and look for the section that is any holdup or overloading, etc.	1-B) Motor leads are broken. Check the resistance of the motor winding. The motor is out of order.	1-C) The driver circuit is out of order. Replace the MAIN board.	25-2)No sensor signal entry 2-4) The sensor is out of order or broken.	2-B) Connector connection defective Check CN64 of INT board.
	23. Error E907 X feed motor origin retrieval error			23-2)No sensor signa			24. Error E908 Y feed motor origin retrieval error			24-2)No sensor signa			25. Error E910 Presser motor origin retrival error			25-2)No sensor signa	

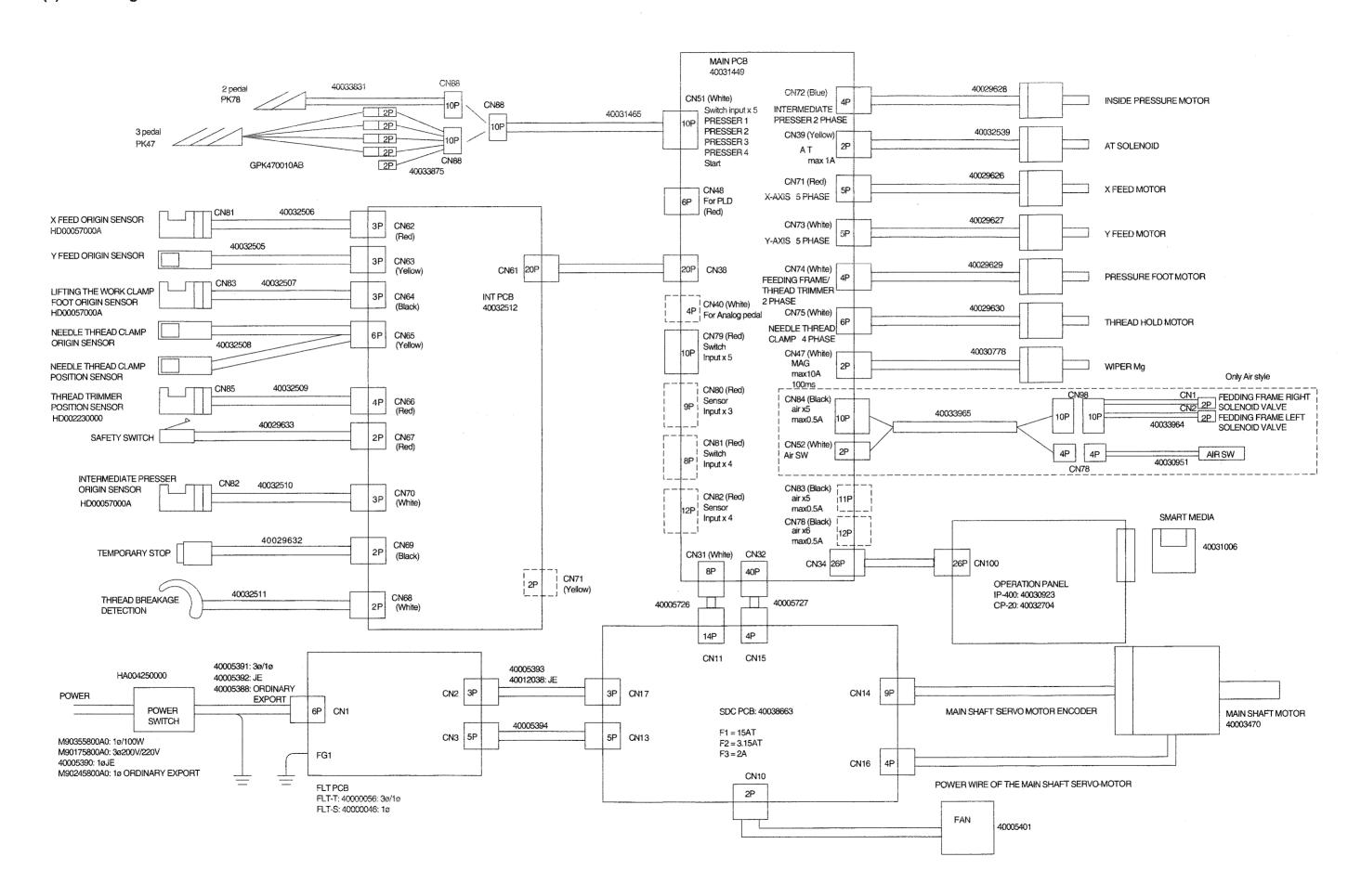
26		Caron	Cause (2)	Check and corrective measures
	26. Error E913 Needle thread clamp origin retrieval error	26-1)Irregular motor rotations	1-A) There are irregularities in the mechanism, such as overloading, etc.	Check the mechanism and look for the section that is particularly overloaded, that is any holdup or whether screws are loose.
			1-B) Motor leads are broken. The motor is out of order.	Check the resistance of the motor winding. Replace the motor, as required.
			1-C) The driver circuit is out of order.	Replace the MAIN board.
		26-2)No sensor signal entry	2-A) The sensor is out of order or broken.	Check the sensor with the test program I_03 or I_08.
			2-B) Connector connection defective	Check CN65 of INT board.
			2-C) Input circuit is out of order.	Replace the MAIN board.
27	27. Error E914 Feed trouble error	27-1)Irregular main shaft motor rotations	1-A) Motor revolutions are unstable.	Check whether coupling for connection of main shaft and motor is loose.
78	28. Error E915 Communication error between	28-1)Data cannot be received from the MAIN board.	1-A) MAIN board fails to work.	All the dip switches of the MAIN board shall be set at OFF.
	on MAIN board: Flashing 1 times		1-B) Board defective	Replace the MAIN board or PANEL board.
29	29. Error E916 Communication error between	29-1)Data cannot be received from the SDC board.	1-A) MAIN board fails to work.	All the dip switches of the MAIN board shall be set at OFF.
	LED3 on SDC board: Flashing 15 times		1-B) SDC board fails to work.	All the dip switches (SW2) of the SDC board shall be be set at OFF.
			1-C)Board defective	Replace the MAIN board or SDC board.
30	30. Error E918 MAIN board overheat	30-1)The heat sink for the power supply has exceeded 85°C.	1-A) Cooling is not effective.	Check for any clogging at the suction port or examine the conditions in the fan, etc.

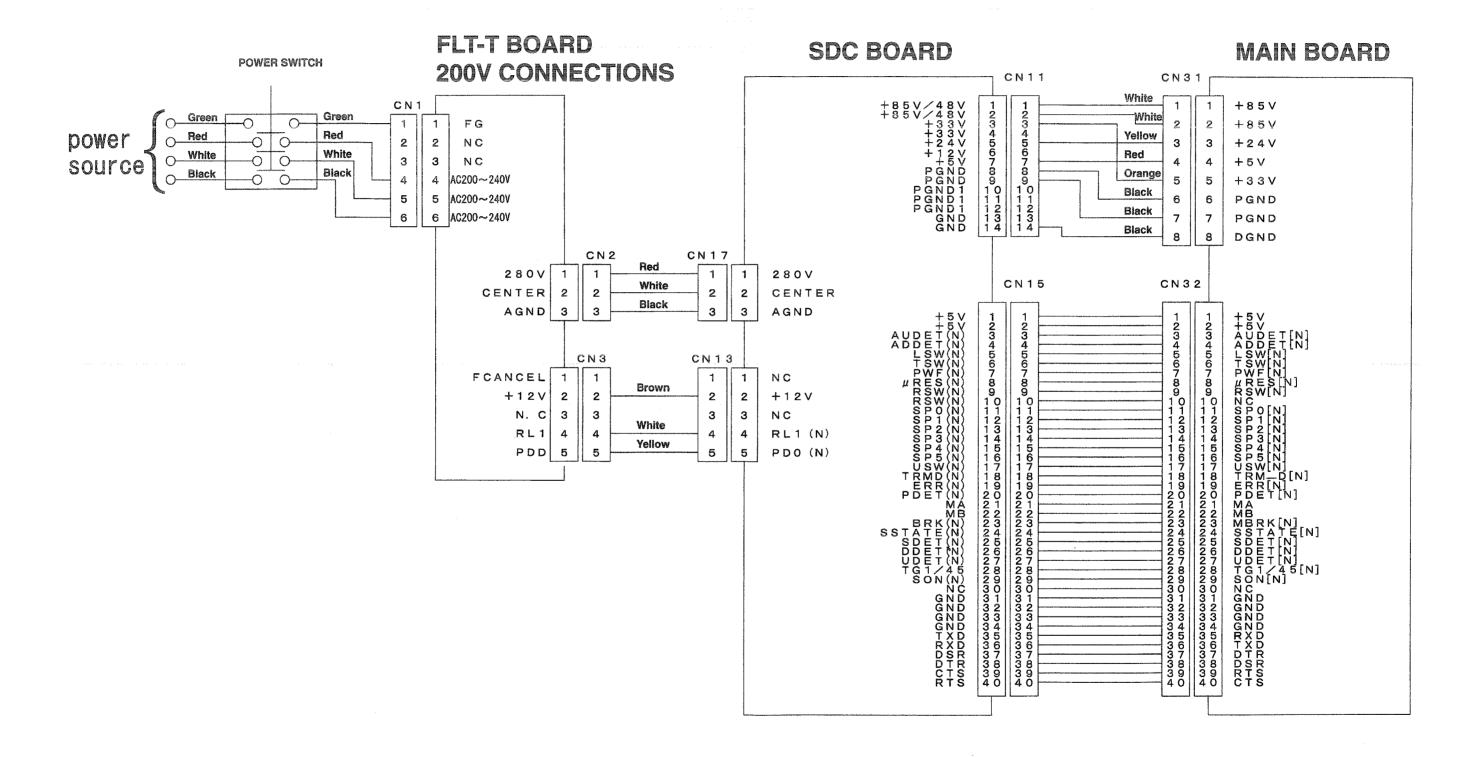
Trouble	Cause (1)	Cause (2)	Check and corrective measures
31. Error E925 Intermediate presser motor origin retrival error	31-1) Irregular motor rotations	1-A) There are irregularities in the mechanism, such as verloading, etc.	Check the mechanism and look for the section that is particularly overloaded, that is any holdup or whether screws are loose.
		1-B) Motor leads are broken. The motor is out of order.	Check the resistance of the motor winding. Replace the motor, as required.
		1-C) The driver circuit is out of order.	Replace the MAIN board.
	31-2) No sensor signal entry	2-A) The sensor is out of order or broken.	Check the sensor with the test program I_03 or I_10.
		2-B) Connector connection defective	Check CN70 of INT board.
		2-C) Input circuit is out of order.	Replace the MAIN board.
32. Error E943 MAIN board EEP-ROM write-in trouble	32-1) MAIN board EEP-ROM failingin writing	1-A) Devices defective, soldering inadequate	Replace the MAIN board.
33. Error E946 INT board EER-ROM write-in	33-1) INT board EEP-ROM failing in writing	1-A) Poor connections	Check the CN38 connections of the MAIN board.
trouble		1-B) Defective board	Replace the MAIN board and the INT board.
34. Error E948 MAIN board F-ROM write-in trouble	34-1) MAIN board F-ROM failing in writing	1-A) Devices defective, soldering inadequate	Replace the MAIN board.

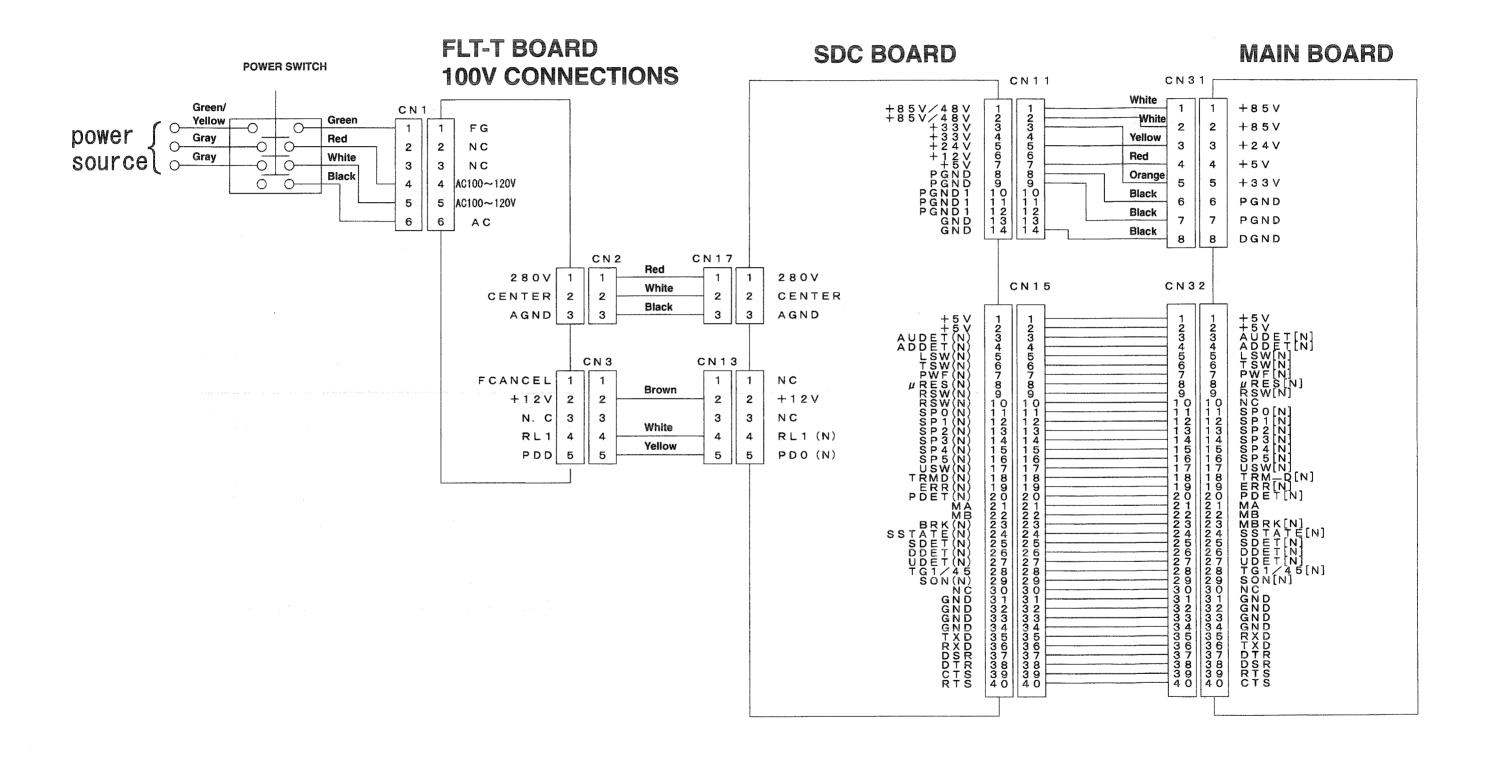


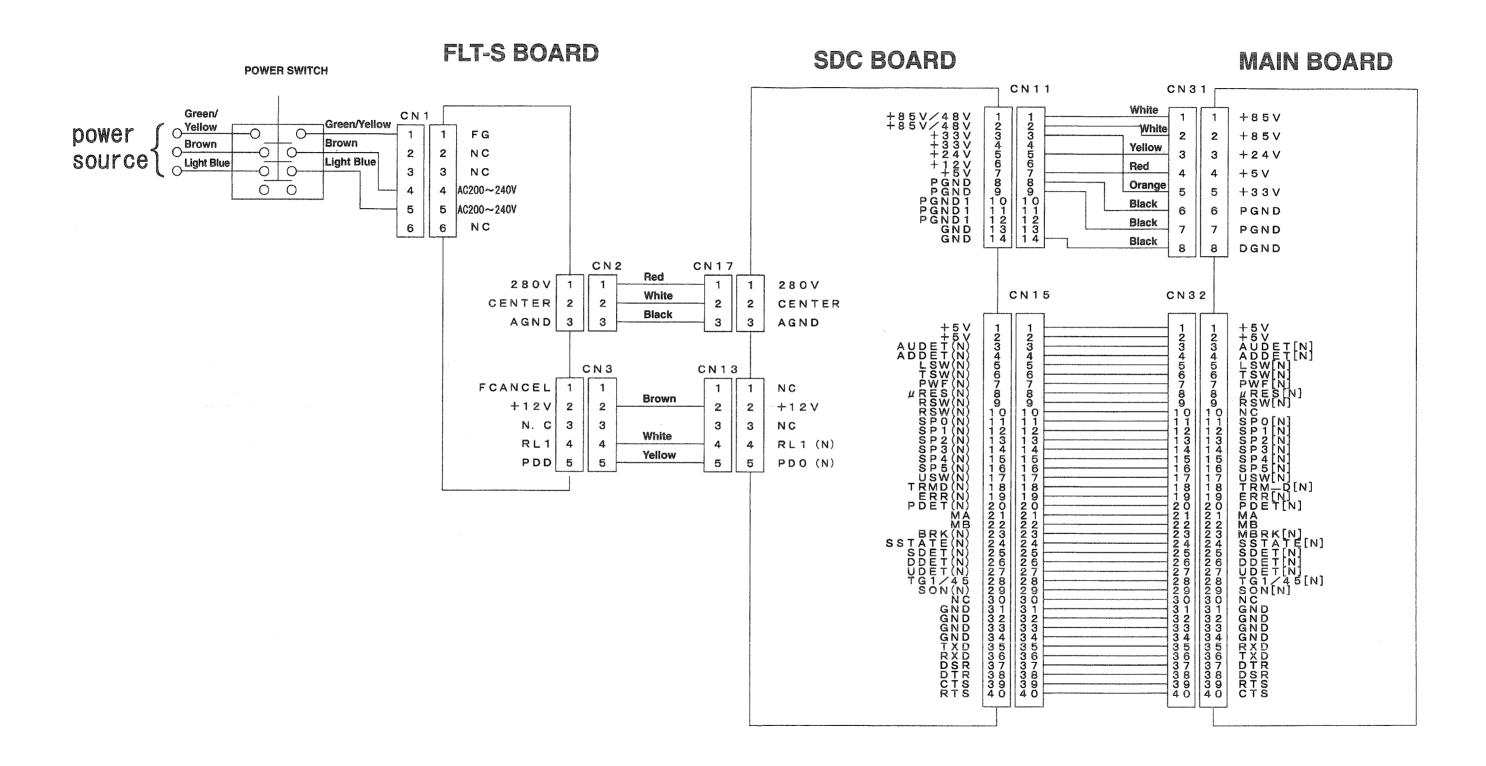
13. Circuit diagrams

(1) Block diagram A



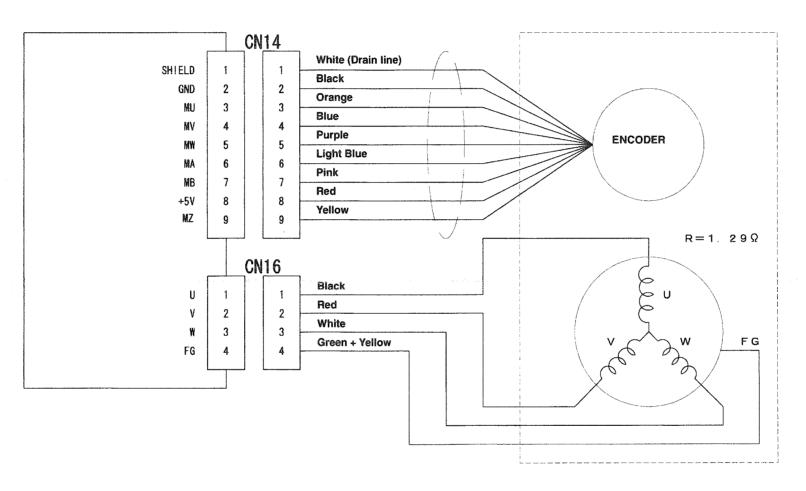


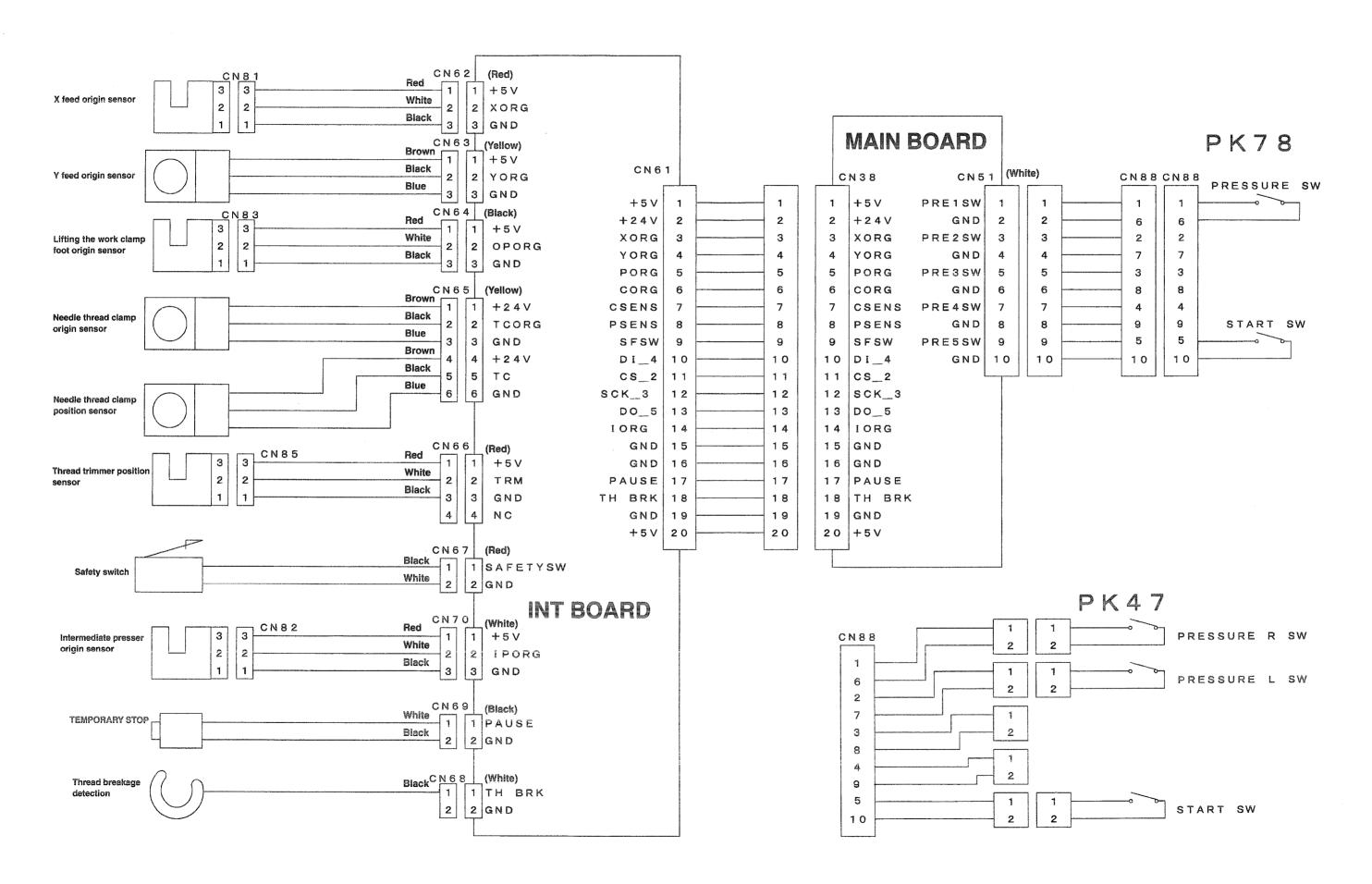




SDC BOARD

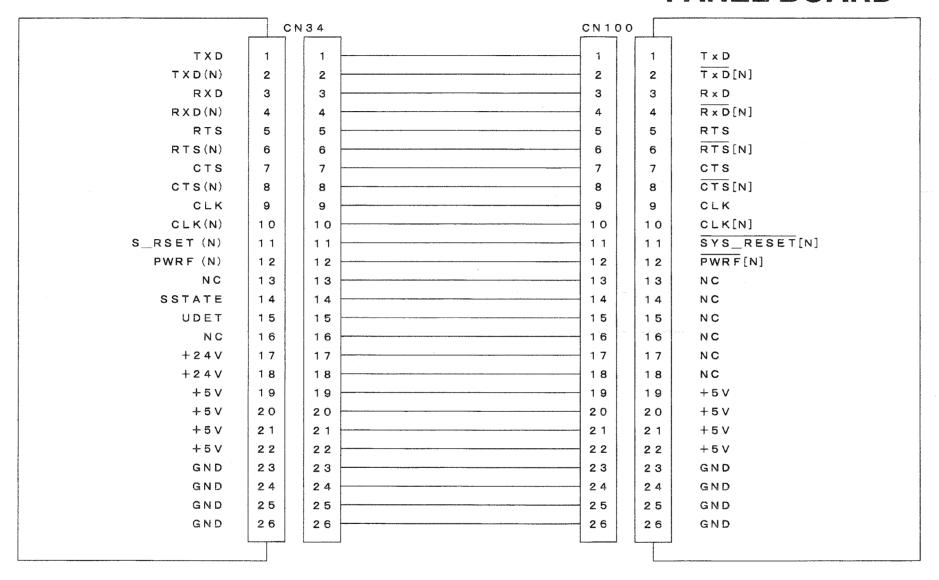
AC SERVO MOTOR

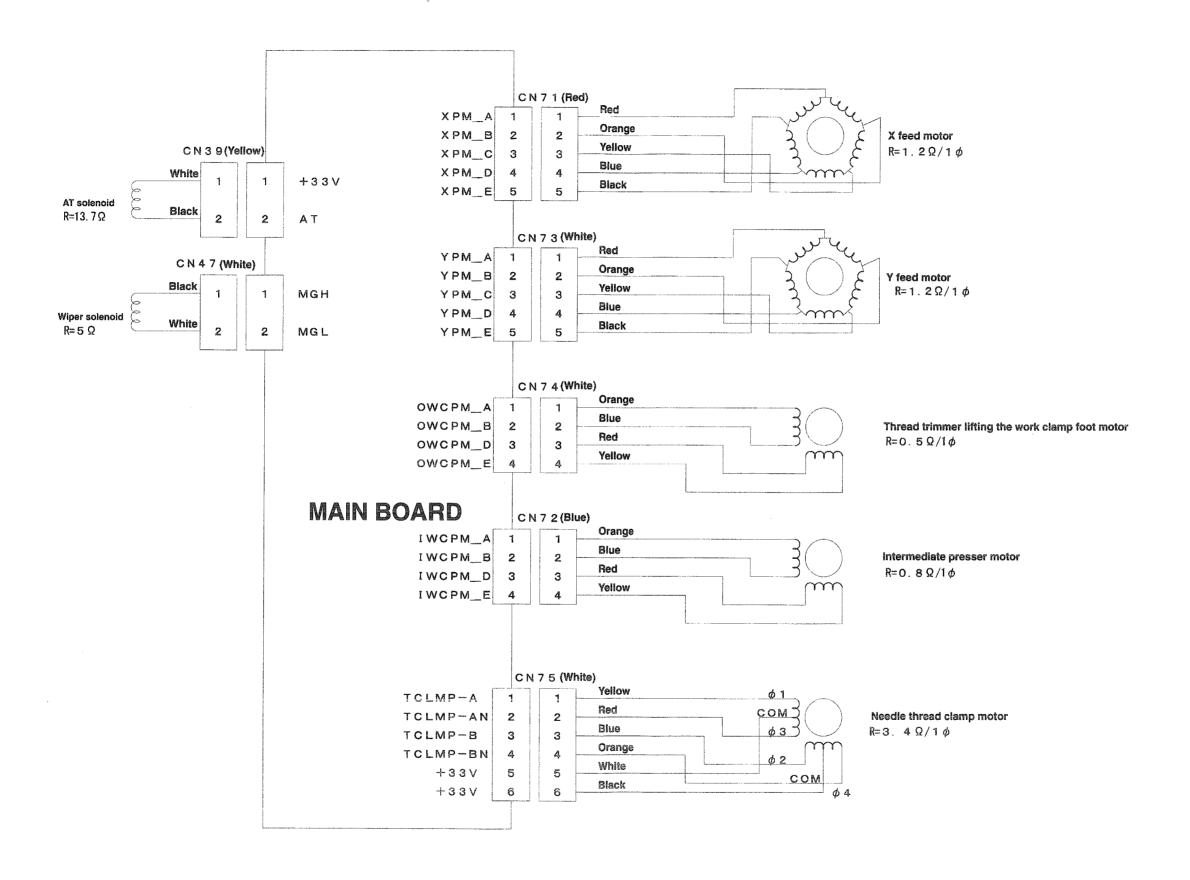




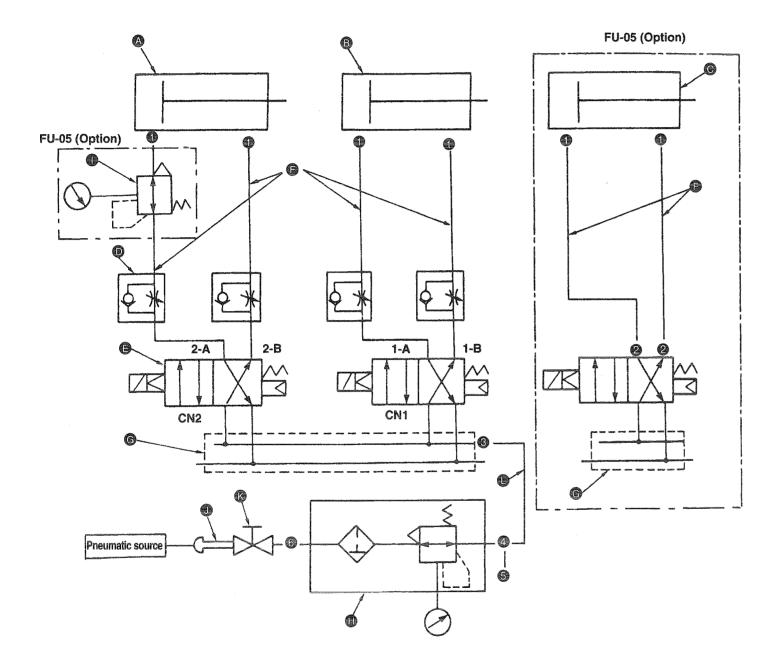
MAIN BOARD

PANEL BOARD





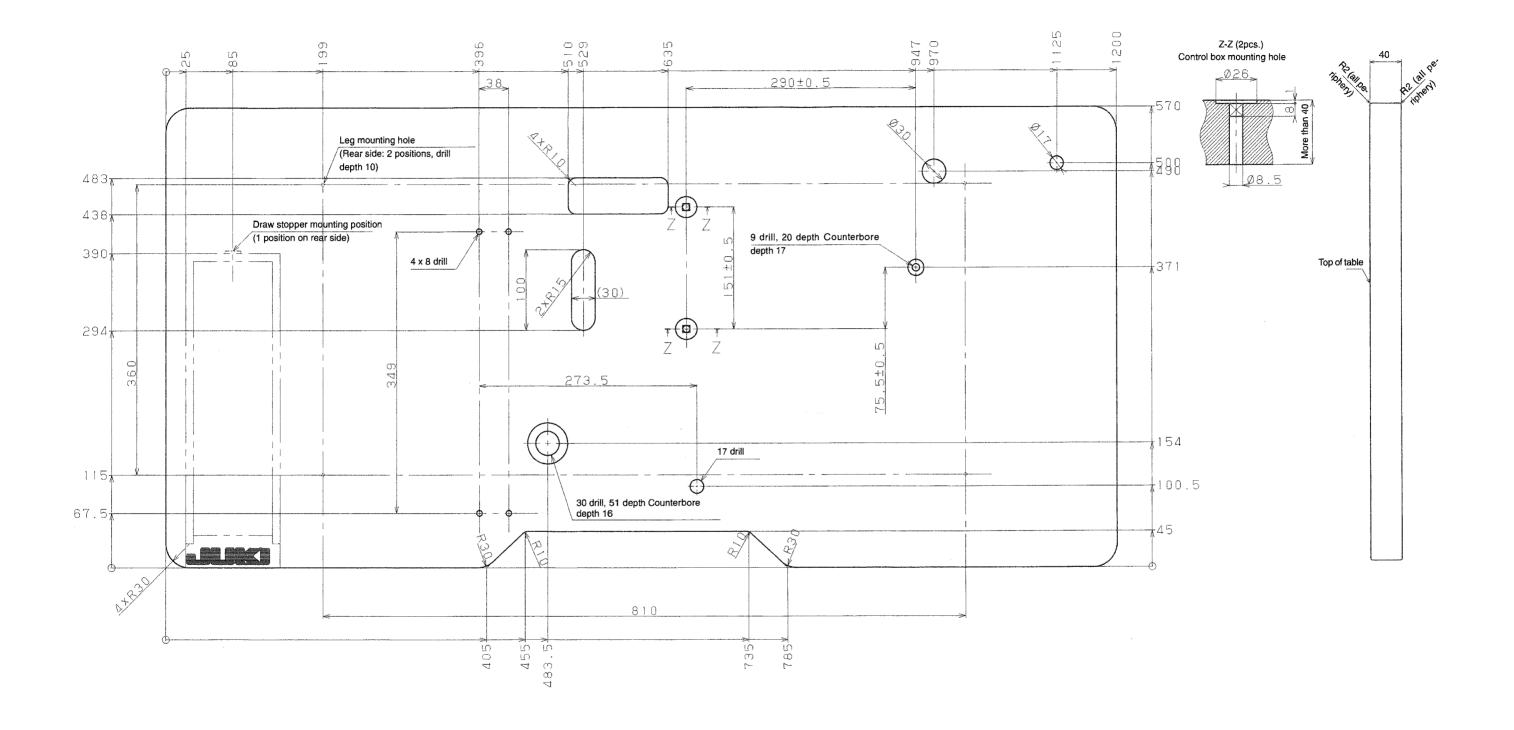
(9) Air system circuit diagram



(A)	Feeding frame cylinder (left)
0	Feeding frame cylinder (right)
0	Inverting cylinder
0	Speed controller
G	Solenoid valve
0	ø 4 Air tube
6	Manifold
0	Filter regulator
0	Regulator
0	One-touch joint plug
	One-touch joint socket
®	Air cock
0	ø 6 Air tube
Town and Concession of the Con	

0	Hose elbow
0	Hose nipple
0	Elbow union
0	T type tee
6	Plug
0	Barrel nipple

14. Drawing of the table









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The environmental management system to promote and conduct ①the technological and technical research, the development and

(i) the technological and technical research, the development and design of the products in which the environmental impact is considered,

(ii) the conservation of the energy and resources, and the recycling, in the research, development, design, distribution, sale and maintenance service of the industrial sewing machines, household sewing machines and industrial-use robots, etc. and in the sale and maintenance service of date entry system and in the purchase, distribution and sale of the household commodities including the healthcase, orgulates. healthcare products

This manual uses environment-friendly soyink.



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The description covered in this engineer's manual is subject to change for improvement of the commodity without notice.

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