

Sewing machine controller

SC-380

ENGINEER'S MANUAL



PREFACE

of the machine. This Engineer's Manual is written for the technical personnel who are responsible for the service and maintenance

factory contains operating instructions in detail. And this manual describes "Standard Adjustment", Adjustment Instruction Manual. Procedures", "Results of Improper Adjustment", and other important information which are not covered in the The Instruction Manual for these machines intended for the maintenance personnel and operators at an apparel

carrying out the maintenance of these machines. It is advisable to use the relevant Instruction Manual and Parts List together with this Engineer's Manual when

is described and on the latter page the "Results of Improper Adjustment" under which stitching errors and troubles arising from mechanical failures and "How To Adjust" are described. This manual gives the "Standard Adjustment" on the former page under which the most basic adjustment value

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. ` DRIVE UNIT SAFETY INSTRUCTIONS

<u>.</u> 5 ensure safe use

380. Always observe the following items to ensure safe use of the industrial sewing machine drive unit SC-

1.1 Before starting

Read all instruction manual thoroughly before starting use of this drive unit, and follow the Engineer's Manual. Also read the instruction manuals for the installed sewing machine.

ю Application and purpose

purposes. Do not use this drive unit until it can be confirmed that safety measures for the installed sewing machine have been taken. This drive unit is designed to drive a sewing machine and must not be used for other applications or

<u>၊</u> မ Work environment

- dry sewing material. Use this drive unit in dry and well-kept clean locations, e.g. in the clothing industry, and which process
- Avoid using this control unit in the following types of environments
- (1) Power voltage
- Place where voltage fluctuation exceeds ± 10 % of the rated voltage
- Place where frequency fluctuation exceeds \pm 1 % of 50/60 Hz
- Place where the specified power capacity cannot be secured
- (2) Electromagnetic noise
- Place where strong electric or magnetic fields are generated such as near a large-output high frequency oscillator or high frequency welding machine
- ω Temperature and humidity
- Place where atmospheric temperature is 40 °C or higher and 5 °C or lower
- Place subject to direct sunlight or outdoors.
- Near a heat source such as a heater.
- (4) Atmosphere Place where relative humidity is 30 % or less and 95 % or more, or where dew condensation occurs
- Atmosphere with dust or corrosive gases
- Atmosphere with combustible gases or explosive atmosphere
- (5) Altitude
- Place where at altitudes exceeds 1,000 m above mean sea level
- (6) Storage
- Place where storage temperature is 55 $^\circ\text{C}$ or higher and –25 °C or lower.
- (7) Vibration
- If excessive vibration occurs when the control box is installed on the sewing machine, install it separately

N Installation

2.1 Motor and control box

Correctly install according to the attached Engineer's Manual

2.2 Accessories

line).) Always disconnect this control unit from the main power supply when installing any accessories listed in the Engineer's Manual. (Turn the main switch OFF, and remove the plug from the outlet (power supply

2.3 Cable

- (1) Arrange the connection cable so that excessive force is not applied during use, and do not excessively bend the cable.
- (2) Cables near moving parts (e.g., pulley or V-belt) must be wired at a minimum distance of 25 mm

(3) Confirm that the power voltage of the power cable for supplying to the control box meets the specifications designated places to supply the power. Perform this step with the power ON/OFF switch turned OFF. on the motor and control box rating nameplates before connecting it to the power line. Connect it to the

2.4 Grounding

(1) Correctly connect the control box grounding to the power supply grounding

2.5 Accompanying appliances and accessories

(1) Electric accompanying appliances and accessories must only be connected to safely low voltage

2.6 Removal

- (1) Turn the main switch OFF and remove the plug from the outlet Åipower supply lineÅjbefore removing the motor or control box.
- (2) Do not pull on the cord when removing the plug. Always hold the plug itself.
- (3) There is a high voltage applied inside the control box, so always wait at least 10 minutes after running the power switch OFF and remove the plug from the outlet Aipower supply line Ajbefore opening the control box panel

3. Maintenance, inspection and repairs

- Follow the Engineer's Manual for maintenance and inspection of the this control unit.
- Repairs and maintenance must be done and approved by specially trained personnel.
- with dust, loose cloth, etc. Do not run this control with the ventilation openings of the motor's dust-proof filter blocked or clogged
- Always turn the power switch OFF and remove the plug from the outlet Åipower supply lineÅjbefore replacing the sewing machine needle or bobbin, etc.
- Always use original replacement parts for repairs or maintenance

4. Other safety measures

- Keep fingers away from all moving parts Åiespecially near sewing machine needle, V-belt, etc. Åj
- Do not drop this control unit or insert any object into any opening.
- Do not operate without required protective devices.
- approvals have been made by qualified personnel. If any damage is observed on this control unit, if the drive does not run properly or if operator is uncertain about operation, do not operate the drive unit. Operate the drive only after adjustments, repairs and
- The user must avoid making modifications or changes based on user's judgment.
- Observe all safety guidelines if modifications or changes must be made

5. Hazard display, warning display

- (1) Risks that may cause personal injury or risk to the machine ate marked with this symbol in the instruction manual.
- (2) This symbol indicates electrical risks and warnings.

Save these Engineer's Manual for future reference.





Do not inspect the control circuit with a tester.



The semiconductor parts may be damaged when the tester's voltage is applied.

Needle

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5. Always ground the machine.





4. Always turn the power switch OFF before tilting the sewing machine head, replacing the needle.
 Sewing machine machine head, replacing the needle.

Do not use branched wiring when using the single-phase motor.











belt will not slip. sewing machine. Refer to page 28 for the pulley diameter to be used when using the Mitsubishi thread trimming











сл ' 1. Insertion of the power connector WIRE AND GROUNDING

box and insert completely. Confirm the connector from and insertion direction when inserting the power connector into the control



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Cord for push-button switch

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Green Black White Red

Ø 6 б Ø

Ground the green (green/yellow) wire to the grounding terminal. Consult with an electrician for the grounding wires.

R-phase S-phase T-phase

(green/yellow)

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| i capacity | |
|----------------------|----------------------------|
| se or complete break | er for the power |
| Power | Recommended power capacity |
| Single phase | |
| 100-120 V 550 W | 15 A |
| 200-240 V 550 W | |
| 3-phase | 40 > |
| | |







phase 200 to 220V class". Refer to "[5] Wire and Grounding 4. When using the 3-phase 200V class SC-380 with Single-

6. CONFIRMATION

1. Before turning switches on.....

| (7) Can the sewing machine be rotated lightly by hand ? | (5) Is the belt tension okay ? | (4) Is the lead wire contacting the V belt ? | (3) Are the connectors inserted correctly ? Power connector from push-button switch Motor connector Motor encoder connector Lever connector Position detection connector Other connectors (options, presser foot lifter control switch panel, etc.) | Place to confirm (1) Is the power and capacity suitable? (2) Is the power voltage the same as the mark on the factory preset voltage nameplate on the side of the control box? (XC-EMFY Control Box) the control box? |
|--|---------------------------------|--|---|--|
| | Mounting of the belt on page 7. | | Installation of control box on page 6. Installation of lever unit on page 9. Installation of position detector on page 9. | Reference Current capacity on page 11. Current capacity on page 11. XC-EJK-20-05 (JE : XC-EJKCE20-05) (200 V type) POWER UNIT L20E OUTPUT 200-220 V S50 W XC-EJK-10-05 (100 V type) POWER UNIT L10E POWER UNIT L10E 0UTPUT 110-120 V 550 W |





3. Adjustment of operation speed Operation speed Slow start speed End tack speed Start tack speed Thread trimming speed T Low speed Maxim speed Adjustment of each speed Z Т S <Refer to program mode [P]. Refer to program mode [P]. [C] key and [D] key on the operation panel. The speed can be adjusted from low to maximum the Refer to program mode [P]. **Rotation speed** \rightarrow \leftarrow Maximum speed Low speed ר' A 1-2 J [C] key ۶ Reference 1 / ° 9 **,** 9 between 0 and 99. It is possible to adjust [D] key 0 99 Adjustment range with the [C]key and [D]key.



(Caution) No matter how large the motor pulley diameter is, the speed will not rise higher than the maximum speed H and the speed set with the [C]key and [D] key.

8. PEDAL OPERATION



(Caution) Refer to the explanation of [A] key " How to use normal mode" page 27 for details on setting the 1 position and 2 position.

9. **OPERATION OF THE OPERATION PANEL KEYS**

1 Displays during normal mode and functions of each key

When the rotation direction isn't displayed on LED.M, press the [When the power supply switch is turned ON, the rotation direction will display on the LED.M shown below.] key anytime

Note) be set. stitches of preset stitching can And the validity and No. stitches can be set. tacking stitch and number of The validity of start and end This state is called the normal mode, and the following keys can be operated.] Up key This above keys can be operated only when the rotary display is shown on the LED.M [] Down key, [w] no.
By operating these two keys direction of the sewing simultaneously, the rotation LED.M. The display is shown machine can be changed. \rightarrow <u>o</u> on ≤ 90 keys LED.M changed with the [The rotation direction can be sewing machine is displayed. The rotation direction of the [A] key selected for the needle position during stopping. 1 position and 2 position can be ۶ 00 1-2 m 00 SL] + [M] ი $\overline{0}$ ۵ 00 function setting is shown. LED.A-D The state of the [A] to [D] keys [B] key start with a slow start. trimming, the sewing will ON and After the power is turned sewing with a slow start. This is used to ร down is set. which the pedal The speed [C] key, [D] key after thread fully start toed at

2) Selection of each mode

and application functions set with this operation panel. The modes can be changed from the normal mode to various program modes and various basic functions

(For each mode function, refer to a table of program mode function.)

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| Model SC-38 | 30 Model name | SC-380 |
|-------------------------------------|------------------|--------|
| Normal mode | Program mode [F] | |
| Tacking setting mode | Program mode [G] | |
| No.of tacking stitches setting mode | Program mode [H] | |
| Preset stitching setting mode | Program mode [J] | |
| Pattern No. selection mode | Program mode [Q] | |
| Program mode [P] | Program mode [R] | |
| Program mode [A] | Program mode [S] | |
| Program mode [B] | Program mode [1] | |
| Program mode [C] | Program mode [2] | |
| Program mode [D] | | |
| Program mode [E] | | |
| | | |

| | | | | | | | displayed on LED.M) | The rotation direction is | √ormal mode | | | | | | | |
|---|---|---|---------------------------------------|---|---|---|---|---|--------------------------------------|---|---------------------------------------|--|---|--|---|------|
| Tacking (condensed stitch) mode, preset stitching setting mode pattern select mode. | Program mode [2] Simple setting mode for chain stitch sewing machine. | Program mode [1] Simple setting mode for Mitsubishi thread trimming sewing machine. | Program mode [S] Simple sequence mode | Program mode [R] Reset/returning to original data. (Return to factory setting) | Program mode [Q] Unusual speed setting mode | Program mode [J] Panel switch cancel mode | Program mode [H] Setting speed limit setting mode | Program mode [G]Thread trimming timing setting mode | Program mode [F] Cutter setting mode | Program mode [E] H/W checking mode/Recorder of running. | Program mode [D] Tacking setting mode | (setting in/output signal to function,etc) | Program mode [C] In/Out definition mode | Program mode [B] The setting to otten use 3 *Counter/Speed display, etc. | Program mode [A] The setting to often use 2 *Servo motor,etc. | etc. |

| Program mode [G] | Program mode [F] | Program mode [E] | Program mode [D] | Program mode [C] | Program mode [B] | Program mode [A] | Program mode [P] | Pattern No. selection mode | Preset stitching setting mode | No. of tacking stitch setting mode | Tacking type setting mode | Mode mane | |
|--|--|---|--|--|--|---|---|--|---|--|---|---------------------------|--|
| While holding down the ↓ key, press the , key and the ↑ key for 2 seconds or more from normal mode. | While holding down the key, press the s₁ key and the ↑ key for 2 seconds or more from normal mode. | While holding down the \downarrow key, press the $[1,2]$ key and the \uparrow key for 2 seconds or more from normal mode. | While holding down the key, press the seconds or more from normal mode. | While holding down the key, press the seconds or more from normal mode. | While holding down the wey, press the seconds or more from normal mode. | While holding down the \bigcirc key, press the \blacksquare_{1_2} key for 2 seconds or more from normal mode. | While holding down the \bigcirc key, press the \uparrow key for 2 seconds or more from normal mode. | Press the the rormal mode. | Press the 🔶 key three times form the normal mode. | Press the key two times form the normal mode. | Press the | Key operation | |
| | | | | • | 5 9 0 9 8 | | H H D D F - F * | P 5 7 | Note) Skipping about this | * H H H | b - 2 - 2 * * Note) Skipping about this = 4. | Digi | |
| The display will flicker. The program mode [G] will be entered. | The display will flicker. The program mode [F] will be entered. | The display will flicker. The program mode [E] will be entered. | The display will flicker. The program mode [D] will be entered. | The display will flicker. The program mode [C] will be entered. | The display will flicker. The program mode [B] will be entered. | The display will flicker. The program mode [A] will be entered. | The display will flicker. The program mode [P] will be entered. | The pattern No. selection mode will be entered. | The tacking stitches setting mode will be entered. menu at the time of pattern A to | The tacking stitches setting mode will be entered. | The tacking setting mode wil be entered. menu at the time of pattern No | tal display | |
| While holding ⇒ down ↓ key, press ↑ key. | While holding ⇒ down ↓ key, press ↑ key. | While holding down ↓ key, press ↑ key. | While holding ⇒ down ↓ key, press ↑ key. | While holding ⇒ down ↓ key, press ↑ key. | While holding ⇒ down ↓ key, press ↑ key. | While holding e down ↓ key, press ↑ key. | While holding down ↓ key, press ↑ key. | e Press ↓ key any time. | g Press ↓ key any time. | g Press ↓ key any time. | Ⅱ Press ↓ key any time. | Return to the normal mode | |

(3) Selection of each program mode from the normal mode.

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| Program mode [2] While holding down the key, press the key key the key for 2 seconds more from normal mode. | Program mode [1] While holding down the key, press the key a key a the key for 2 seconds more from normal mode. | Program mode [S] While holding down the key, press the key a the key for 2 seconds more from normal mode. | Program mode [R] While holding down the key, press the key a the key for 2 seconds more from normal mode. | Program mode [Q] While holding down the key, press the key a key for 2 seconds more from normal mode. | Program mode [J] While holding down the key, press the read key and the seconds or more from the seconds or more from the seconds. | Program mode [H] While holding down the key, press the key a key a the ↑ key for 2 seconds more from normal mode. | Mode mane Key operation |
|---|---|---|---|---|--|---|-------------------------|
| or 3 6 0 0 entered. | or D U D I I The display will flicker. The program mode [1] will be entered. | or E S I O E S * The display will flicker. * The program mode [S] will be entered. | or E E E F * The display will flicker. | or I I I I I I I I I I | he for I B C O F m | or H H G D * The display will flicker. • H H G D * The program mode [H] will be entered. | Digital display |
| Press key for 2 seconds or more. (*1) | Press key for 2 seconds or more. (*1) | While holding down ↓ key, press ↑ key. | Press key for 2 seconds or more. | While holding down ↓ key, press ↑ key. | While holding down ↓ key, press ↑ key. | While holding down ↓ key, press ↑ key. | normal mode |

Note (*1) :

It is set by pressing [D] key for over two seconds. It is possible to return to normal mode by holding down [], [] key, but in this case it is not set to new setting.

3) HOW TO USE PROGRAM MODES [1] AND [2]

(1)PROGRAM MODE [1]

(SEWING MACHINE HEAD FOR LEATHER AND **HEAVY-WEIGHT MATERIALS)**

(ex.To set for the DNU-241H) To set the functions for the sewing machine with thread trimmer for leather and heavy-weight materials Function setting [DNU4]

Enter program mode [1] ([

] + [A] + [B])

- 4 ω \bigcirc \leftarrow \rightarrow \leftarrow \rightarrow \leftarrow \rightarrow × 2 z Q, 0 Q, ▲ 1-2 ▲ 1-2 ▲ 1-2 3 כ C: sr > ېد ۲ ۶ C: C: ¢ • ¢ / • S r • ٥ ٥ 7 7 * * * Program mode [1] will be entered [DNU4] will flicker when [D] key is pressed. Set function to [DNU4].
- * Press [D] key (2 seconds or mode) to return to the normal mode.

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2 THE PROGRAM MODE [2] (CHAINSTITCH SEWING MACHINE HEAD)

To set the functions for the chainstitch sewing machine head

① Enter program mode [2] ([] + [C] + [D])



(J

Program mode [2] will be entered

*

- * Set function to [3700]
- * [3700] will flicker when [D] key is pressed
- * Press [D] key (2 seconds or more) to return to the normal mode.

Description

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- ₽ JUKI sewing machine with thread trimmer" described in the next page. Press [D] key for 2 seconds or more, and Select the function name that corresponds to the sewing machine model from "Table of simplified setting value for
- Ψ To return to the normal mode from the [dU] display, press the [the number of revolution of the function name and connector function setting can be automatically set] key while holding down [] key. In
- the case, [dU] will not be set, and the last settings will be used
- 0 Each time the [[dSU] ...[U639]. (The factory setting is [LU2v].)] key is pressed in step (3), the function will change in order from [dU] [dnU4] [LZH]
- (Note) In case of SC-380, when this setting function is performed, all contents which have been set sewing machine model can be set automatically. so far are cleared and the number of revolution and function which correspond to the selected

Table of simplified setting value for JUKI sewing machine with thread trimmer

Program mode [1] (Machine head for leather and heavy-weight materials)

| Note2. | | | | | | | | | | | | - | (| | | | Note1 | |
|---------|----------|---|---------|---------|---------|---------------------|---------------------|----------|--------------|-----------|-----------------------|------------|--------------|----------|----------|---------|-------------------|-------------------|
| U639 | LS34 | LU11 | LU56 | LU51 | LU2L | LU2s | LU2v | | PLC | PLW6 | PLW4 | dSC | dSU | LZH | dnU4 | ЧU | name | Function |
| 6 E 3 U | h E S 7 | ~ | 6 2 7 7 | 1 5 1 7 | 2 2 2 2 | 2 2 11 7 | ר נו ל ט ט | | <i>ה ו</i> נ | 9 L L L L | <i>Ь</i> Г <i>В</i> А | <u>, 5</u> | и 5 <i>п</i> | L = H | d n U 4 | d U | | 7 segment display |
| 63900 | LS-341N | LU-1114 | LU-1560 | LU-1510 | LU-2216 | LU-22 * 0 (SW type) | LU-22 * 0 (VR type) | PLC-1610 | PLC-1660 | PLW-126 * | PLW-124 * | DSC-24 * | DSU-14 * | LZH-1290 | DHU-241H | DU-141H | model | Sewing machine |
| 4000 | 2000 | 2500 | 2500 | 3000 | 3000 | 3500 | 3500 | | 2000 | 2500 | 2500 | 2200 | 2000 | 2000 | 2400 | 2000 | (H) | High speed |
| 250 | 170 | 170 | 170 | 170 | 170 | 170 | 170 | | 170 | 180 | 180 | 185 | 170 | 185 | 200 | 200 | (L) | Low speed |
| 180 | 170 | 170 | 170 | 170 | 170 | 170 | 170 | | 170 | 180 | 180 | 185 | 170 | 185 | 170 | 200 | speed (T) | Thread trimming |
| I | 1200 | 600 | 600 | 600 | 1200 | 1200 | 1200 | | 1200 | 570 | 570 | 570 | 1270 | 490 | 820 | 600 | speed (N) | Start tacking |
| I | 1200 | 600 | 600 | 600 | 1200 | 1200 | 1200 | | 1200 | 570 | 570 | 570 | 1270 | 490 | 820 | 600 | speed (V) | End tacking |
| 250 | 170 | 170 | 170 | 170 | 170 | 170 | 170 | | 170 | 180 | 180 | 190 | 170 | 190 | 200 | 200 | speed (S) | Slow start |
| ω | <u> </u> | - | | - | 0 | 0 | 0 | | - | - | <u> </u> | - | - | - | 0 | 1 | of stitches (SLN) | Slow start number |
| CCW | CCW | CCW | CCW | CCW | CCW | CCW | CCW | | CCW | CCW | CCW | CCW | CCW | CCW | CCW | CCW | direction | Rotating |
| z | A | A | D | D | B | C | B | | A | A | A | A | A | A | A | A | function setting | Connector |

Note) 1. Each time the [] key is pressed, a function name is displayed in order to the direction of

2. Each time the [] key is pressed, a function name is displayed in order to the direction of

(Caution) Be sure to select the function name corresponding to the machine head used. If the selection is mistaken, damage to the machine head, control box or motor may result. (However, the actual number of rotations is limited by the machine head used.)

head, control box

or motor may result. (However, the actual number of rotations is limited by the machine head used.)

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Note) 1. Each time the [] key is pressed, a function name is displayed in order to the direction of

. .

2. Each time the [] key is pressed, a function name is displayed in order to the direction of

| | | (|
|-----|------|------|
| MO6 | 3900 | 0004 |

| | i | | | - | · | - | | | | - | - | | | | 1 | | | | | |
|------|-------|----------------|----------------|----------|-------------|-------------|---------|--------------|-------|---------|---------|-------|-------|--------------|-------------|-------------|-------------|-------------|-------------------|-------------------|
| 1116 | U160 | U348 | U347 | U345 | AXM2 | AXM1 | MF | AH1 | MO85 | MO80 | MO75 | MO70 | MO65 | 3900 | 3904 | 3914 | 3700 | 3600 | name | Function |
| | U 160 | <i>U 3 4 8</i> | <i>1</i> 7 7 1 | 5 4 5 11 | 5 U II B | 8 11 11 1 | ר: ר | 8 8 7 | 5800 | n 0 8 0 | 5 1 0 1 | 0 0 0 | 5901 | 0068 | h 0 6 E | h i 6 E | 0065 | 0 0 3 E | | 7 segment display |
| 16 | 160 | 34800 | 34700 | 34500 | MH-486, 488 | MH-481, 482 | MF-7000 | MFC-7000/AH1 | SY-30 | SY-31 | SY-32 | SY-33 | SY-34 | MOR-3900/Z18 | MO-3904/Z18 | MO-3914/Z18 | MO-3700/Z18 | MO-3600/Z18 | model | Sewing machine |
| 800 | 1000 | 5500 | 4000 | 4000 | 4500 | 5500 | 5000 | 5000 | 8500 | 8000 | 7500 | 7000 | 6500 | 7000 | 8500 | 8000 | 7000 | 6000 | (H) | High speed |
| 250 | 250 | 200 | 200 | 200 | 200 | 200 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | (L) | Low speed |
| 200 | 200 | 200 | 200 | 200 | 200 | 200 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | speed (T) | I hread trimming |
| | | | | | | | | | | | | | | | | | | | speed (N) | Start tacking |
| I | | ı | ı | | 1 | 1 | | | 1 | | | 1 | 1 | | I | | | ı | speed (V) | End tacking |
| 250 | 250 | 1000 | 1000 | 1000 | 200 | 200 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | 250 | speed (S) | Slow start |
| 2 | 2 | σı | σ | σ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | of stitches (SLN) | Slow start number |
| CW | CW | CW | CW | CW | CCW | CCW | CCW | CW | CW | CW | CW | CW | CW | CW | CW | CW | CW | CW | direction | Rotating |
| 0 | _ | - | ⊼ | ≤ | _ | _ | т | G | п | п | п | п | п | п | т | т | п | т | function settin | Connector |

Note2.

Note1.



5) Display and function of each key in the tacking mode and pattern mode. (for lock stitch machine)





When the [can be set.] key is turned ON again, n will display above the [M] key indicator, and the No. of stitches





<u>10</u>. HOW TO USE FREQUENTLY USING) THE PROGRAM MODE (EXAMPLE OF MOST

To change the maximum speed (EX. To change to 4500 rotations)......Function setting [H.4500]






| Description A. This is used to increase the penetratio Each time the switch [BCR] connected t is turned ON, the (forward) - (reverse needle will stop right with forward opera the operation signal is turned ON ar machine will operate forward after rev When stopped with reverse operation position. * The needle position stop angle is s position stop angle [C8] in the program. B. Each time the [D] key is pressed in step will be changed. (factory setting is [S0] | (1) Enter program mode [C] ([] + [C]) (2) ↑ , , , , , , , , , , , , , , , , , , | Description A. Using the external switch connected N stitch operation will be operated. B. The setting value will be changed with (factory setting is [S0]) Note) When using this function, alway starting operations. (2) To confirm the position where the need strength of the first stitch with the external strength of the strength of the first stitch with the external strength of the s | (1) Enter program mode [C] ([] + [C]) (2) ↑ , , , , , , , , , , , , , , , , , , | No.5 To change input/output port function.(1) To operate one stitch operation with a |
|--|---|---|---|---|
| st stitch when the fabric is thick. option A connector option A repeated, and the ic. However, when opped the sewing 6 0 OV BCR is BCR is C i C C C C C C C C C C | function to [IC] | OptionA A connector, one [D] key in step (4). (C) (C) (C) (C) (C) (C) (C) (C) | function to [IC] | function setting[IC.S01] |





BSL



Option B

SOL2











- When external one shot signal [SH] (connected No.6 pin in option connector A) is turned ON.automatic
- When one shot signal ON and then either of external operation signals (S0,S1,S4) is turned ON, the sewing machine will be operate at each order speed. And external operation signal is turned OFF,
- signals.) (When [P] mode [AT]=ON or control panel key is ON, operation can be stopped by PSU, PSD or ES
- <u>0</u> Each time the [D] key is pressed in step (4), the set value will be changed
- D. Each time the [D] key is pressed in step (10), the set value will be changed. (factory setting is [SH])
- Set[SS] setting, the operation will be become same as No. 13.

Note) When using this function, always return to the normal mode before starting operations.





No.7 To set number of stitches to the needle UP position stop after detecting the fabric end with an optical sensor, etc. (Ex. to set to 10 stitches).....function setting C mode [IA.PSU] + P mode [PSU.10]



- The setting range of the number of stitches in 0 to 99 stitches.
- Ш ш Set function [IB.PSU] + [PSU.10], it is possible to set number of stitches after detecting the fabric end Each time the [C] key in step (10) or [D] key in step (11) is pressed, the set value will change between 0 to 9.
- (* for example, use the optical sensor in OMRON E3V3-D62) with an optical sensor. (Connect optical sensor output to No.4 pin in option connector A.)



No.8 To continue presser foot lifting after the thread trimming, and to bring down the presser foot after the time set on the timer has passed. function setting [FUM.ON] + [FU.C]











will be invalidated.

N The setting of "BT2" "BT3" and "BT4" is as same as "BT1".

42

| (1) Enter program mode [E] ([] + [] +[A]) | No.13 To check the error code history and input/output signal (1) How to view the error code historyfunction setting [1.E], [2.E], [3.E |
|---|--|
| | .E], [4.E] |



C mode input signal setting table



| Description A. It is useful function for check a wiring. B. The input terminal refer to the explanation of the C mode input signal setting table. | Note) While displaying this function, sewing | Output signal is turned ON while pressing the [D | | * Program mode [E] will be entered. | (1) Enter program mode [E] ([] + [] + [A]) | (4) To check an output terminal (It is turned ON an output terminal without sewin [OFO], [010]-[070]) | Description A. It is useful function for check a operation before B. The input terminal refer to the explanation of the C mode input signal setting table. | (Caution) Be careful to sewing machine operat machine operation has relation. | * Operate that the output terminal turned ON and | | * Program mode [E] will be entered. | (1) Enter program mode [E] ([]+[]+[A]) |
|--|--|--|---|-------------------------------------|--|---|--|---|--|---|-------------------------------------|--|
| input/output signal and input function name refer to a | machine can not operate. |] key. | (5) Return to the normal mode ([]+[]) | * Select output function to see | | ng machine operationfunction setting [OAO]- | wiring solenoid. input/output signal and input function name refer to a | ion when turned ON the signal which the sewing | d check display is turned [ON] | (5) Return to the normal mode ([]+[]) | * Select output function to see | |

No.14 To return all setting to the factory settingsfunction setting [RESET]



When the [D] key is held down (for two seconds), all settings will be returned to the factory settings.

Description

- ₽ When the normal mode will be entered pressing the [D] key when displayed [RESET], all settings will be returned to the factory settings.
- B. To return the normal mode from the [RESET], press the [] key while holding down the [] key.

(Caution) When this function is set, the contents of all settings to this point will be cleared, and will return to the factory settings. Please take care when using this function.

11. HOW TO SET COUNTER FUNCTION

1. To use the counter function

(1) The outline of the counter function

By setting a counter function which is shown in the following figure, it is possible to do the operation to want.



(2) Example for counter function

The counting product amount and bobbin thread are enabled with up and down counter

UP counter for product amount (one hundred times)

 \rightarrow

- (1) Up counter "U" is add at each thread trimming.
- (2)When up counter amount "U" become the setting amount "P", sewing will be prohibited.
- ω When the input signal "11" is turned on, Up counter amount become zero and sewing become possible

Ξ

Enter program mode "C"

+

[C])









2 Down counter for bobbin remain thread count (10,000 stitches is count over)

- [1] Down counter "D" is subtracted at each ten stitches.
- [2] When down counter amount "D" become zero, sewing will be prohibited
- [3] When the input signal "I1" is turned on, Down counter amount become "N" stitch and sewing become possible.







Complete the "I1" function setting.



Complete the "CDN" function setting



[CNU.10] Ten stitches subtract one count amount.

Mark "*" is factory setting.

3. How to Adjust current count amount to use input signal.





| Presser foot lii | Wiper V | | | | Tread release L | | | | | | | Thread trimming T | | | | Needle DOV position Needle position | Run signal |
|--------------------|------------|----------|---------------|---------------|-----------------|---------|---------|-------------|----------|---------------|---------------|----------------------|---------|---------|-------------------|--|------------|
| fter FU | ~ | L7 | ۲S | F | L4 | LЗ | 5 | LLM setting | 77 | TS | TK | T4 | T3 | T2 | LTM setting T1 | | S1 |
| | | LS(Deg) | Cannot be use | Cannot be use | L1(ms) | LS(Deg) | LS(Deg) | LS(Deg) | TS(Deg) | Cannot be use | Cannot be use | T1(ms) | TS(Deg) | TS(Deg) | TS (Deg) | | |
| | W1(ms | | d. | đ. | L2(m | | | | | ¢d. | ġd. | T2(n | | | ▲ | ON | |
| F(x10 ms F1(ms) | | ► L1(ms) | | | <u>s</u> | (ms) | LE(Deg) | | ► T1(ms) | | | () | | E(Deg) | ► T2(| N | |
| | W2(x 10 ms | L2(ms) | | | | | | 2(ms) | | | | | | | ns) | | 0 |

1) Thread trimming timing when thread trimming mode TR setting is PRG

12. SETTING IN THE THREAD TRIMMING MODE TR

Notes : *2. The presser foot lifter [FU] chopping duty can be set with FUD in the P and C mode. *1. The wiper output [W] operation will be special according to the G mode WMD setting.

| | Thread trimmin | | Wiper output W | | Wiper output settin | Sewing machin | Needle UI position UI | signal s Needle DOWI | Thread trimming |
|----|----------------|----|----------------|------------|---------------------|---------------|--------------------------|-------------------------|-----------------|
| AN | ig signal : | 12 | R R | WD setting | ng time | e | م م | | |
| | S2 | | | | W1 [ms] | | - Ou | ON | N |

(2) Wiper output timing

* Wiper output OFF timing is changed by S2 signal OFF timing like above chart [1] and [2].





2. The reverse angle can be set with R8 in the P mode. (*1)



14. OUTPUT KS1,KS2,KS3 TIMINGS



Note) The KS1 to KS3 output start time and output time can be set with K11 to K32 in the S mode.

(Caution) This timing chart (sequence) is only available when [SQS] is set to [NO]. When [SQS] is not set to [NO], please refer to "[15] Simple sequence".

15. SIMPLE SEQUENCE

The function outputs [KS1], [KS2] and [KS3] can be set as simple sequence outputs.

simple sequence starting condition To set the simple sequence output, the starting conditions [IN] [T] [R] [S] [TR] [SB] [GO] are set in the

sequence outputs. (The default setting is the [NO] setting.) Setting function [SQS] of the [S] mode. With this, function outputs [KS1],[KS2] and [KS3] will be simple

1. Simple sequence starting conditions

- [0] The function outputs [KS1],[KS2] and [KS3] can be set as simple sequence outputs. [NO] : The simple sequence is not started. (The default setting is the [NO] setting.)
- (Refer to "[18] Output KS1,KS2,KS3 timings".)
- Ī When input signal I4 (IN4) is turned ON.
- When thread trimming is completed.
- When operation is starting.

স Ξ

- $\overline{\mathbb{O}}$ When motor is stopped. (This also includes when single-stitch operation is stopped.)
- TR When starting stitching after thread trimming.
- [SB] When start tacking is completed. (This will not start if the start tacking setting is "NO".)
- [GO] Always start.

N Simple sequence output timing chart

2<u>2</u> 2-1

Start (The operation will start when the starting conditions are satisfied.)



Explanation of setting function

- (a) Sequence output [KS1][KS2][KS3] output start time/No. of stitch setting changeover [NS1][NS2][NS3] [OF] setting : Time setting ([K11][K21][K31] : 10 msec unit)
- [ON] setting : No. of stitch setting ([K11][K21][K31])
- 0 Sequence output [KS1][KS2][KS3] output start time/No. of stitch setting changeover [NS1][NS2][NS3]
- [OF] setting : Time setting ([K12][K22][K32] : 10 msec unit) [ON] setting : No. of stitch setting ([K12][K22][K32])
- Sequence output [KS1][KS2][KS3] output reference setting [S1S][S2S][S3S]
- <u>(</u>)
- [ON] setting : The output start reference will be the input signal ON reference as shown in the timing [OF] setting : The output start reference will be as shown in the timing chart[2-1]above.
- chart[2-2] above
- (d) Sequence output [KS1][KS2][KS3] output reference setting [S1E][S2E][S3E]

[OF] setting : The output end reference will be as shown in the timing chart [2-1] above. [ON] setting : The output end reference will be the input signal ON reference as shown in the timing chart [2-2] above

- Note) . ` When using the simple sequence make each simple sequence related setting shown above, and assign the function output [KS1][KS2][KS3] to the output setting of the output
- N If the starting conditions are not set in the simple sequence setting starting condition setting [SQS] above (when [NO] is set), the function output [KS1][KS2][KS3] will have the pin being used by setting the C mode output function.

output timing shown on the next page.

ω When starting condition setting [SQS] is [NO] (default setting)





[KS1] : Output for [K12] after the [K11] time after the motor starts rotating.[KS2] : Output for [K22] after the [K21] time after the motor stops.[KS3] : Output for [K32] after the [K31] after thread trimming (or needle lift) stop by pedal heeling.

Note) 1. The output [KS1] [KS2] [KS3] output start time and output time can be adjusted with [K11] [K32] in the [S] mode.

4 Example of simple sequence setting

When the following timing output is to be output to the option B connector's No.3 pin,No.12 pin and No.15 pin. [OUT1][OUT2][OUT3]



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16. COMMUNICATION FUNCTION

| | Specification |
|----------------|--|
| Connector | Mini-DIN connector 6-pin |
| Signal level | Doing based of RS-232C |
| Baud rate | 9600 bps |
| Operation mode | Asyncrouns |
| Start bit | 1 bit |
| Data length | 8 bit |
| Parity | none |
| Stop bit | 1 bit |
| Record format | Original |
| Function | The reading with various multiple time and various counter-value |

1. About the communication

direction by this product. When communication among the equipment, it becomes the method which returns the reply by receiving a

which issues this direction is called a parent machine and equipment Equipment (being computers such as the personal computer in this communication function) on the side

(being SC-380 form control board in this communication function)

The child machine sends an answer only to the inquiry from the parent machine.

must be each other adjusted, to communicate difference machine. parent machine. The form of the data, the electric characteristic, the communication protocol and so on For example, when wanting to take out data continuously, it makes require repeat data on the side of the

1-1. The electric characteristic

parent machine which has to do RS-232C or of RS-232C display and based a can be connected with. and so on. This communication function is based on RS-232C which are an international standard, the It defines the definition of the voltage level and High/Low of the signal, the airlines of the communication

1-2. The communication procedure (protocol)

protocol can not be changed, make a program to agree with this protocol on the side of the parent machine. The protocol to be using for this communication function is the original method of the SC-380. Because this

2. Wiring

2-1. The pin arrangement by the connector

Connector H

| Peripheral plate | 6 | თ | 4 | З | 2 | 1 | Pin number | |
|--------------------------|--------|--------------|----------------|-----------|--------|--------------|-------------|--|
| FG | I | +12 V | COM | TXD | I | RXD | Signal name | |
| | | | | 0 | | _ | I/O | |
| Grounding for the shield | No use | Power supply | Control common | Send data | No use | Receive data | The use | |

2-2. The manufacturing of the data

a cable and connect a child machine and a parent It makes the wiring figure of the following figure reference and manufacture machine.

| 1 | COM | RXD | TXD | I | I | FG | Signal name | P |
|---|-----------------------|--------------|-----------|---|---|--------|-------------|------------|
| | Common for the signal | Receive data | Send data | I | I | Ground | Contents | arent side |
| | | | | | | | | |
| | | | | | | T | Signa | Chi |

Note : Please be careful because the pin number to the signal and so on depend on the computer.

2-3. The attention item in case of wiring

(1) Please use a numerous wick cable with the shield and the shield connect with FG surely.

(2) The wiring distance depend on the environment around but use at the distance which is as short as possible.

ω The basic procedure

3-1. Commands

Transmitting a user command to the child machine from the parent machine.

It is answered that it does ACK to these all transmissions of it. (Note 1)

Note) <u>.</u> As for the partial command, the data which it was answered that it does and input condition itself become ACK. And all data transfer is used by ASCII code.

3-2. The sending and receiving of the various command



3-2-1. User command (Parent machine Child machine)

It manufactures optional data and it answers when receiving data.

(1) 9-byte fixation

| - | ż |
|---|-----------|
| 4 | Command |
| 2 | Check sum |
| - | CR |
| - | F |
| | |

| CR + LF | Check sum | | | Command | | | ċ | |
|----------|--|-------------------------------------|------------------|--|-----------------------------------|---------|------------|--|
| End code | Add ASCII coo | " **** " | "TYPE" | "DATV" | "VSYS" | Command | Start code | |
| | de of user command and invert all bit (refer note 1) | Command (Refer to the command list) | Answer the type. | Answer the version of the EEPROM data. | Answer the version of the system. | | | |

Answer of the data (Child machine Parent machine)

(2) 13-byte fixation

| # | Command | Data | Check sum | CR | _ |
|-------|----------|--------------|-----------------|----------|-----|
| 1 | 4 | 4 | 2 | 1 | |
| | # | Start code | | | |
| 0 | Command | Received co | mmand (echo) | | |
| | Data | Data which c | corresponded to | o the co | mr |
| C | heck sum | Add ASCII c | ode of user con | nmand | ano |
| _ | CR + LF | End code | | | |

At the time of the reception error, following ACK is returned. Answer of ACK (Child machine Parent machine)

(3) 13-byte fixation

| # | П | * | No r | lsed | Check sum | CR | ᆔ | |
|-------|-----|----------|------|----------|---------------|-----------|------------|--------------|
| - | 4 | | 4 | - | 2 | 1 | - | |
| # | | Start co | ode | | | | | |
| | | ПQ | 8 | Norma | al end | | | |
| m, | ** | EQ | 94 | Reco | de type error | | | |
| | | ЕQ | 22 | Check | k sum error | | | |
| Nou | sed | Unsett | ed | | | | | |
| Check | sum | Add AS | | de of us | er command an | ıd invert | all bit (r | efer note 1) |
| CR + | ĥ | End cc | de | | | | | |

Note) 1. For example to make check sum of (13-byte fixation command "type") *refer 4-1. The user command 1.

- "type" ASCII code is 54,59,50.45.
 Add ASCII code. (54+59+50+45=142)
 It uses 2 digits below for the computati It uses 2 digits below for the computation. (use 42 of 142) It uses 42 out of 142.
- 4 Invert all bit of 42. (Again, it hangs reduction 1 and it adds up 1.) The result which inverted all bit of 42 is BD.
- 5 The check sum is BD The check sum is BD.

4. The communication command list

4 <u>'</u> The user 8 Imand 1 (Permitted to data clear

| rating power supply tim | grating power supply tim | grating motor ON time 1 | | tegrating motor ON time 2 | itegrating motor ON urrie z itegrating needle stitches 1 | ttegrating motor ON unre 2 ttegrating needle stitches 1 ttegrating needle stitches 2 | ntegrating motor ON unite 2 ntegrating needle stitches 1 ntegrating needle stitches 2 -ull speed time 1 (upper 1 w | ntegrating motor ON time z ntegrating needle stitches 1 ntegrating needle stitches 2 -ull speed time 1 (upper 1 w -ULL Full speed time 2 (low | Integrating motor ON time 2 Integrating needle stitches 1 Integrating needle stitches 2 Full speed time 1 (upper 1 w FULL Full speed time 2 (low Thread trimming the numbe |
|---|--|---|--|---|--|---|---|---|---|
| iches2 (lower 1 word) ver 1 word) er 1 word) number of times | iches2 (lower 1 word) ver 1 word) rer 1 word) number of times ly time 1 (upper 1 word) | iches2 (lower 1 word) ver 1 word) er 1 word) number of times ly time 1 (upper 1 word) ly time 2 (lower 1 word) | iches2 (lower 1 word) ver 1 word) er 1 word) number of times ly time 1 (upper 1 word) ly time 2 (lower 1 word) me 1 (upper 1 word) | iches2 (lower 1 word) ver 1 word) er 1 word) number of times ly time 1 (upper 1 word) ly time 2 (lower 1 word) me 1 (upper 1 word) me 2 (lower 1 word) | iches2 (lower 1 word) | iches2 (lower 1 word) yer 1 word) er 1 word) rumber of times ly time 1 (upper 1 word) ly time 2 (lower 1 word) me 1 (upper 1 word) me 2 (lower 1 word) nes 1 (upper 1 word) nes 2 (lower 1 word) hes 2 (lower 1 word) | iches2 (lower 1 word) yer 1 word) er 1 word) rumber of times ly time 1 (upper 1 word) ly time 2 (lower 1 word) me 1 (upper 1 word) me 2 (lower 1 word) nes 1 (upper 1 word) nes 1 (upper 1 word) nes 2 (lower 1 word) nes 2 (lower 1 word) hes 3 (lower 1 word) hes 3 (lower 1 word) hes 4 (lower 1 word) hes 5 (lower 1 word) hes 5 (lower 1 word) hes 6 (lower 1 word) hes 6 (lower 1 word) hes 7 (lower 1 word) hes 6 (lower 1 word) hes 7 (lower 1 word) hes 7 (lower 1 word) hes 6 (lower 1 word) hes 7 (lower 1 word) | iches2 (lower 1 word) ver 1 word) er 1 word) number of times ly time 1 (upper 1 word) ly time 2 (lower 1 word) me 1 (upper 1 word) me 2 (lower 1 word) nes 1 (upper 1 word) nes 2 (lower 1 word) es 2 (lower 1 word) nes 2 (lower 1 word) es 1 (upper 1 word) hes 2 (lower 1 word) es 2 (lower 1 word) es 1 word) | Iches2 (lower 1 word) ver 1 word) er 1 word) rumber of times ly time 1 (upper 1 word) ly time 2 (lower 1 word) me 1 (upper 1 word) me 2 (lower 1 word) res 1 (upper 1 word) res 2 (lower 1 word) res 2 (lower 1 word) res 2 (lower 1 word) er 1 word) er 1 word) her 1 word) er 1 word) er 1 word) er 1 word) er 1 word) er 1 word) |
| Numerical value Numerical value Numerical value | Numerical value Numerical value Numerical value Numerical value Numerical value | Numerical value Numerical value Numerical value Numerical value Numerical value | Numerical value | Numerical value | Numerical value | Numerical value | Numerical value | Numerical value | Numerical value |
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| Numerical value (Only subordinate position 12 bit is used.) | Version of the data | DATV |
|---|--|---------|
| Numerical value | Version of the system | VSAS |
| | Swing machine type | TYPE |
| | Voltage | VOLT |
| | Watt | WT_ |
| Only subordinate position 4 bit is used. ***0 The number of trimming times become "1" ***1 The number of sewing stitch become "N" (Function setting [CUN.] in program mode B) ***2 The number of trimming times become "N" (Function setting [PRN.] in program mode B) ***3 When input function "IO1" become ON. ***4 When output function "O1" become ON. ****4 When output function "O1" become ON. | Present count DOWN way | DTYP |
| Only subordinate position 4 bit is used. ***0 The number of trimming times become "1" ***1 The number of sewing stitch become "N" (Function setting [CUN.] in program mode B) ***2 The number of trimming times become "N" (Function setting [PRN.] in program mode B) ***3 When input function "IO1" become ON. ***4 When output function "O1" become ON. Note : *** is irregular. | Present count UP way | UTYP |
| Numerical value | The principal axis number of rotations | SRV_ |
| FFFF (YES) 0000 (NO) | In sewing | MOVE |
| FFFF (Connected) 0000 (none) | Control panel (Connected/none) | BOX_ |
| FFFF (YES) 0000 (NO) | Thread break detector ON/OFF | THRE |
| FFFF (Presser foot OFF) 0000 (Presser foot ON) | Condition of the presser foot lift | OSAE |
| Numerical value | Setting speed | SPDD |
| FFFF (YES) 0000 (NO) | DOWN counter ON/OFF | DPCT |
| FFFF (YES) 0000 (NO) | UP counter ON/OFF | UPCT |
| Numerical value | DOWN counter value | DCNT |
| Numerical value | DOWN counter setting value | DSET |
| Numerical value | UP counter setting value | USET |
| Numerical value | Pattern number | PAT. |
| FFFF (YES) 0000 (NO) | In the error | ERNW |
| | Error code Four times ahead | ERR4 |
| | Error code Three times ahead | ERR3 |
| | Error code Twice ahead | ERR2 |
| | Error code Once ahead | ERR1 |
| 4: Motor connector omission 3: Encoder error. Motor, sewing machine lock error 2: Over voltage 1: Transistor module error | | |
| 6 : Noise error 5 : EEPROM error | | |
| 9 : Solenoid overcurrent 8 : Detector error | | |
| (Only subordinate position 15 bit is used). | | |
| Form of the answer data | Contents | Command |

4-2. User data command 2 (Data clear command)

| Command | Contents | Form of the answer data |
|---------|--|--------------------------------------|
| PPCL | Integrating power supply time clear | Data which can be cleared becomes 0. |
| PMCL | Integrating motor ON time clear | Data which can be cleared becomes 0. |
| PSCL | Integrating needle stitches clear | Data which can be cleared becomes 0. |
| PFCL | Full speed time clear | Data which can be cleared becomes 0. |
| PTCL | Integrating needle stitches clear | Data which can be cleared becomes 0. |
| PCCL | Number of the integrating cycles clear | Data which can be cleared becomes 0. |

4-3. User command 3

| СҮМТ | CYTR | CYOS | CYOF | CYON | ATOF | ATON | MTOF | MTON | Command |
|---|--|---|-----------------|-------------------------------|---|-------------------------------------|-----------------|-----------------|-------------------------|
| One-cycle motor stop frequency (multiplication) | One-cycle thread trimming frequency (multiplication) | One-cycle foot lifting frequency (multiplication) | One cycle time | Idle time after the one cycle | The integrating time to the thread trimming | Idle time after the thread trimming | Motor OFF time | Motor ON time | Contents |
| Numerical value | Numerical value | Numerical value | Numerical value | Numerical value | Numerical value | Numerical value | Numerical value | Numerical value | Form of the answer data |

(Caution) 3 BIT of the place is the order.

13 BIT of the subordinate position is time (unit of 0.1 s) or frequency.

(Reference chart 1)



| S0 : Low speed input | CKU : Up position output | PSD : Down position stop input | +12 V | PSU : Up position stop input | V 0 | Option A | V to 5 V. | 6) The power supply (+12 V) voltage will change form 1 | +12 V | VC : Variable speed command | S3 : Presser foot lifte | S2 : Tread trimming | S1 : Run (Variable speed) | ν0 | command of 5 V, set the setting value of pedal curv Lever (white connector) | $12 \vee$ to 5 V. (When wanting to make change gears o | 5) The power supply (+12 V) voltage will change form | +12 V/ (+5 V) | | Ground | , 1 | 00 | 4) The power supply (+12 V) voltage will change form 12 V to 5 V. | 5 +5 V +12 V ↓ +5 V +12 V +12 V 5 5 | This is set to 5 V when shipped from the factory. To and reinsert it into the 12 V side. | J2, J7, J10, J11 □ □ □ □ +5 ∨ ↓ +12 ∨ ↓ +5 ∨ ↓ +12 ∨ ↓ +12 ∨ ↓ +5 ∨ ↓ +12 ∨ ↓ | This is set to 12 V when shipped from the factory. To and reinsert it into the 5 V side. | 2) The DC5 V/12 V can be changed with the J2, J6,J board on the cover side as shown next page. | How to change the output voltage DC5 V/12 V Remove the cover. | . To change Solenoid voltage 24 V/30 V. (Refer to | RETURN SPEED |
|----------------------|--------------------------|--------------------------------|--------------------------|------------------------------|-----|----------|-----------|--|------------------|-----------------------------|-------------------------|---------------------|---------------------------|----------|--|--|--|-----------------|---|--------|-----|------------|--|---|--|--|--|---|--|---|----------------------------|
| 6 | 512 V = = > 5 V | 4 | $3 \dots 12 V = = > 5 V$ | 2 | | | | 2 V to $5 V$ by changing the J7 connector from 12 | 6 12 V = = > 5 V | 5 | 4 | 3 | Ν | <u> </u> | re function setting <pdc> by the A mode.)</pdc> | if the sewing machine possibly at variable speed | 12 V to 5 V by changing the J11 connector from | 612 V = = > 5 V | 4 | . ω | | <u>د</u> د | 12 V to 5 V by changing the J10 connector from | | change from 12 V to 5 V, pull out the connector | J7, J10, J11 |) change from 5 V to 12 V, pull out the connector | 7,J10 and J11 connector on the printed circuit | | page 13.) | NEL CONNECTOR AND SOLENOID |



3. How to set the switch for increasing the solenoid return speed.

- (1) Remove the cover.
- (2) The solenoid return speed can be increased with the setting of the J1, J5, J8 connector on the printed circuit board on the cover side as shown on the last page.
- (3) Connector factory settings and solenoid return

| OD | Normal | Sewing machine connector 7-8 pin output. | SLOW | J8 |
|--------|--------------------|--|---------------------------------|-----------|
| OA | Normal | Sewing machine connector 3-4 pin output. | SLOW | J5 |
| oc | Normal | Sewing machine connector I1-I2 pin output. | FAST | J1 |
| Output | Solenoid return | Output during simple setting | Connector factory setting | Connector |

(4) Set the connector setting from SLOW to FAST increase the solenoid return speed.

(Caution) The solenoid return cannot be increased if solenoid output chopping duty OAC, ODC, and O3C is return ON in the program mode [C].

speed is increased. The resistance on the printed circuit board will be burnt out if the solenoid return

fast). If "UNION SPECIAL" [UN1], [UN2] and [UN3] are set in program mode [2], always use J1 and J8 set at SLOW (solenoid return is normal), J5 set at FAST (solenoid return is

18. HOW TO SET THREAD BREAK DETECTOR

1. Setting Thread break detector function


| | "THO" output function become on and trimming thread |
|--------|---|
| [ST.] | "THO" output function become on and sewing machine will be stooped. |
| | * When the sewing machine run,"THO" output will be clear. |
| [B.] | To set the speed neglect thread break function. |
| | When sewing machine rotation speed become under this speed, it neglect thread break function. |
| [THS.] | [B.] Setting the neglecting stitch amount from first stitch. |
| THE | Setting the judgment stitch amount of thread break. |

Selection the function on program mode "C".

2. Timing chart of thread break input and output.



Fig 1 Timing chart

Term (1): Sewing machine speed is under "B" speed, so it neglect thread break function.

- Term (2): After sewing machine speed become over "B" speed, still under "THS" stitch amount, so it neglect
- thread break function. Term (3) : Thread break function is valid.
- Term (4): The judgment stitch amount "THF" of thread break, after this stitch amount, thread break function move to "TST" function.

19. CUTTER OUTPUT

1) Cutter



Note) Use of the I*1 input is prohibited when using the blower output.

F mode setting

| | СТС | CEC | CSC | ED | SD | coc | СОВ | COA | CTR | CTM | СТҮ | | 12M | O3M | O2M | O1B | Function name | (|
|----------------------------|--|--|---|--------------------|----------------|-------------------|-------------------|-------------------|---|--|---------------------------------------|--|---|----------------------------------|-------------------------------|----------------------------------|---------------|---|
| sewing machine is stopped. | The output of the automatic cutter output is prohibited while the sensor input is ON while the | The output of the automatic cutter output is prohibited while the sensor is OFF. | The output of the automatic cutter output is prohibited while the sensor is ON. | Mesh judgment time | Cutter ON time | No. of stitches C | No. of stitches B | No. of stitches A | When IO3 is ON, turn OT3 output ON/OFF per set No. of stitches. | Set OT3 cutter output to both OFF ON and ON OFF of IO2 photo switch. | Set I*3 input to manual cutter input. | judgment time set with ED, the IO2 input will not be fixed.) | Add mesh judgment control to IO2 input. (If output stays ON or OFF for longer than the mesh | Set OT3 output to cutter output. | Set OT2 output to air output. | Set OT1 output to blower output. | Specification | |

Note) 1. Always set O2M to ON even when not using the air output.

2 Customize the option connectors I1, I2 and O1 to O3 to the required functions using the program mode beforehand.



- When CTL is set to ON, the BT specification operation will be applied after the I*1 input turns ON. (If the BT output is turned OFF after I*1 turns OFF, the BT specifications will be canceled.)
- *2: S1 is invalidated after the photo sensor detection.
- Operation will restart after stopping and then turning S1 OFF and ON
- ڻ . . Medium speed preset stitching when photo sensor turns OFF after BT input.
- *4: Up position stop after thread trimming.
- *5: Not output when photo sensor is OFF after BT input.
- Note) 1. Always set O2M to ON even when not using the air output.
- N Customize the option connectors I1, I2 and O1 to O3 to the required functions using the program mode beforehand.
- ω The No. of stitch settings PSU, PSD and FCT are common with the other settings. automatically lowers the presser with a timer cannot be used. Thus, when using as the BT specifications, the PSU/PSD input and the function that

20. TABLE OF PROGRAM MODE FUNCTIONS

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | Fu | unctio name Dig | on gital (| display | Settinę | g | Specification | Ref. page |
|--------------|--|--|--|-------------------------------------|------------------|------------------|-----------------------|---------------|------------|--|----------|---|--------------|
| | Maximum speed H. | 0 | 3500 | r/min | 0 to 8999 | H. | | | **** | | **** | The maximum speed can be set. | |
| | Low speed L. | 0 | 170 | r/min | 0 to 499 | L. | | | *** | | *** | The low speed can be set. | - |
| | Thread trimming speed T. | 0 | 170 | r/min | 0 to 499 | ſ. | | | *** | 1 | *** | The thread trimming speed to reach the needle UP position stop from the needle DOWN position during full heeling of when thread trimmer signal (S2) is turned ON can be set. | - |
| | Start tacking speed N. | 0 | 1200 | r/min | 0 to 2999 | n. | | | **** | , | **** | The speed of start tacking can be set. | - |
| | End tacking speed V. | 0 | 1200 | r/min | 0 to 2999 | U. | | | **** | | **** | The speed of end tacking can be set. | - |
| | Medium speed M. | 0 | 2000 | r/min | 0 to 8999 | ſĨ. | | | **** | | **** | The medium speed can be set. | - |
| P mode | Slow start speed S. | 0 | 170 | r/min | 0 to 2999 | 5. | | | **** | | **** | The slow start speed can be set. | - |
| \bigcup | No. of slow start stitches SLN. | 0 | 0 | Stitches | 1 to 5 | 5 | L | n. | * | , | * | The No. of slow start stitches can be set. This is valid when the [B.SL] key is ON in the normal mode. | - |
| + | Slow start operation mode SLM. | 0 | Т | - | _ | 5 | Ł | ſĨ. | | | | The slow start operation mode is selected. This is valid when the [B.SL] key is ON in the normal mode. | - |
| | | | | | | | | | ٢ | | Т | Slow start operation will begin when the power is turned ON or when the first toe down after thread trimming, or the first external run signal ÅiS0, S1Åjis turned ON. | - |
| | | | | | | | | | R | | A | Slow start operation will begin when the pedal is toed down or when the external run signal (S0, S1) is turned ON. | - |
| | Slow start when power SLP. sturned ON | 0 | OF | - | - | 5 | L | Р. | o n o F | | ON OF | Slow start operation will begin when the pedal is toed down for the first time after turning the power ON, or when the first external run signal (S0, S1) is turned ON even if the [B, SL] key is turned OFF in the normal mode. | - |
| | One shot SH. | 0 | OF | - | - | 5 | H. | | on of | , I . I | ON OF | The one shot function can be selected. One shot operation (automatic operation) will begin when the external run signals (S0, S1, S4) is turned ON. | - |
| | One shot operation mode SHM. | ○ | SH | - | - | 5 | Н | N. | | | | The one shot SH operation mode is selected. This is valid when one shot SH is [ON]. | - |
| | Operation validity O mark : The sewing machin X mark : The sewing machine Operate the sewing after retu | C e can be e cannot irning to | aution operated in be operated the normal | the functi I in the fur mode. | on setting s | state. Ig sta | ate. | | 5 <i>.</i> | i | SH | When one of the external run signals (S0, S1, S4) is turned ON the sewing machine will rotate at the commanded speed while ON, and will continue operating even when the signal is turned OFF. However, the speed will be that commanded with the speed setting key ($[C,<==], [D, ==>]$ key) while OFF. (When the automatic operation function is turned ON in the normal mode.) Stops with PSD, PSU, ES or SEN signal. | _ |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | Function name Digital | | spla | Settir y | ng T | Specification | Ref. page |
|--------------|------------------------------|-----------------|-----------------|------|------------------|-------|-----------------------------|------------|----------|-----------------|---------------|--|--------------|
| | One shot operation Mode SHM. | 0 | SH | _ | - | 5 | н | <u>n</u> 5 | | 5 | S | When one of the external run signals (S0,S1,S4) is turned ON, the sewing machine will rotate at the | _ |
| | | | | | | | | | | | 1 | speed commanded with each signal even if the signal is turned OFF. | |
| | | | | | | | | S | Ē | 3 | | The same operation as when [SS] is set is included. When one of the external run signals (S0,S1,S4) | |
| | | | | | | | | - | | | 1 | is turned (1) OFF=>ON=> (2) OFF=>ON, the sewing machine will stop (1) and will restart at (2) | |
| | | | | | | | | | | | 1 | .(Alternate operation). | |
| | | | | | | | | r | Ē | ر | R\ | If the automatic operation function is OFF and the one shot signal (SH) is turned ON, the sewing | |
| | | | | | | | | | | | 1 | machine will run at the low speed. | |
| | | | | | | | | | | | l I | If the lever connector variable speed command [VC] is input in this state, the sewing machine speed | |
| | | | | | | | | | | | 1 | will be approximately in proportion with the voltage. | |
| | | | | | | | | | | | l I | The sewing machine will continue to run at the speed proportional to the variable speed command | |
| | | | | | | | | | | | 1 | [VC] even if the one shot signal (SH) is turned OFF in the normal mode. If the automatic operation | |
| | | | | | | | | | | | 1 | function is ON and the one shot signal (SH) is turned on, the sewing machine will run at the speed set | |
| Р | | | | | | | | | | | 1 | with the speed setting key ([C, $\leq =$], [D,= \geq] key). | |
| mode | | | | | | | | | | | 1 | The sewing machine will continue to run at the set speed even if the on shot signal (SH) is turned | |
| | | | | | | | | L. | | | + | OFF | |
| | | | | | | | | r | ł | 4 | R | The sewing machine will run at the maximum speed [H] when the one shot signal (SH) is turned ON. | - |
| + | | | | | | | | L. | | | + | The sewing machine will continue to run at that speed even if the signal is turned OFF. | |
| (\uparrow) | | | | | | | | r | ſ | 7 | RN | The sewing machine will run at the medium speed[M] when the one shot signal (SH) is turned ON. | - |
| | | | | | | | | L. | | | + | The sewing machine will continue to run at that speed even if the signal is turned OFF. | |
| | | | | | | | | r | L | | RI | The sewing machine will run at the low speed [L] when the one shot signal (SH) is turned ON. The | - |
| | | | | | | | | L | | | | sewing machine will continue to run at that speed even if the signal is turned OFF. | |
| | | | | | | | | 8 | ! L | , | A A | When the one shot signal (SH) is turned OFF => (1) ON => OFF=> (2) ON=> OFF=> (3) ON=> OFF, | - |
| | | | | | | | | | | | 1 | the same operation as the sewing machine speed is set to [RV] above is executed at (1). | |
| | | | | | | | | | | | i i | The sewing machine will stop at (2) and will run at the same conditions as [RV] at (3). | |
| | | | | | | | | L. | | | + | (This operation is referred to as alternate operation hereafter.) | |
| | | | | | | | | R | ' F | 4 | i Al | The alternate operation of [RH] is executed. | - |
| | | | | | | | | R | ſ | 7 | + AN | The alternate operation of [RM] is executed. | |
| | | | | | | | | R | | | + – – I Al | The alternate operation of [RL] is executed. | |
| | | | | | | | | | | | | | |

| Mode name | Function name | | Oper ability | Factory setting | Unit | Setting range | F | unctic name Diç | on e gital (| | Sett lay | ting ¬ | | Specification | Ref. page |
|--------------|--|------|-----------------|-----------------|----------|------------------|----------|-----------------------|--------------------|----------|-----------------|------------------------|----------|---|--------------|
| | No. of stitches after PSU input | PSU. | 0 | 0 | Stitches | 0 to 99 | P | 5 | U. | ** | | | ** | The no. of stitches until stopping after the UP position priority stop signal PSU is input is set. | _ |
| | No. of stitches after PSD input | PSD. | 0 | 0 | Stitches | 0 to 99 | ρ | 5 | ď. | ** | | | ** | The no. of stitches until stopping after the DOWN position priority stop signal PSD is input is set. | - |
| | Restart after PSD, PSU input PSN | PSN. | 0 | OF | _ | - | Ρ | 5 | n. | 0 0 | n F | | ON OF | After detecting the end of the fabric by a sensor with the PSU,PSD and SEN signals and stopping, restarting is possible with the pedal toe down or external run signalÅiS0,S1Åjeven if the sensor does not detect the fabric. (even if PSU,PSD signals are ON). | - |
| | Input sensor function | SEN. | 0 | OF | - | _ | 5 | Ε | n. | 0 | n | (| ON | Sensor input function "SEN" is valid. [SEN] have to be set on C mode. | - |
| | valid/invalid | 0 | | 0 | Ctitohoo | 0 to 00 | r | <u> </u> | | 0 | + | | OF ** | (as same as the sensor key on control panel) | |
| Р | to stop by "SEN" | SE. | | 0 | Suiches | 01099 | כ | ζ. | | | | 1 | | ("SEN" have to be set "ON") | _ |
| mode | Presser foot lift momentary | FUM. | 0 | ON | - | _ | F | U | N. | 0 0 | n F | | ON OF | This is the momentary function of the presser foot lifting. | - |
| + | FUM operation mode | FU. | 0 | Μ | - | - | F | U. | | | | | | The operation mode of the presser foot lift momentary mode is selected. This is valid when the presser foot lift momentary FUM is set to [ON]. | - |
| (\uparrow) | | | | | | | | | - | <u>ה</u> | | | M | After thread trimming with full heeling or the external thread trimmer signal S2, the presser foot lifting operation is continued. | |
| | | | | | | | | | | [| | | С | After thread trimming with full heeling or the external thread trimmer signal S2, the presser foot lifting operation is continued while the timer is on, and then the presser foot will lower. The timer time is set with the timer setting FCT. | _ |
| | | | | | | | | | | R | | - 上 | Ā | The presser foot lifting operation is activated with full heeling, light heeling, or the external control signal (S2,F) ON. Then, when the full heeling, light heeling or external control signal (S2,F) is turned ON, the presser | |
| | | | | | | | | | | | | 1 | | foot will bring down, and when turned ON again, the presser foot will lift. (Alternate operation.) | |
| | | | | | | | | | - | ٢- | | | T | The timer operates in the manner as the [C] setting. |] |
| | | | | - | | | <u> </u> | | _ | | | | | However, after the presser foot bring down, the same alternate operation as the [A] setting will occur. | ļ |
| | Time setting for FUM operation mode (FU is set to [C],[T]) | FCT. | 0 | 12 | sec | 1 to 99 | F | ζ | <i>F</i> . | ** | | | ** | The timer time for the presser foot output to turn ON and then turn OFF when the mode P FUM operation mode FU is set to [C], [T] can be set. | _ |
| | Time to motor drive after presser foot lifter bring down | FD. | 0 | 176 | msec | 0 to 998 | F | ď. | | *** | | | *** | The time for the motor to start driving after the presser foot output FU is turned OFF when pedal toe down or external run signal (S0,S1) ON during presser foot lifting can be set in 2 millisecond units. | - |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | unctio name Dig | on ; gital c | displa | Settin | ng ¬ | Specification | Ref. page |
|---------------------|---|-----------------|-----------------|-------------|------------------|-------|-----------------------|-------------------------|-------------|-------------|---|--|--------------|
| | Full wave time of presser FO. foot lifter output | 0 | 50 | X10 msec | _ | F | 0. | | 2 | | $\begin{array}{c} 1 \\ - & - & - \\ - & 20 \\ - & 25 \\ + & - & 25 \\ + & - & 25 \\ - & - & 30 \\ - & - & 40 \\ + & - & - \\ - & - & - \\ - & - & - \\ - & - &$ | The full wave time of the presser foot lifter output during [FU] operation can be set. [20] : Full wave time 200 mS [25] : Full wave time 250 mS [30] : Full wave time 300 mS [40] : Full wave time 400 mS [50] : Full wave time 500 mS [60] : Full wave time 600 mS [80] : Full wave time 800 mS [100] : Full wave time 1 sec | |
| | Delay time of presser S3D. foot signal S3 input | 0 | 10 | X10 msec | 1 to 99 | 5 | 3 | d . [*] | ** | , , | ** | The delay time for the presser foot output FU to turn ON when the light heeling (lever signal presser foot lifting signal S3) is input before thread trimming can be set. | - |
| P mode ↓ + | Presser foot lifting FUD. output chopping duty | 0 | MF | _ | - | F | U | d. | n n F | 5 F L | + | The chopping output duty during holding after the presser foot lifting output FU presser foot lifting operation can be set. Set to [MS] : 4 msON/OFF, 50 %duty Set to [MF] : 2 msON/OFF, 50 %duty Set to [HI] : 4 msON,2 msOFF, 50 %duty Set to [FL] : 100 % (full wave) Set to [I O] : 2 msON 4 msOFF 33 % duty | |
| | Presser foot lifting PFU. output when power is turned ON | 0 | OF | _ | _ | ρ | F | U. C | 0 | n F | ON OF | The presser foot lifting operation begins when power is turned ON. This is valid when the FUM function is set to [ON]. When FU is set to [C] or [T], the presser foot will lift only while the timer is ON. | - |
| | Cancel the presser FL. foot lifting with full heeling | 0 | OF | - | - | F | L. | 6 | 0 | n F | ON OF | The presser foot lifting operation after thread trimming with full heeling or the external thread trimmer signal S2 is prohibited. However, the presser foot lifting is carried out with the presser foot lifting signal F or light heeling. | - |
| | Cancel presser foot lifting S3L. with light heeling | 0 | OF | - | _ | 5 | 3 | L. 0 | 0 0 | n F | ON OF | The presser foot lifting operation with light heeling is prohibited. The presser foot operation is carried out with full heeling or the presser foot lifting signal F. | - |
| | Cancel of thread S2L. trimming operation | 0 | OF | - | - | 5 | 2 | ٤. (ر | 0 0 | n F | ON OF | The thread trimming operation and subsequent presser foot lifting operation with full heeling or external thread trimmer signal S2 is prohibited. | - |
| | Thread trimming protection S6L. signal (S6) logical changeover | X | LO | _ | _ | 5 | 6 | L. | H | , | | The operation can be changed when the thread trimming protection signal (S6) is turned Short/ Open The sewing machine will stop when the input signal (S6) is Open | |
| | | | | | | | | | ٤ | 0 | LO | The sewing machine will stop when the input signal (S6)is Short. | - |

| Mode name | Function name | | Oper ability | Factory setting | Unit | Setting range | F | unctio name Dig | on e gital d | | Setti | ing ㄱ | | Specification | Ref. page |
|---------------------------|---|-------|-----------------|-----------------|--------|------------------|----------|-----------------------|--------------------|------------|--------|-----------|----------|---|--------------|
| | Automatic operation | AT. | 0 | OF | - | _ | R | ſ. | | 0 0 | n F | | ON OF | Automatic operation (standing operation) can be set. | - |
| | Thread trimmer cancel | TL. | 0 | OF | - | _ | ſ | Ł. | C |) (| n c | I I | ON | The thread trimming operation with full heeling of the pedal or with the thread trimming signal S2 is | - |
| | | | | | | | <u> </u> | | <u> </u> | <u>)</u> | F | 1 | OF | not performed, and instead needle UP position stop will occur. | |
| | Auto-stop of preset | TLS. | 0 | OF | - | - | F | Ł | -5. C | , , | n c | 1 | ON | Auto-stop of preset stitch sewing before thread trimming. | - |
| | stitch sewing before trim | | | | | | _ | | 0 | , 1 | ۴ | | OF | And then it is free sewing till thread trimming. | |
| | Reverse run needle lifting | RU. | 0 | ON | - | - | r | U. | C | , (| n - | I. | ON | The motor is reverse run after thread trimming, and the needle will stop near the needle bar top dead | - |
| | after thread trimming | | | | | | | | C | , 1 | F | | OF | point. | |
| P | RU reverse run angle | R8. | 0 | 60 | Degree | 0 to 360 | r | 8 . | * | ** | | i | *** | The reverse run angle from the UP position after thread trimming can be set for when the reverse run | - |
| mode | | | | | | | | | | | | 1 | | needle lifting after thread trimming RU is set to ON. The setting angle is in two degree intervals. | |
| | Thread trimming with | TB. | 0 | OF | - | - | ſ | b . | 0 | יכ | n | i | ON | The thread is trimmed with reverse feed by driving the backstitch solenoid simultaneously with the | - |
| | reverse feed | | | | | | | | C | , i | F | 1 | OF | thread trimmer solenoid. | |
| + | Cancel of TB function | TBJ | 0 | ON | - | - | ſ | Ь | J.C | , (| n | I I | ON | Thread trimming is canceled with reverse feed of end N or W tacking when TB function is set to ON. | - |
| $\left \uparrow \right $ | at the time of end N or W tac | cking | | | | | | | C | , i | F | 1 | OF | | |
| | Full heeling, S2 signal soperation mode | S2R. | 0 | ON | - | _ | 5 | 2 | r. | | | | | The operation mode of full heeling or external thread trimmer signal S2 is selected. This is valid when cancel of thread trimming operation S2L is set to [OF]. | - |
| | | | | | | | | | 6 | , | n | + - | ŌN | With full heeling or the external thread trimmer signal S2 after the needle UP postion stop, the motor | |
| | | | | | | | | | | | | 1 | | will rotate once to trim the thread. Then the presser foot will lift. | |
| | | | | | | | | | | | | 1 | | When stopped at the needle DOWN position, the motor will make a half-rotation and then the | |
| | | | | | | | | | | | | I. | | presser foot will lift. | |
| | | | | | | | | | Ē | | F | + - | ŌF | The needle will remain at the UP position even when full heeling or external thread trimmer signal S2 | |
| | | | | | | | | | 1 | | • | i. | | is turned ON after stopping at the UP position. Only the presser foot lifting operation will operate after | |
| | | | | | | | | | | | | 1 | | this. | |
| | | | | | | | | | | | | i | | When full heeling or external thread trimming signal S2 is input after the needle DOWN position | |
| | | | | | | | | | | | | l I | | stop, motor will make a half-rotation and trim the thread. Only the foot lifting operation will operate | |
| | | | | | | | | | | | | 1 | | after this. | |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | Function name | | | Sett | ting ¬ | | Specification | Ref. page |
|---------------------|--|--|--|--|--|------------------------------------|---|------|----------|---|--|--|--------------|
| | Cancel of interlock after full IL. | 0 | OF | _ | _ | Digita | tal dis | spla | ıy | 1 | | This releases the restart operation prohibit command during thread trimming. | _ |
| P | Cancel of interlock after full IL. pedal heeling Thread trimming mode TR. Needle DOWN position DN | 0 0 | OF J1 — Thread t | - - | _ _ gnal S2 | , L. [r. | | | | | ON OF PRG NO KA1 KA2 KA3 | This releases the restart operation prohibit command during thread trimming. Restart is possible for a designated time after the pedal toe down or external operation signal (S0, S1) is turned ON immediately after full pedal heeling. This is used with a sewing machine that does not have thread trimming. Restart is not possible. Restart is possible if the pedal toe down or external run signal (S0,S1) is turned ON again after a set time is passed. The thread trimming timing for each manufacturer's thread trimming sewing machine can be set. Not used. For free setting of the thread trimming. Not thread trimming sewing machine. Not used. Not used. Not used. Not used. | |
| P mode ↓ + | Needle UP | ming pos e factory | S8 | E8 ON hal's ON s for S8, and | ON tarting angle d 90 for E8.) | S8, | | | | 1 <u> </u> + + + + + + + + + + + + + + + + + + + | KA4 KA5 KA6 KA7 KB1 KB2 KB3 KB4 B1 D1 J1 | Not used. Standard | |
| | The thread trimming timing for in the thread trimming mode be set separately. When set the B mode to [LO] 33 % duty | or each t TR, but to [D1], : /. | Caution thread trimm the speed, e set the lifting | ing sewin etc., canno g output c | g machine c ot be set. The hopping dut | an be set ese must ty FUD in | <u></u> σ σ σ σ σ σ σ σ σ σ σ σ σ σ σ σ σ σ σ | | - | \cdot $+$ $+$ $+$ $+$ $+$ $+$ $+$ $+$ $+$ $+$ | J2 P1 P2 P3 P4 T1 T2 RK | Not used Not used. Not used. | |

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| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | | Functi nam D | ion ie igital | disp | Sett | ting – | | Specification | Ref. page |
|---------------------------|-------------------------------------|-----------------|-----------------|--------|------------------|---|--------------------|---------------------|------|----------|-----------|-----|---|--------------|
| | Thread trimming validity POS. | 0 | OF | - | _ | P | 0 | 5. | 0 | n | 1 | ON | The needle will stop in the UP position after thread trimming, during neutral after pedal toe down or | _ |
| | at neutral pedal | | | | | | | | 0 | F | 1 | OF | when external run signal (S0,S1) is turned OFF. | |
| | Operation when power is P1P. | 0 | OF | - | _ | ρ | 1 | Ρ. | 0 | n | Т | ON | When 1 position is set with the [A,1-2] key in the normal mode, the needle will lift to the UP position | _ |
| | turned ON during 1 position setting | | | | | | | | 0 | F | 1 | OF | if not in the UP position when the power is turned ON. | |
| | Operation when power is P2P. | 0 | OF | - | _ | ρ | 2 | ρ. | 0 | n | İ | ON | When 2 position is set with the [A,1-2] key in the normal mode, the needle will lift to the UP position | _ |
| | turned ON during 2 position setting | | | | | | | | 0 | F | 1 | OF | if not in the UP position when the power is turned ON. | |
| | Needle stop position C8. | 0 | 60 | Degree | 0 to 360 | 1 | 8 . | | *** | | 1 | *** | The needle stop position angle can be set just above the fabric looking from the UP position when | _ |
| | before fabric | | | | | | | | | | 1 | | the input signal is set the [BC] or [BCR]. | |
| | | | | | | | | | | | 1 | | (The setting angle is in 2 degree intervals.) | |
| Р | Needle DOWN position D8. | 0 | 32 | Degree | 10 to 180 | ď | 8 . | | ** | | I | ** | The coasting angle at the needle DOWN position stop can be set. | _ |
| mode | stop angle | | | | | | | | | | 1 | | (The setting angle is in 2 degree intervals.) | |
| | Needle UP position U8. | 0 | 10 | Degree | 10 to 180 | U | 8 . | | ** | | 1 | ** | The coasting angle at the needle UP position stop can be set. | _ |
| | stop angle | | | | | | | | | | 1 | | (The setting angle is in 2 degree intervals.) | |
| + | Reverse run angle from K8. | 0 | 180 | Degree | 0 to 360 | E | 8 . | | *** | | I | *** | The reverse run angle from the DOWN position to the UP position can be set when the S0 operation | - |
| $\left(\uparrow \right)$ | DOWN position to UP position | | | | | | | | | | | | mode [USR] or reverse thread trimming mode operation mode TR [RK] is set in mode P. | |
| | ON angle of virtual TM E8. | 0 | 90 | Degree | 0 to 360 | E | 8 . | | *** | | I | *** | The width of virtual signal "TM" .: | - |
| | | | | | | | | | | | 1 | | When [TR] = [B1] or [T2], it is possible to use this function. | |
| | ON start angle of virtual TM S8. | 0 | 50 | Degree | 0 to 360 | 5 | 8 . | | *** | | 1 | *** | The start angle of virtual signal "TM" .: | - |
| | | | | | | | | | | | 1 | | When [TR]= [B1] or [T2], it is possible to use this function. | |
| | Setting sensor "SEN" SNM. | 0 | ON | - | - | 5 | n | Π. | 0 | n | 1 | ON | Input "SEN" is always valid. | - |
| | input function | | | | | | | | 0 | F | 1 | OF | Input "SEN" is only valid, when setting pattern is free sewing. | |
| | Virtual down Setting KD. | 0 | OF | - | - | E | d . | | 0 | n | 1 | ON | Sewing machine run without down signal. The angle between up and down position is set to "K8". | - |
| | | | | | | | | | 0 | F | 1 | OF | The width is set at 60 degree automatically. | |
| | Virtual width of up and KDU. | 0 | OF | - | - | E | d | U. | 0 | n | 1 | ON | It set the up and down signal width to 60 degree automatically. | - |
| | down signal | | | | | | | | 0 | F | 1 | OF | | |

| Mode name | Function name | | Oper ability | Factory setting | Unit | Setting range | Fi | unction name Digita | Settir | ng T | Specification | Ref. page |
|--------------|-------------------------|------|-----------------|-----------------|-------------|------------------|----------|-------------------------------|----------------|-------------|--|--------------|
| | Gain high/low selection | GA. | 0 | Н | _ | _ | ն | <i>R</i> . | | | The high/low gain can be set. Set with the following according to the sewing machine being used. | - |
| | | | | | | | | | H | ⊥ ! H | Sewing machine with large inertia. | |
| | | | | | | | | | L | L | Sewing machine with small inertia. | _ |
| | | | | | | | | | | | This is used when there is a slight vibration when stopping even when the gain is set to [L]. |] |
| | Pedal curve | PDC. | 0 | 30 | - | 10 to 99 | ρ | d [| ** | ** | The size of the curve of the speed changes for the pedal toe down amount can be set. The speed | - |
| | | | | | | | | | - | 1 | change curve will change from small to large according to the small => large of the set value. | |
| A mode | | | | | | | | | | | Speed Speed Factory setting[30] Set value-Small Pedal toe down | |
| | Acceleration time | AC. | 0 | М | _ | _ | 8 | ſ | | 1 | The time for the sewing machine to reach the high speed after the pedal toe down or external run | _ |
| + | simple setting | | Ũ | | | | " | ٤. | | 1 | signal (S1) is input can be set easily. | |
| A | | | | | | | | | 8 | ÷ | [H] : 100 mS | |
| 1-2 | | | | | | | | | <i>n</i> | + M | [M] : 140 mS | |
| | | | | | | | | | ℓ | Γ L | [L] : 240 mS | |
| | | | | | | | | | • | + | [-] : The time set in the next acceleration time ACT is used. | |
| | Acceleration time | ACT. | 0 | 14 | x10 msec | 6 to 99 | 8 | E F. | ** | ** | The acceleration time for the sewing machine to reach the high speed after pedal toe down or external run signal (S1) ON can be set. This is valid when the acceleration time simple setting AC is set to [–]. | - |
| | Deceleration time | DC. | 0 | М | _ | _ | ď | ί. | | + | The deceleration time for the sewing machine to stop after returning to neutral from pedal toe down | _ |
| | simple setting | | | | | | | | | 1 | or when the external run signalÅiS1Åjis turned OFF can be set easily. | |
| | _ | | | | | | | | H | + H | [H] : 90 mS | |
| | | | | | | | | | n | ! M | [M] : 160 mS | |
| | | | | | | | | | [L | + L | [L] : 230 mS | |
| | | | | | | | | | • | | [-]: The time set in the next deceleration time DCT is used. | |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | unction name Digita | l dis | Setting | g | Specification | Ref. page |
|----------------|--|-----------------|-------------------------|-------------|------------------|-------|---------------------------|-------------|----------------------------------|----------------------------------|--|---|
| | Deceleration time DCT. | 0 | 16 | x10 msec | 6 to 99 | ď | ſſ. | • | • | ** | The deceleration time for the sewing machine to stop after returning to neutral from pedal toe down or when the external run signal (S1) is turned OFF can be set. This is valid when the deceleration | - |
| | The factory setting [I6] refers | C to [l6x1 | aution 0 millisecond | ds=160 m | illiseconds]. | | | | | | time simple setting DC is set to [-]. Normally use this at 350 milliseconds or less. | |
| A mode + | S-character cushion SC. | 0 | OF | _ | _ | 5 | ζ. | 0 | 7 7 7 | ON OF | The speed change curve is accelerated slowly for the t time after pedal toe down or the external run signal (S1) is turned ON, and then the sewing machine accelerates rapidly and enters the high speed operation. This is effective when carrying out one stitch sewing with the external run signal (S1) when automatic operation function is set in the P mode. | - |
| A 1-2 | S-character cushion SCT. time setting | 0 | 7 | x10 msec | 0 to 99 | 5 | ſſ. | ** | ۱ ^۲ | ** | The "t" time can set when S-character cushion is set to [ON]. | - |
| | Full heeling S2 signal S2M. operation mode when power is turned on or after thread trimming | 0 | FU | _ | _ | 5 | 2 N. | F U U | U | FU - U - U - NO - UF | The operation mode of the full heeling or S2 signal when the power is turned on or after thread trimming is determined. The presser foot lifting operation is entered. The needle lifting operation is entered. No operation. The presser foot lifting operation after needle lifting is entered. | - - - - - - - - - - - - - - - - - - - |
| | Sewing machine shaft/ PL. motor shaft speed setting selection | 0 | OF | _ | _ | Ρ | L. | 0 | F F | ON OF | The speed setting is set so that the normal sewing machine shaft speed is constant, but by the [ON] setting, it is possible to operate at the value which was set by the [MR], [SR] function. This is effective when the motor pulley diameter is small, the V belt slips and the sewing machine speed is unstable. | - |
| | Setting motor pulley MR. diameter | 0 | 70 | mm | 20 to 349 | n | г . | *** | ** | *** | Set the diameter of motor pulley When "PL" is "ON", this function is valid. | - |
| | Setting sewing machine SR. pulley diameter | 0 | 70 | mm | 20 to 349 | 5 | r . | *** | ** | *** | Set the diameter of sewing machine pulley When "PL" is "ON", this function is valid. | - |

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| Mode name | Function name | | Oper ability | Factory setting | Unit | Setting range | F | uncti nam | ion e igita | L I disp | play | Settin | g I | Specification | Ref. page |
|--------------|-------------------------|----------------|--------------------|-----------------|---------------|------------------|-------|--------------|-----------------------|-------------|--------|--------|-----------|--|--------------|
| | No detector mode | NOS. | 0 | OF | - | - | n | 0 | 5 | 0 | n | | ON | Variable operation is possible when the detector has broken by setting to [ON] to invalidate the | - |
| | | | | | | | | | | 0 | F | | OF | detector. The positioning stop and thread trimming operations will not be possible. | |
| | Motor maximum speed | MSP. | 0 | 36 | x100 r/min | - | n | 5 | Ρ. | | | | | The motor's maximum speed can be set. | - |
| | | | | | | | | | | 3 | 6 | | 36 | Set to [36]:3600 r/min | |
| | | | | | | | | | | ' 4 | 0 | | 40 | Not used | |
| | First priority stop => | STM. | 0 | OF | _ | _ | 5 | ٢ | ſ. | | | | ON | When machine will be stop, first priority become speed control | _ |
| | speed contro | | | | | | | | | | | | OF | (Usually first priority to stop is stop angle.) | |
| A | Brake time | BKT. | 0 | 14 | x10 | 0 to 99 | Ь | Ł | ſ. | ** | | | ** | The brake time for stopping the sewing machine can be set. | - |
| mode | | | | | msec | | | | | | | | 1 | | |
| | Weak brake angle | B8. | 0 | 14 | x0.1 | 4 to 500 | Ь | 8 . | | *** | | | *** | Setting the angle to clear weak break. | - |
| | | | | | Degree | | | | | | | | I | Minimum setting angle is 0.2 degree. | |
| + | The factory setting [14 | Ca] refers | ution to[l4x0.1 | 1 degree=1.4 | l degree]. | | | | | | | | | | |
| | Reduction of weak | BNR. | 0 | ON | _ | _ | Ь | 0 | r | 0 | n | | ON | Reducing the sound (noise) of weak brake. | _ |
| | brake sound | | - | | | | | | | 0 | F | | OF | | |
| | Weak brake force | BKS. | 0 | 99 | % | 0 to 99 | Ь | Ł | 5. | ** | | | ** | The weak brake force can be set. | _ |
| | Weak brake mode | BKM. | 0 | E | - | - | Ь | Ł | n. | | | | | The weak brake force can be set for when stopping the sewing machine when the weak brake [BK] | - |
| | | | | | | | | | | | | | I L | is set to [ON]. | |
| | | | | | | | | | | E | | | i E | Set to [E] : Brake that allows manual rotation. | |
| | | | | | | | | | | H | | | H | Set to [H] : Strong brake | |
| | Weak brake | BK. | 0 | OF | - | - | Ь | દ . | | 0 0 | n F | | ON OF | The weak brake validity can be set. | - |

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| Mode name | Function name | | Oper ability | Factory setting | Unit | Setting range | F | Function name Digita | al di | S isplav | ettinę – – | g | Specification | Ref. page |
|--------------|---|------|-----------------|-----------------|-------|------------------|------------|--------------------------------|-------------|-----------------|----------------|------|--|--------------|
| | Display sewing speed | S. | 0 | - | r/min | _ | 5. | | * | *** | | **** | Display the round per minute of running sewing machine. | - |
| | Down counter setting count amount | N. | 0 | 99 | - | 0 to 9999 | n. | | ** | *** | | **** | Setting the number of down counter. | - |
| | Down counter display count amount | D. | 0 | 99 | - | 0 to 9999 | d . | | * | *** | | **** | Display the number of current down counter. | - |
| | Up counter setting count amount | Ρ. | 0 | 99 | - | 0 to 9999 | P . | | * | *** | | **** | Setting the number of up counter. | - |
| | Up counter display count amount | U. | 0 | 0 | - | 0 to 9999 | U. | | ** | *** | | **** | Display the number of current up counter. | - |
| | Up counter the selection of setting mode | CUP. | 0 | CU | - | - | ٢ | U F | ? | | | | Selection of count up condition. | - |
| В | | | | | | | | | 1 | <u> </u> | - T | CU | After thread trimming is finished. | |
| mode | | | | | | | | | 5 | ; <u> </u> | - + | ST | The number of sewing stitch become "N" | ¬ |
| | | | | | | | | | | | 1 | | ("N" have to be set at "CNU") | |
| | | | | | | | | | F | - | | PR | The number of trimming times become "N" | |
| + | | | | | | | | | | | | | ("N" have to be set at "PRN") | |
| B | | | | | | | | | 1 | - n - | | IN | When output signal "O1" become ON. | [¬ |
| | | | | | | | | | | | 1 | | ("IO1" have to be set to input signal on the program mode C.) | |
| | | | | | | | | | 0 | - U | | ŌŪ | When output signal "O1" become ON. | [¬ |
| | | | | | | | | | | | | | ("O1" have to be set to output function on "O1" of the program mode C.) | |
| | Up counter the selection of counter operation | USC. | 0 | ST | - | - | U | 5 (| - | | 1 | | Selection of operation count over.(Up counter) | _ |
| | | | | | | | | | ĪS | ; <u> </u> | - + | ST | Control panel buzzes and running is prohibited after trimming with buzzer sound. And then when | [] |
| | | | | | | | | | | | 1 | | counter clear key "CCL" is pressed, sewing become possible. (Buzzer will stop after a while.) | |
| | | | | | | | | | | | i | | (Factory is possible to continue without buzzer sound.) | |
| | | | | | | | | | 0 | 5 F | — т | ŌF | Sewing is possible to continue without buzzer sound. | |
| | | | | | | | | | Ŀ | , <u> </u> | | BZ | Sewing is possible to continue with buzzer sound. | [] |
| | | | | | | | | | | _ | | | (Buzzer will stop after a while.) | |
| | Up counter changing | UCM. | 0 | OF | - | - | IJ | [[| 7 0 | , n | i | ON | When sewing pattern is changed, it clear "up counter". (UCM=ON) | - |
| | sewing pattern | | | | | | Ĺ | _ | o | , F | | OF | | |
| | Up counter valid/invalid | UPC. | 0 | OF | - | - | IJ | Ρ | <u>.</u> 0 |) n | I | ON | The up counter is valid. (UPC=ON) | - |
| | | | | | | | - | | 0 | , F | 1 | OF | | 1 |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | Function name Digit | tal d | | Settin | ig 1 1 | Specification | Ref. page |
|--------------|---|-----------------|-----------------|------|------------------|-------|---------------------------|--------------|-------------|------------|--------------|--|--------------|
| | Up counter operation NXU. after counting over | 0 | OF | - | - | n | 11 [| <i>U</i> . | | | | The UP counter operation, after counting over. (it is valid, when [USC] is set to "OF,"BZ".) | _ |
| | | | | | | | | 4 | | ר | _ ON | The display shows the setting number and the counting is stopped. | L |
| | | | | | | | | C | <u>, F</u> | | OF | The display shows setting number and the counting is continued. | - |
| | Down counter CDN. the selection of setting mode | 0 | CU | - | - | נ | d 1 | n . | | | l l | Selection of count condition. | - |
| | | | | | | | | [| <u>נ</u> ע_ | ; | CU | After thread trimming is finished. | [|
| | | | | | | | | 9 | 5 7 | • | ST | The number of sewing stitch become "N" | _ |
| | | | | | | | | | | | i i | ("N" have to be set at "CNU") | |
| | | | | | | | | - 1 | ρ | • | PR | The number of trimming times become "N" | |
| | | | | | | | | | | | i i | ("N" have to be set at "PRN") | |
| | | | | | | | | 1 | ō | | IN IN | When input signal "O1" become ON. | □ <u>-</u> - |
| B mode | | | | | | | | | | | | ("IO1" have to be set to input signal on the program mode C.) | L |
| | | | | | | | | C | o U | 1 | OU | When output signal "O1" become ON. | - |
| | | | | | | | | | | | i i | ("O1" have to be set to output function on "O1" of the program mode C.) | |
| + | Down counter DSC. | 0 | ST | - | - | ď | 5 (| <u>.</u> | | | 1 | Selection of operation at count over. (Down counter) | - |
| B | the selection of counter operation | | | | | _ | | | | | | | L |
| | | | | | | | | 4 | 5 ſ | • | ¦ ST | Control panel buzzes and running is prohibited after thread trimming with buzzer sound. And then | - |
| | | | | | | | | | | | l. | when counter clear key "CCL" is pressed, buzzer and sewing become possible. (Buzzer will stop | |
| | | | | | | | | | | | 1 | after a while.) | |
| | | | | | | | | | | | i | (Factory is setting of counter clear key is "P" key on control panel.) | L |
| | | | | | | | | 6 | <u>o_</u> f | | OF | Sewing is possible to continue without buzzer sound. | L |
| | | | | | | | | 12 | 5 E | | BZ | Sewing is possible to continue with buzzer sound. | - |
| | | | | | | | | | | | | (Buzzer will stop after a while.) | |
| | Down counter changing DCM. | 0 | OF | - | - | ď | E 1 | <u>n</u> 4 | חכ |) | i ON | When sewing pattern is changed, it clear "down counter". (DCM=ON) | - |
| | sewing pattern | | | | | | | 6 | <u>, F</u> | | OF | | |
| | Down counter DNC. | 0 | OF | - | - | ď | n l | <u>.</u> 9 | ה כ |) | ON | The down counter is valid. (DNC=ON) | - |
| | valid/invalid | | | | | | | 6 | 5 F | • | OF | | L |
| | Down counter operation NXD. | 0 | OF | - | - | n | - 11 - e | d . | | | I | The down counter action, after counting over. | - |
| | after counting over | | | | | | | L | | | । ↓ | (It is valid, when [DSC] is set to "OF", "BZ".) | L |
| | | | | | | | | 4 | 0_0 | | ON | The display shows "0" and the counting is stopped. | L |
| | | | | | | | | 6 | 5 F | | OF | The display shows "" and the counting is continued. | - |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | - | Functi nam D | ion ie igita | L | S play | etting | | Specification | Ref. page |
|--------------|--|-----------------|-----------------|----------|------------------|---|--------------------|--------------------|----|---------------|----------------|----|--|--------------|
| | Counter condition turning PCN on power switch | 1. O | OF | - | - | ρ | [| n, | | | | | When power switch is turned on, | - |
| | | | | | | | | | O | n | | ON | Up counter is clear (zero) and down counter is set the setting number. | |
| | | | | | | | | | 0 | F | | OF | Both counter keep previous amount. | |
| | Setting Thread trimming PRN times "N" | I. O | 0 | times | 0 to 99 | ρ | r | n | ** | | | ** | When "CUP" and "CDN" are PR, trimming times "N" is set. | - |
| mode | Setting Number of CNL stitches "N" | I. O | 1 | stitches | 1 to 99 | ٤ | n | U. | ** | | | ** | When "CUP" and "CDN" are ST, number of stitch "N" is set. | - |
| | Count modification CC | I. O | OF | - | - | E | Ľ | 1. | | | 1 | | Modification of count amount. | - |
| + SL | (to use IO1,IO2) | | | | | | | | o | n | | ON | When input function "IO1" is turn on, it become count up. When input function "IO2" is turn on, it become count down. (Input function can set input signal on program mode "C".) | - |
| | | | | | | | | | 0 | F | | OF | Modification is prohibited. | |
| | Display condition turning PMI on power switch |). O | OF | _ | - | P | Π | ď. | | | | | Selection display mode, when power switch is turned on. | - |
| | | | | | | | | | 0 | n | | ON | When power switch turn on, display shows previous condition. (Keep previous condition) | |
| | | | | | | | | | 0 | F | | OF | When power switch turn on, display shows normal mode. | |

| Mode name | Func | tion name | Oper ability | Factory setting | Unit | Setting range | Function name Digita | Setting | | Specification | Ref. page |
|--------------|-------------------------------------|-----------------------------------|-------------------------|----------------------------|---------------------------------|------------------|--------------------------------------|---------------------------|---|---|--------------|
| | Selection of inp signal function | Dut 1. to 7. A. to P | X | _ | _ | - | , l. , J. , R. , R. , P. | *** | ** The input functions of each signal 1' 1. Refer to the C mode input signal 2. Refer to the Conception figure of Caution Input signal I3 is not available. Set CPK to ON when using the Set CKK to ON when using the | 1 to I4 and IA to IP can be selected from 60 types of functions. setting table of the pages 126 to 131. input and output customization of the page 132 to 134. input signal I6. input signal IC. | - |
| | Tab | le of each input signal[IP] is [C | signal and CL] hey c | d connecto on control p | Caution r pin conn panel. | ection and fa | actory settin | g correspondenc | | (Option A connector) IA : PSU (Needle UP position priority stop signal) IB : PSD (Needle DOWN position priority stop signal) IC : S0 (Low speed run signal) IB | |
| C | Inp | ut signal | A IB | IC | ID | IE | | (Lever cor IG : S1 (Va | ector) able speed run signal) | | |
| | Facto | ory setting PS | SU PSI | D S0 | TL | S7 | | IH : S2 (Th | ead trimmer signal) | Al Al | |
| | | | | | | | | II : 53 (Pre | ser foot lifter signal) | | |
| | Inp | ut signal II | = IG | IH | | | | | | | |
| | Facto | bry setting F | - 51 | 52 | 53 | | | | | | |
| | | ut signal | 1 2 | 14 | 15 | 16 17 | 7 | E | | (Option B connector) | |
| | Facto | prv setting IC | 01 101 | I NO | NO | F BTL | - | | | I1: 101 (Signal output to virtual output 1) I2: 101 (Signal output to virtual output 1) | |
| | | , , | | | | | | | in | I4 : NO (No setting) | |
| | | | | | | | | | | I5 : NO (No setting) | |
| | | Cauti | on | | 7 | | | (0) | | I7 : BTL (Start/end tacking cancel signal) | |
| | Input s | ignals [14, 15, 16 | 6, 17] are o | dual port of | F | | | (Sewing mad | ine connector) | | |
| | input a | nd output. | ianale wi | ill be used | | | | $\overline{\bigcirc}$ | [4] IE : S7 (Backstitching during ru | n signal) | |
| | output | functions of O4, | 05, 06 a | nd O7 have | , à | | | <u> </u> | <u>Ö</u> | | |
| | to be s | et to "NO". | | | ID : T | L (Thread tri | mmer cance | el signal) 🚊 | | | |
| | | | | | _ | | | (4) | IF : F (Presser foot lifter signal) | (7) (8) (9) (7) (9) (1) (2) (1) (2) (1) (1) (2) (1) (2) (1) (1) (2) (1) (2) (1) (1) (2) (1) (2) (1) (2) (1) (1) (1) (1) (1) (1) (1) (1) (1) (1 | |
| | | | | | | | | | | lo | |
| | | | | | | | | | | | |

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| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | uncti nam D | ion e | L I disp | Set | tting | | Specification | Ref. page |
|--------------|---|-----------------|-----------------|--------------|------------------|-------------|------------------------------------|----------------------------|-------------|-------------|---|----------------|--|--------------|
| | Input signal logical changeover function I1L. to I7L. IAL. to IPL. | Х | OF | _ | - | ; ; ; | | L. L. L. | 0 | n F | | ON OF | The input logic of each Input signal I1 to I7 and IA to IP is reversed. Caution The function I3L is not available. Set CPK to ON when using the function I6L. | - |
| | Input signal alternating operation I4A. to I7A. IAA. to IPA. | X | OF | _ | _ | , , , | י. ק ק א ר | 2. R. R. R. R. | 0 | n F | | ON OF | If each input signal I4 to I7 and IA to IP performs OFF =>(1) ON=>OFF=>(2) ON=>OFF=>(3) ON=>OFF the signal will stay ON at (1),stop (turn OFF) at (2), and will turn ON again at (3). (iThis is hereafter referred to alternate operation.) Caution Set CPK to ON when using the function I6A. | - |
| C mode | Setting the function for I1 and I2 I1M. to I2M. | Х | AL | _ | _ | , | ۱ ح | <u>П.</u> П. | n | 0 [5 | | NO AL RS | The operation mode of each input signal I1 and I2 can be selected. Normal operation Alternating operation. RS F/F (Flip-Flop) operation. | |
| + | Special setting for input signal "I1" (Neglecting of signal) I1O. | 0 | OF | - | - | • | 1 | 0 . | 0 0 | n F | | ON OF | When sewing machine is running, input signal[11] is not accepted This function is valid, only [11M] set [AL] or [RS]. | - |
| ° | Special setting for input I1F. signal "I1" is ON | Х | OF | - | - | , | 1 | F. | 0 0 | n F | | ON OF | When [I1M] set [AL] on program mode "C", the alternate operation of input [I1] sets virtual output [OT3] to alternative output. | - |
| | RS F/F clear setting 11C. to 12C. | Х | OF | _ | _ | , | 2 | Е. Е. | 0 0 | n F | | ON OF | F/F (Flip Flop) operation of input signal [11] and [12] is cleared by thread trimming operation. | - |
| | RS F/F delay time setting 1CT. to 2CT. | 0 | 0 | x100 msec | 0 to 99 | ן 2 | ן ן נ | Г. Г. | ** | | | ** | When above setting (I1C,I2C) is valid, these delay timer is set. | - |
| | Input signal I1 virtual F1P. F/F circuit operation 1 | Х | OF | - | - | F | 1 | Р. | 0 0 | n F | | ON OF | The input signal I1 virtual F/F (flip-flop) operation is tuned ON when power is turned ON. It is only valid, when [I1M] function is set to "AL" or "RS". | - |
| | Input signal I1 virtual F/F F1C. circuit operation 2 | Х | OF | - | - | F | 1 | ٤. | 0 0 | n F | | ON OF | The input signal I1 virtual F/F (flip-flop) operation is turned OFF when the sewing start No. of stitches RLN setting is completed. | - |
| | Input signal I1 virtual F/F F1S. circuit operation 3 | Х | OF | - | - | F | 1 | 5. | 0 | n F | | ON OF | The input signal I1 virtual F/F (flip-flop) operation is turned ON when the tacking starts or after thread trimming. | - |

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| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | Functior name Digi | Setti al display | ng ⊣ | Specification | Ref. page |
|---------------------|---|-----------------|-----------------|----------|------------------|---|---|---|---|--------------|
| | Set condition of RS F/F for I1 and I2 R1S. to R2S. | X | IN | _ | _ | r r 2 | 5. 7. 7. 5. 7. 5. 7. 5. 5. 5. 5. 5. 5. 5. 5. 5. 5 | | Set condition RS F/F of I1 and I2 When [I1M] and [I2M] is set to [RS], it is valid. RS F/F of I1 is set by I1, RS F/F of I2 is set by I2. After thread trimming operation (stop to up position.) When motor start, RS F/F will be set. When motor stop, RS F/F will be set. When sewing start, after thread trimming. When start tacking or condensed stitch was finished. (When condensed stitch is not set, it is invalid) | |
| C mode ↓ + | Reset condition of RS F/F for I1 and I2 R1R. to R2R. | X | IN | _ | _ | r . r 2 . | r. | | Reset condition RS F/F of I1 and I2 When [I1M] and [I2M] is set to [RS], it is valid. RS F/F of I1 is reset by I6, RS F/F of I2 is reset by 17. When thread trimming is done (stop to up position.) When motor start, RS F/F will be reset. When motor stop, RS F/F will be reset. When sewing start, after trimming. When start condensed stitch was finished. (When condensed stitch is not set, it is invalid.) When sewing machine sew the setting stitch after set RS F/F, it will be reset. (R1N, R2N) | |
| | RS F/F reset stitch amount for I1 and I2 R1N. to R2N. Selection of output signal function OA. to OD. OF. O1. to O7. OJ. to OK. | O X | * | Stitches | 0 to 99 | r r 2 o R o d o F o l o l o l o l | n. ** *** | | When [R1R] or [R2] set [NC], the number of stitch is set by this counter. The output functions of each output signal OA to OD,OF,OJ to OK and O1 to O7 can be selected from 37 types of functions. 1. Refer to the C mode input signal setting table of the pages I68 to I71. 2. Refer to the Conception figure of input and output customization of the page I74 to I76. Caution Output signal OE is not available. Set CPK to ON when using the function O6. | _ |



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| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | Function name – – – – – Digita | Setti | ing ¬ | Specification | Ref. page |
|----------------|--|-----------------|-----------------|-------------|------------------|--|------------|---|---|--------------|
| | Output signal logical changeover function OJL. to OKL. OOL. to OPL. | Х | OF | _ | _ | 0 J L. 0 L L. 0 0 L. 1 J 0 P L. | 0 n 0 F | ON OF | The output logic of each output signal OJ to OK, and OO to OP is reversed. | - |
| C mode ↓ | Output chopping function OAC. to ODC. O1C. to O3C. | X | OF | _ | _ | 0 | | ON OF | Each output is output with full wave immediately after output starts, and then is reduced to half-wave output for each output signal OA to OD and O1 to O3. (Chopping control) The full wave output time can be set with the full wave time [PO] function for each output. Caution Output signal [O4, O5, O6, O7] are chopping function is not available. | - |
| + | OFF function OFF function OIT. to ODT. OJT. to OTT. OJT. to OKT. OOT. to OPT. | X | OF | _ | _ | 0 H I. 0 d F. 0 l F. 0 l F. 0 l F. 0 l F. 0 l F. 0 P F. | o F | ON OF 1 1 1 1 1 1 1 1 1 1 1 1 1 | In each output signal OA to OD, OJ to OK, OO to OP and O1 to O7, each output is forcibly turned OFF after the time set in the OFF timer is passed. The OFF timer set time can be set with each output's forced OFF timer [OTT] function. | _ |
| | Output signal delay time setting function DA. to DD. DF. | X | 0 | x20 msec | 0 to 08 | d R. 1 d d. d F. | *** | *** | In each output signal OA to OD and OF the delay time to when each output is started can be set. Each delay time can be set in 20ms intervals. | - |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | Func nan [| ction me Digital | Settin display | g 1 | Specification | Ref. page |
|--------------|--|-----------------|-----------------|-------------|------------------|--|------------------------|--|---|---|--------------|
| | Output signal delay time setting function D1. to D7. DJ. to DK. DO. to DP. | X | D1=10 | msec | 0 to 510 | d 1 d 7, d 0 d E d 0 d 2 d 0 | /. 7. /. | *** | *** | In each output signal OJ to OK, OO to OP and O1 to O7, the delay time to when each output is started can be set. Each delay time can be set in 2 ms intervals. | |
| C mode | Presser foot lifter output FUD. chopping duty | X | MF | _ | _ | FU | i d. | N 5 N F H ' F L | + | The chopping output duty during holding after the presser foot lifter output FU lifting operation can be set. Set to [MS] : 4 ms ON/OFF 50 %duty Set to [MF] : 2 ms ON/OFF 50 %duty Set to [HI] : 4 ms ON, 2 ms OFF, 66 %duty Set to [FL] : 100 % (full wave) Set to [I Q] : 2 ms ON 4 ms OFF 33 %duty | |
| | Presser foot lifter FU full FO. wave output time | X | 50 | x10 msec | _ | Fo | 7. | 2 0 2 5 3 0 4 0 5 0 6 0 8 0 1 0 0 | $\begin{array}{c} 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 2 \\ 1 \\ 1 \\ 2 \\ 1 \\ 1$ | Set to [20]: 2 Ins ON,4 Ins OFF 33 700tly The full wave output time of the presser foot lifter output FU can be set. Set to [20]: 200 ms Set to [25]: 250 ms Set to [30]: 300 ms Set to [30]: 300 ms Set to [50]: 500 ms Set to [60]: 600 ms Set to [80]: 800 ms Set to [100]: 1000 ms | |
| | Presser foot lifter FU FU. momentary mode | X | M | _ | _ | FU | J. | n C | | The operation mode of presser foot lifter momentary FUM is set. This is valid when presser foot lifter momentary FUM is set to [ON] in the P mode. The presser foot lifter operation is continued after full heeling or after thread trimmer with external thread trimmer signal S2. The presser foot lifter operation is continued during the timer time after full heeling or after thread trimming with external thread trimmer signal S2. Then the presser foot lifter is lowered. The timer can be adjusted with timer setting FCT in the P mode. | |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | Function name Die | on e igital (| Se display | etting | | Specification | Ref. page |
|--------------|--|-----------------|-----------------|-------------|------------------|-------------------------|---------------------|--|--------------------------|--|---|--------------|
| | Presser foot lifter FU FU momentary mode | X | М | _ | - | FU. | - | R | | A T | The presser foot lifter operates with full heeling or when the external signal (S2, F) turns ON, and then the presser foot lifter. Lower when full heeling, light heeling or external signal (S2,F) turns on. The presser foot lifter will rise if these signal is turned ON again. (Alternate operation) The timer operates in the same manner as [C] setting. However, after the presser foot lifter lowers, the operation will be alternate as with the [A] setting. | |
| C mode | Full wave output time PO for each output | 0 | 50 | x10 msec | _ | Ρο. | | 2 2 3 9 9 0 0 0 0 0 0 0 0 0 | | 20 25_ 30 40 50 60 80 100 | The full wave output time of each output signal OA to OD and O1 to O7 can be set. Set to [20]: 200 ms Set to [25]: 250 ms Set to [30]: 300 ms Set to [40]: 400 ms Set to [50]: 500 ms Set to [60]: 600 ms Set to [80]: 800 ms Set to [100]: 1000 ms | |
| + | Output chopping duty POD except of FU output | 0 | MF | _ | _ | Ρο | ď. | <u>N</u> 5 NF H , | | MS MF HI LO | Setting output chopping duty, except FU output. Set to [MS] : 4ms ON/OFF 50%. Set to [MF] : 2ms ON/OFF 50%. Set to [HI] : 4ms ON, 2ms OFF, 66% duty. Set to [LO] : 2ms ON, 4ms OFF, 33% duty. | |
| | Forced OFF timer setting OTT function for each output | 0 | 12 | sec | 1 to 24 | οΓ | Г. | | ** | ** | The timer that forcibly turns off output signals OA to OD and O1 to O7 can be set. | - |
| | FUM operation mode FCT timer setting function | 0 | 12 | sec | 1 to 99 | F [| ſ. | | ** | ** | The timer from the time when the presser foot lifter output is turned ON to the time when it is turned OFF. (when FUM operation mode FU [C] or[T] is set can be set.) | - |
| | Logic [AND] input/selecting AN input function | X | NO | _ | _ | Я п. | | | *** | *** | Select input function to the logic input [AND]. Input function is select on "Input/output function for signal on C mode setting" (pages 126 to 131) Refer to " The composition figure of input and output customization" about [AND] setting. (Pages 132 to 134) | _ |
| | Logic[AND] input setting ANL Hi / Low logic | X | OF | _ | _ | R n | ٤. | o n o f | | ON OF | [AND] input logic is set to opposite Refer to "The composition figure of input and output customization" about [AND] setting. (Pages 132 to 134) | - |
| | Logic[AND] input ANA Alternate | X | OF | _ | - | R n | R. | 0 n 0 F | | ON OF | [AND] input is set to alternative. Refer to "The composition figure of input and output customization" about [AND] setting. (Pages 132 to 134) | - |

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| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | - F | Functi nam Di | on e igital | disp | Se olay | etting |] | Specification | Ref. page |
|--------------|---|-----------------|-----------------|------|------------------|--------|--------------------------|-------------------|--------|------------|----------------|----------|---|--------------|
| | Logic [AND 1/2/3] output selecting output function N1. to N3. | х | HI | _ | - | n n | ; . ; 3. | | *** | | | *** | Select output function of [AND 1/2/3] Refer to "The composition figure of input and output customization" about [AND] setting. (Pages 132 to 134) | - |
| | Logic [AND 1/2/3] output setting of Hi/Low logic N1L. to N3L. | х | OF | _ | - | n | 3 | L. L. | 0 0 | n F | | ON OF | [AND 1/2/3] output logic is set to opposite Refer to "The composition figure of input and output customization" about [AND] setting. (Pages 132 to 134) | - |
| | Logic[OR] input selecting input function OR. | Х | NO | _ | _ | 0 | r. | | *** | | | *** | Select input function to logic input [OR] Input function is select on "Input/output function for signal on C mode setting" (pages 126 to 131) Refer to "The composition figure of input and output customization" about [OR] setting. (Pages 132 to 134) | - |
| C | Logic [OR] input setting of Hi/Low logic ORL. | Х | OF | _ | - | 0 | r | L. | 0 0 | n F | | ON OF | [OR] input logic is set to opposite. Refer to "The composition figure of input and output customization" about [OR] setting. (Pages 132 to 134) | _ |
| ↓ + | Logic[OR] input Alternate ORA. | Х | OF | _ | - | 0 | r | R. | 0 0 | n F | | ON OF | [OR] input logic is set to Alternate. Refer to "The composition figure of input and output customization" about [OR] setting. (Pages 132 to 134) | - |
| | Logic [OR 1/2/3] output selecting output function R1. to R3. | Х | NO | _ | - | r r | , I. , . , 3. | | | | | *** | Select output function of [OR 1/2/3] Refer to "The composition figure of input and output customization" about [OR] setting. (Pages 132 to 134) | - |
| | Logic[OR 1/2/3] output setting of Hi/Low logic R1L. to R3L. | Х | OF | - | - | r r | ; ; 3 | L. L. | 0 0 | n F | | ON OF | [OR 1/2/3] output logic is set to opposite. Refer to "The composition figure of input and output customization" about [OR] setting. (Pages 132 to 134) | - |
| | Variable speed command for digital input CSP. | Х | OF | - | - | 2 | 5 | Р. | 0 0 | n F | | ON OF | Set variable speed command for digital input. (I1, I2, I6, I7) High speed is set to [H] on program mode "P". (CSP=ON.CSG=OFF) | - |
| | Variable speed command for digital input (Grav code) CSG. | Х | OF | _ | - | נ | 5 | Б. | 0 0 | n F | | ON OF | Set variable speed command for digital input. (I1, I2, I6, I7) High speed is set to [H] on program mode "P". To use grav code. (3, 2, 1, 0)= (I6, I7, I2, I1), (CSP=ON, CSG=ON) | - |
| | Thread release + backstitch output LB. | 0 | OF | - | - | L | b . | | 0 0 | n F | | ON OF | Thread release output L will turn ON even while backstitch output B is ON. | _ |
| | Virtual output (OT1 to OT3) forced OFF function T1C. to T3C. | 0 | OF | _ | - | ר ר | 3 | ۲. ۲. | 0 0 | n F | | ON OF | Virtual outputs OT1 to OT3 will be turned OFF forcibly after the OFF timer set time has passed. The OFF timer set time can be set with the virtual output OFF timer setting function [T1T to T3T]. | _ |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | Functi nam D | ion e igital | l disp | Settin | g | Specification | Ref. page |
|--------------|---|-----------------|-----------------|-------------|------------------|--------|--------------------|------------------------|--------|------------|----------|---|--------------|
| | Forced OFF timer setting function for virtual outputs (OT1 to OT3) T1T. to T3T. | 0 | 99 | x10 msec | 0 to 99 | ר ר | 3 | Г. Г. | ** | | ** | The timer time for forcibly turning OFF virtual outputs OT1 to OT3 can be set. | - |
| | Feed pulse output (CP) CPK. cancel function | 0 | ON | - | - | ٤ | Ρ | £. | 0 0 | n F | ON OF | Feed pulse [CP] is invalid. When feed pulse will be used, set this function to "CF" This signal output is from the same pin of "I6" and "O6". | - |
| | Setting CP pulse amount CP. | 0 | 32 | - | 1 to 99 | Ľ | Ρ. | | ** | | ** | Setting the number of pulse [CP]. After changing this number, turn on power switch again. | - |
| C mode | Prohibited angle of CPC. output CP pulse | 0 | OF | - | - | ٤ | Ρ | ξ. | 0 0 | n F | ON OF | The prohibited angle section of pulse generated can be set from UP position. The prohibited angle of pulse generated is 60 degree from the setting position (angle). | - |
| + | Panel switch PSW. operation prohibit | 0 | OF | - | - | | | | 0 0 | n F | ON OF | Panel switch operation ([M], [A,1-2], [B,SL], [C,<= =]. [D,= =>] key operations) during the normal mode, tacking mode and pattern mode will not be possible. However, changeover into each mode will be possible. | - |
| | CKD output cancel CKB. during backtack trem | 0 | OF | - | - | 2 | | Ь. | 0 0 | n F | ON OF | Output signal "CKD" is prohibited during backtack term. | - |
| | CP output cancel during CPB. backtack term | 0 | OF | - | - | 2 | ρ | Ь. | 0 0 | n F | ON OF | Output signal "CP" is prohibited during backtack term. | - |
| | CKD output cancel CKK. | 0 | ON | - | - | 2 | Ł | Ł. | 0 0 | n F | ON OF | Output signal "CKD" is prohibited. | - |
| | F key function CNF. on control panel | 0 | SE | - | - | ٢ | n | F. | | | | Selection F key function. | - |
| | | | | | | | | | U | ρ | UP | Display Up counter amount | |
| | | | | | | | | | ď | <u>n</u> | DN | Display Down counter amount | |
| | | | | | | | | | 5_ | <u> </u> | SE | Display stitch amount of sensor | L |
| | | | | | | | | | 5 | ρ | SP | Display routine speed of sewing machine. | - |



| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | Function name Digital c | | Setting | | | Specification | Ref. page |
|--------------|--|--|---------------------------|-------------------------------|--------------------|--------|-------------------------------|-----------|---------|------------|--|--|--------------|
| | Operation mode during D2. start tack completion | 0 | CON | - | _ | ď | 2 . | | 1 | | | The operation mode during the completion of start tack is determined. | - |
| | | | | | | | | ר <u></u> | 0 | | | If the pedal is toed down or the external run signals (S0, S1) are ON when start tacking is completed, the next straight line stitching will begin. | |
| | | | | | | | | 5 | ſ | - P | STP | Even if the pedal is toed down or the external run signals (S1) turned ON when start tacking is completed, the sewing machine will stop. | |
| | | | | | | | | | | | | The next straight line stitching will start when the pedal is toed down for neutral again, or when the external run signals (S1) is turned OFE to ON | |
| | | | | | | | | f | - r | - <u>-</u> | TRM | The thread is trimmed when start tacking is completed. This is used for continuous tack stitch. | |
| D mode | Stop time at each corner CT. during start and backtacking | 0 | 5 | x10 msec | 0 to 99 | 2 | ſ. | ** | | | ** | The stop time at each corner during tacking can be set when [CST] in operation mode D1 is set.[CSU], [CSD] | - |
| \bigcup | Tack alignment BM. | 0 | OF | - | - | ь | N. | | | | | The backstitch solenoid operation timing can be set to align the tacking. | - |
| + | | | | | | | | 0 | 'n | | + | Set to [ON] : Tacking speed less than 1000 rotations. | |
| | If the operation mode during tacking alignment functions | Caution g D1 is set t , BT2, BT3 a | ti [CST], [(Ind BT4 w | CSU] and [(ill be invalid | CSD <u>:</u> I. |], the | 0 | F | | OF | Set to [OFF] : Tacking speed 1000 rotations or more. | _ | |
| | No. of stitch compensation BT1. | 0 | С | - | 0 to F | ь | ſ | * | | | * | By finely adjusting the backstitch solenoid operation timing of start tacking from forward to reverse, | - |
| | for start tacking alignment | | | | | | | | | | 1 | the no. of stitches can be compensated. The relation of the setting value and no. of stitch compensation is as shown below. | |
| | No. of stitch compensation BT2. for start tacking alignment | 0 | 2 | - | 0 to F | ь | r 2. | • | | | * | By finely adjusting the backstitch solenoid operation timing of start tacking from forward to reverse, the no. of stitches can be compensated. | - |
| | No. of atitab companyation PT2 | | 5 | | 0 to E | | <u> </u> | * | | | | The relation of the setting value and no. of stitch compensation is as shown below. | |
| | for start tacking alignment | | 5 | | | Ø | í J. | • | | | | the no. of stitches can be compensated. | |
| | | | | | | | | | | | I | I ne relation of the setting value and no. of stitch compensation is as shown below. | |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | | Functi nam | on e igital | S display | Setting | | | | | Specific | ation | | | | Ref. page |
|--------------|--|-----------------|-------------------------------|-------------------------|-----------------------------|-----------|---------------|-------------------|--------------|----------------|---------|---|--|--------------------------------|---------------------------------|-------------------------------------|----------------------------------|-----------------------------------|----------------------|--------------|
| | No. of stitch compensation BT4. for end tacking alignment | 0 | 0 | _ | 0 to F | Ь | ٢ | Ч. | | | * | By finely adju the no. of stito is as shown | usting the ba ches can be c below. | ckstitch soler compensated. | noid operatio The relation o | n timing of en of the setting va | d tacking from alue and no. o | m forward to 1 of stitch compe | reverse, ensation | _ |
| | Start | | •==== | End | | | | | Relatio | on of no | o. of c | compensated | d stitches ar | nd setting va | lue | | | | | |
| | BT1 | BT2 | BT3 | • | BT4 | | | Se | etting valu | ue | | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | |
| | | | Τ | <u> </u> | | | | No | o. of com | pensate | d | -2,1/4 | -2 | -1,3/4 | -1,2/4 | -1,1/4 | -1 | -3/4 | -2/4 | |
| | | | | × . | | | | Se | etting valu | ue | | 1 | 0 | А | В | С | D | E | F | |
| | | | | | | | | No | o. of com | pensate | d | -1/4 | 0 | +1/4 | +2/4 | +3/4 | +1 | +1,1/4 | +1,2/4 | 4 |
| | | | | | | | | | | | | | | - | | | | | | — |
| | | | | | | | L | | | 1 | | | | | | | | | | |
| D | | | | | | Ц | | | | 1 | | | | | | | | | | |
| mode | | Cau | tion | | | | | | | 1 | | | | | | | | | | |
| | If the operation mode during the tacking alignment fund | tacking | D1 is set to [M. BT1. BT2 | CST], [CS 2. BT3 and | U] and [CSD d BT4 will b |], e | | | | Ì | | | | | | | | | | |
| + | invalid. | | , 21., 21. | -, D i o ain | | | | | | | | | | | | | | | | |
| | | | | | | | | | | 1 | | | | | | | | | | |
| | | | | | | | | | | į | | | | | | | | | | |
| | No of tool ing atitabas (1) DTD | 0 | 05 | | | | ſ | 0 | 0 0 | 1 | | 15 offitables o | ro oddod to t | he est No. of | atort and an | d to olving ofito | haa | | | |
| | 15 stitches function | 0 | OF | _ | _ | 0 | í | r . | o F | 1 | | For example | if the set No | ne sel NO. O | na stitches is | A stitches the | nes. Nactual No. o | of start tacking | stitches | _ |
| | | | | | | | | | . | Ì | 01 | will be 19 stit | ches (4+15) | | ng stiteries is | - 50101105, 010 | , actual 140. 0 | n start taotting | 30101103 | |
| | | | | | | | | | | 1 | | | | | | | | | | |
| | No. of tacking stitches BTO. | 0 | 0 | _ | 0 to 99 | Ь | ٢ | 0 . | | | ** | [BTO] setting | g stitches are | added to the | set No. of st | art and end ta | acking stitche | es. | | _ |
| | addition stitches function | | | | | | | | | i | | For example | , if the set No | . of start tacki | ng stitches is | 4 stitches and | l [BTO] settin | ng value is 20 | stitches, | |
| | | | | | | | | | | 1 | | the actual No | o. of start tac | king stitches | will be 24 stit | ches (4+20). | | | | |
| | | | | | | | | | | 1 | | | | | | | | | | |
| | Full heeling function BTT. | 0 | ON | - | - | Ь | ſ | Γ. | | į | ON | If full heeling | is performed | d immediately | / after start ta | acking stops, e | end tacking v | will not be per | formed, | - |
| | immediately | | | | | | | | 0 7 | 1 | OF | and the sewi | ing machine | will stop after | thread trimm | ning. | | | | |
| | | | OF | | | r | <i>c</i> | | 0 0 | <u> </u> | | ON The sour | ing maching | temporarily d | tone immedia | ately before or | d tacking stit | ch (Regardled | es of the | |
| | immediately before | | UF | _ | | L | כ | U. | | i i | OF | position the | sewing machine | hine stops at | DOWN none | atery Derore er | iu launii iy siil | un (negarule: | | |
| | end tacking stitch | | | | | | | | | I I | 5. | Stop time ca | n be adjuste | d with the fun | ction of stop | time CT. | | | | |
| | | | | | | | | | | | | 2.50 00 | | | | | | | | |

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| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | unction | n | | Setti | ng | Specification | Ref. page |
|--------------|-------------------------------|-----------------|-----------------|------|------------------|-------|---------|---------|------------------|-------|-----------------------------|--|--------------|
| | | | | | | | Dig | jital c | displa | ау | I | | |
| | The speed operation SP | N. 0 | OF | - | - | 5 | ρ | n. | | | 1 | When both the medium speed signal (medium speed run signal S5, medium speed command | - |
| | mode when both | | | | | | | | | | i | signal SPM) and the end tacking speed run signal S5 V is ON, the speed operation mode can be set. | |
| | the medium speed | | | | | | | | | | 1 | | |
| | signal and S5 V signal is ON. | | | | | | | | | | | | |
| | | | | | | | | P | 0 | n | ON | If both the medium speed signal (S5, SPM) and the end tacking speed run signal (S5 V) is ON, the | - |
| | | | | | | | | | | | | speed will be the end tacking speed N. | |
| | | | | | | | | | 0 | F | + 1 OF | If both the medium speed signal (S5, SPM) and the end tacking speed run signal (S5 V) is ON, the | |
| | | | | | | | | | | | l l | speed will be the end tacking speed V. | |
| D | Settable types of tacking BT | M. O | 6 | _ | 1 to 7 | Ь | ٢ | ſI. | | | | Determine the type of tacking that can be set with the front and end tacking type ([B], [D] keys) in the | _ |
| mode | | | | | | | | | | | 1 | tacking setting mode with setting values 1 to 7. | |
| | | | | | | | | - | - , - | | + | | |
| + | | | | | | | | + | 5 | | <u> </u> '_ | | |
| | | | | | | | | ť | <u>c</u> 5 | | + | | |
| | | | | | | | | ŀ | <u>-</u> ע | | $\frac{1}{1} - \frac{3}{4}$ | | |
| | | | | | | | | | <u>-</u> | | + | | |
| | | | | | | | | ŀ | <u>כ</u> | | <u> </u> | | |
| | | | | | | | | | <u>0</u> | | + | | |
| | Input signal S7 operation S7 | W 0 | 05 | | | r | 0 | 0 | <u>'</u> | 0 | | If the backetitch related inputs are turned ON during procest stitching, the backstitch selencid will turn | |
| | mode during preset | vi. O | | _ | _ | כן | 1 | 11. | ~ | ç | | | _ |
| | stitching | | | | | | | | U | , | | | |
| | Manual backstitch S7 | U. O | OF | _ | - | 5 | 7 | U. | 0 | n | ON | The backstitch solenoid drive timing by the backstitch signal S7 is synchronized with the UP position. | _ |
| | ON timing 1 | | | | | | | | 0 | F | OF | (When this function setting is [OF] setting, it will be synchronized with the random position.) | |
| | Manual backstitch S7 | D. O | OF | - | - | 5 | 7 | ď. | 0 | n | ON | The backstitch solenoid drive timing by the backstitch signal S7 is synchronized with the DOWN | |
| | ON timing 2 | | | | | - | | | 0 | F | , OF | position. | |
| | | | | | | | | | | | 1 | (When this function setting is [OF] setting, it will be synchronized with the random position.) | |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | | unctio | on e | displ | Settir | ng T | Specification | Ref. page |
|--------------|--|-----------------|-----------------|------|------------------|---|--------|---------|----------|--------------|------------------|--|--------------|
| | The OFF timing setting 7BD. of output B when the backstitching signal (S7) is OFF setting. | 0 | OF | - | _ | 7 | Ь | d. | 0 0 | n F | ON OF | When the manual backstitching signal (S7) is OFF setting, the OFF timing of the backstitching output B will be synchronized with the UP position. (When this function setting is [OF] setting, it will be synchronized with the DOWN position.) | _ |
| | The maximum BTN. tacking stitches | 0 | OF | - | - | ь | ٢ | n. | | | | The maximum tacking stitches can be set. | - |
| | (maximum stitches is 99 stitches) | | | | | | | - | o | | + | The No. of maximum tacking stitches will be 99 stitches. The No. of start and end tacking stitches will be the same stitches, the No. of start and end tacking stitches A and D can be set by the 2 figures of [A] and [B] of the operation panel, and the No. of start and end tacking stitches B and C can be set by the 2 figures of [C] and [D] of the operation panel. | |
| | | | | | | | | | 0 | F | | The No. of maximum tacking stitches is 15 stitches. | - |
| D mode | No. of end tacking BCC. stitches during direct heeling | 0 | OF | - | _ | Ь | [| £. | 0 0 | n F | ON OF | The No. of end tacking stitches with direct heeling will be the No. of stitches C + 1 stitch when operation mode D1 is set to [D] [M] during tacking. | _ |
| + | Operation mode during. TLS. thread trimmer cancel signal [TL] setting | 0 | OF | - | - | ٢ | L | 5. | 0 0 | n F | ON OF | The operation mode for when the thread trimmer cancel signal (TL) is input will be set. | - |
| | Input signal BTL BTS. guick pressing operation | 0 | ON | - | - | ь | ٢ | 5. | | | | The tacking cancel signal [BLT] operation is set. | - |
| | | | | | | | | - | 0 | n – – | + ON | Tacking is prohibited while the tacking cancel signal [BTL] is ON. | |
| | | | | | | | | - | 0 | F | + OF | The tacking operation is prohibited once after quick pressing (OFF-ON-OFF) of the tacking cancel signal [BTL]. | |
| | Input signal SB and EB BS. guick pressing operation | 0 | OF | - | - | Ь | 5. | | | | 1 | The start and end tacking cancel signals SE and EB operations are set. | - |
| | | | | | | | | | 0 | <u>n</u> | + | The start tacking operation is prohibited while the start tacking cancel signal SE is ON. (Same for end tacking cancel signal EB.) | |
| | | | | | | | | | 0 | F | - ON | The start tacking operation is prohibited once after quick pressing (OFF-ON-OFF) of the start tacking signal SE. (Same for end tacking cancel signal EB.) | |

| Mode name | Function name | | Oper ability | Factory setting | Unit | Setting range | _ F | ⁻ unctic name Diç | on ; gital c | displa | Settir ay | g 1 | Specification | Ref. page |
|----------------|---|-----|-----------------|-----------------|------|------------------|-----|--|--------------------|--------|------------------|--------------|--|--------------|
| | Operation when input B signal BTL is ON | TD. | 0 | ON | - | - | Ь | ſ | d . | 0 | n F | I ON I OF | When the tacking is set to OFF, if tacking cancel signal (BTL) turns ON, the tacking will be permitted. (When this function is set to OFF, the tacking will be prohibited.) | - |
| D mode ↓ | Operation when input signal SB and EB tacking OFF are set | BD. | 0 | OF | _ | _ | Ь | ď. | 4 | 0 | n F | | If the start tacking validity ([A] key) is set to OFF (-) in the tacking setting mode, start tacking can be validated by turning the start tacking cancel signal SE ON. (Same for end tacking cancel signal EB.) | - |
| + | End tacking Pl cancel mode with input signal PSU | NE. | 0 | OF | _ | _ | ρ | n | E . | 0 | n F | | When end tacking is set, if the needle UP position priority stop signal PSU turns ON during operation, the end tacking will not be executed after stopping at the needle UP position. After thread trimming, the presser foot will lift. | _ |
| | The buzzer of control panel validity | BZ. | 0 | ON | _ | - | Ь | Ξ. | 4 | 0 0 | n F | | The buzzer of control panel will be validate. | - |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | Function name Digita | Settin | ig 1 | | Specification | Ref. page |
|----------------|---|-----------------|-----------------|--------------|------------------|--------------------------------|--------|------------------|-----------------|---|--------------|
| E mode ↓ | Error code didplay 1. to 4 (Once ahead) to (Four times ahead) | 0 | E | - | _ | l. | £ | E | ≣ | Error codes of once ahead to four times ahead are displayed. For details of error code, refer to [24. Error Display]. Data can be cleared by simultaneously pressing ([A, 1-2] + [D,==>]) keys. | _ |
| + | Total integration time P of power on | 0 | 0 | x10 hours | 0 to 9999 | Р. | **** | ** | **** - | Total integration time of power on is displayed. Data can be cleared by simultaneously pressing ([A, 1-2] + [D,==>]) keys. | _ |
| A 1-2 | Total integration time M of motor run | 0 | 0 | x10 hours | 0 to 9999 | ſĨ. | **** | *' | **** - | Total integration time of motor run is displayed. Data can be cleared by simultaneously pressing ([A, 1-2] + [D,==>]) keys. | _ |

| Mode name | e Function name C al | | Oper ability | Factory setting | Unit | Setting range | Function name – – – – – Digital | L | Sett | ing ㄱ ╷ | Specification | Ref. page |
|--------------|---|--------------------------|-------------------|-----------------|------------|------------------|--|------------|--------------------------|---------------|--|--------------|
| | Input display | IA. to IP. I1. to I7. | 0 | _ | - | - | , R. , P. , I. , I. , J. | o r o f | ר - | ON OF | The input status (ON/OFF) of the input signal IA to IP and I1 to I7. | - |
| E mode | | C Correspondence of t | aution he disp | lay and inp | but signal | - | | | • | | | |
| \downarrow | | (Factory set | tting) | | | _ | | | 6 |) ③ | | |
| + | + Pedal toe down (S1) IG Sewing machine connector | | | | | | | | Sewing machine connector | | | |
| \square | | Pedal full he | eeling | (S2) | IH | | | Lever | conr | lector | | |
| | | Pedal light he | eeling | (S3) | П | | | | | | | |
| + | | Presser foot lifter s | signal | (F) | IF | | | | | | | |
| A 1-2 | | Input | signal | (TL) | ID | | | | | | | |
| | | Backstitching | signal | (S7) | IE | | | | | | | |
| | | Input | signal | (PSU) | IA | | | | | | | |
| | | Input | signal | (PSD) | IB | | | | | | | |
| | | Input | signal | (S0) | IC | | | _ | ,IB | | | |
| | | Reserved input s | signal | (IO1) | l1 | | | | | 1 | | |
| | | Reserved input s | signal | (U) | 12 | | | | (0 | | | |
| | | Reserved input s | signal | (NO) | 14 | | | | | <u> </u> | | |
| | | Reserved input s | signal | (NO) | 15 | | | | \perp | | | |
| | | Presser foot lifter s | signal | (F) | 16 | | | | | | I6 <u> </u> | |
| | | Reserved input s | signal | (NO) | 17 | | | Opt | tion | A connec | tor Option B connector | |
| | | | | | | | | | | 1 | | |

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| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | ⁻ unctic name Diç | on 2 gital d | lispl | Set ay | ting – | | Specification | Ref. page |
|--------------|--|-----------------|-----------------|--------------|------------------|-------|--|--------------------|--------|---------------|-----------|----------|---|--------------|
| | Encoder signal display ECA. (A phase) | 0 | _ | - | _ | ε | [| <i>R</i> . (| 0 0 | n F | | ON OF | The input status (ON/OFF) of the motor encoder A phase is displayed. | - |
| F | Encoder signal display ECB. (B phase) | 0 | - | - | - | E | Ľ | <i>b</i> . С | 0 | n F | 1 | ON OF | The input status (ON/OFF) of the motor encoder B phase is displayed. | - |
| mode | Detector signal display UP. (UP signal) | 0 | - | - | - | U | Р. | 6 | כ כ | n F | 1 | ON OF | The input status (ON/OFF) of the detector UP signal is displayed. | - |
| + | Detector signal display DN. (DOWN signal) | 0 | - | - | - | d | n. | | כ כ | n F | | ON OF | The input status (ON/OFF) of the detector DN signal is displayed. | - |
| | Display the angle DR. from down position | 0 | - | x2 Degree | 0 to 180 | ď | r . | | כ כ | n F | | ON OF | Display the angle of current position from down position. | - |
| A 1-2 | Display the voltage of VC1 PD. | 0 | - | _ | 0 to 3FF | ρ | d . | * | ** | | | *** | The numerical value that is equivalent to the variable speed voltage VC with the pedal toe down is displayed. Display range : 000 to 3FF | - |
| | Display the voltage of VC2 VC. | 0 | _ | - | 0 to 3FF | U | ξ. | * | ** | | | *** | The numerical value that is equivalent to the variable speed voltage VC with the option B connector is displayed. Display range : 000 to 3FF | - |





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| Mode name | Function name | | Oper ability | Factory setting | Unit | Setting range | F1 | unction name Digital | Settin display | ng 1 | Specification | Ref. page |
|--------------|---|-----|-----------------|-----------------|------|------------------|----|----------------------------|-------------------|---|--|-----------------------|
| | Rated output display | WT. | 0 | 55 | Watt | - | B | ſ. | | | The motor's rated output value is displayed. | - |
| | | | | | | | | | 5 5 7 5 | <u> </u> <u> </u> _ <u>5</u> 5_ 75 | [05] refers to 550 W | ⁻ - |
| E mode | Voltage display | VL. | 0 | 100 | Volt | _ | U | L. | | | The rated input voltage value in the control box is displayed. | - |
| \downarrow | | | | | | | | | 1_0_0 2_0_0 | 1 - 100 1 - 100 1 - 200 | [100] refers to 100 V class. [200] refers to 200 V class. | |
| + | Model display | TP. | 0 | MF | - | - | ſ | Р. | | | The control box model name is displayed. | - |
| + | | | | | | | | | n N F | <u> </u> <u>N</u> <u>N</u> | Not used. SC-380 | |
| 1-2 | Data version No. | DV. | 0 | *** | - | - | d | U. | *** | *** | The data version No. (3-digit alpha-numeral) of the EEPROM is displayed. | - |
| | Software version No. | RV. | 0 | *** | - | _ | r | U. | *** | *** | The version No. (3-digit alpha-numeral) of the software is displayed. | - |
| | Display previous simple setting selected. | Т. | 0 | _ | - | - | ٢. | | **** | **** | Display previous simple setting selected. | - |

Note) For the details of each function, refer to 19. CUTTER OUTPUT.

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | Function name Dig | on e gital | Setting display | g | Specification | Ref. page |
|---|--|-----------------|-----------------|----------|------------------|-------|-------------------------|------------------|--------------------|------------------|--|--------------|
| | Set No. of stitches COA. A for cutter output (Setting the delay time during chain-off output ON) | 0 | 0 | Stitches | 0 to 99 | 2 | 0 | R. | | ** | The No. of stitches A (delay during chain-off output ON) for chain-off output operation can be set. When CTR=ON, the No. of stitches for cutter output OFF can be set. | _ |
| | Set No. of stitches COB. B for cutter output (Setting the delay time during chain-off output OFF) | 0 | 0 | Stitches | 0 to 99 | ٢ | 0 | b . | | ** | The No. of stitches B (delay during chain-off output OFF) for chain-off output operation can be set. When CTR=ON, the No. of stitches for cutter output ON can be set. | - |
| | Set No. of stitches COC. C for cutter output | 0 | 0 | Stitches | 0 to 99 | ٢ | 0 | ٤. | | ** | The No. of stitches C (delay during cutter output ON) during cutter output operation can be set. | - |
| F mode | No. of stitches for BT X. output ON after sensor OFF setting | 0 | 0 | Stitches | 0 to 99 | H. | | | | ** | The No. of stitches to be stitched before the output BT for the in-tacking signal is turned ON after the sensor turns OFF can be set. | - |
| (▼) + (↑) | No. of stitches for sewing Y. machine stop after BT output ON setting | 0 | 0 | Stitches | 0 to 99 | μ. | | | | ** | The No. of stitches to be stitched before the sewing machine stops after the output BT for the in- tacking signal turns ON can be set. | - |
| + SL | No. of stitches for BT Z. output OFF after start of stitching setting | 0 | 12 | Stitches | 0 to 99 | : | | | | ** | The No. of stitches to be stitched before the output BT for in-tacking signal is turned OFF after stitching is started can be set. | - |
| | Delay time to when S SD. output turns from OFF to ON | 0 | 0 | msec | 0 to 508 | 5 | ď. | | | *** | The delay time for the output SL to turn from OFF to ON can be set in 2 msec intervals. The cutter output time setting is also possible. | - |
| | Delay time to when SL ED. output turns from ON to OFF | 0 | 0 | msec | 0 to 508 | 8 | ď. | | | *** | The delay time for the output SL to turn from ON to OFF can be set in 2 msec intervals. The chain- off output mesh judgment time setting is also possible. | - |
| | No. of set stitches SLH. during SL output ON selection mode | 0 | OF | - | _ | 5 | L | H. | o n o F | | The No. of set stitches for the output SL can be selected from HOF set No. of stitches (during ON setting) or SLN set No. of stitches (during OFF setting). Setting HOF function. | - |
| | SL output start SLK. position setting | 0 | OF | - | _ | 5 | L | £ . | on oF | ON OF | The output of SL for thread dislocation prevention starts when the needle lift operation (US, U, UF) is completed. | - |

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Note) For the details of each function, refer to 19. CUTTER OUTPUT.

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | uncti nam | ion ne)igital | l disp | play | Setti | ng ר | | Specification | Ref. page |
|----------------|--------------------------------|-----------------|-----------------|------|------------------|-------|--------------|--------------------------|--------|----------|-------|---------|----|---|--------------|
| | SL output start position SLT. | 0 | OF | - | - | 5 | L | ٢. | 0 | n C | | l I | ON | When the SL output operation mode SLS is ON while the motor is stopped, the output of SL for | - |
| | during SLS function ON setting | | | | | | | | 0 | <u> </u> | | 1 | OF | thread dislocation prevention will start after the thread is trimmed. | |
| | Speed limit M except SLL. | 0 | OF | - | - | 5 | L | L. | 0 | n | | 1 | ON | If the output SL turns ON during an operation other than tacking, the speed is limited to that set in the | - |
| | tacking and SL on | | | | | | | | 0 | <u> </u> | | 1 | OF | medium speed M. | |
| | SL output operation SLS. | 0 | OF | - | - | 5 | L | 5. | 0 | n | | I. | ON | The output SL is ON even when the motor is stopped. | - |
| | during motor stop | | | | | | | | 0 | <u> </u> | | | OF | | |
| | OT1 output blower O1B. | 0 | OF | - | - | 0 | - 1 | Ь. | 0 | n | | i. | ON | Virtual output OT1 will be set to blower output of cutter function. | - |
| | output setting | | | | | | | | 0 | <u> </u> | | 1 | OF | | |
| | OT2 output chain-off O2M. | 0 | OF | - | - | 0 | 2 | R. | 0 | n | | 1 | ON | Virtual output OT2 can be used as the chain-off output. | - |
| | output setting | | | | | | | | 0 | F | | I. | OF | | |
| F | OT3 output cutter O3M. | 0 | OF | - | - | 0 | 3 | n, | 0 | n | | 1 | ON | Virtual output OT3 can be used as the cutter output. | - |
| mode | output setting | | | | | | | | 0 | F | | Ì. | OF | | |
| $[\downarrow]$ | Mesh judgment I2M. | 0 | OF | - | - | , | 2 | <u>n</u> | 0 | n | | 1 | ON | The mesh judgment control of cutter specification is added to chain-off output. | - |
| | control with IR2 input | | | | | | | | 0 | F | | i. | OF | Refer to the section [21. Input/output function for signal on C mode setting] for details on the IO2, IR2 | |
| | | | | | | | | | | | | | | and IS2 signal function. | |
| (↑) | Setting I * 3 signal for CTY. | 0 | OF | - | - | E | ſ | P. | 0 | n | | 1 | ON | When the IO3, IR3 and IS3 signals are ON, the output is set to the manual cutter output. Refer to the | - |
| + | manual cutter output | | | | | | | | 0 | F | | | OF | section [21. Input/output function for signal on C mode setting] for details on the IO3, IR3, and IS3 | |
| B | | | | | | | | | | | | i | | signal function. | |
| | Status of cutter output CTM. | 0 | OF | - | - | 2 | ſ | <u>n</u> | | | | 1 | | The change status of the IO3, IR3 and IS3 signal photo switch that outputs the cutter output by the | - |
| | photo switch (I*3) signal | | | | | - | | - | | | | I. | | virtual output OT3 can be selected. Refer to the section [21. Input/output function for signal on C | |
| | according to OT3 output | | | | | | | | | | | | | mode setting] for details on the IO3 and IR3 and IS3 signal function. | |
| | | | | | | | | | 0 | n | | 1 | ON | The cutter output by the OT3 is output at both changes (OFF=>ON) (ON=>OFF) of the IO3, IR3 and | |
| | | | | | | | | | | | | | | IS3 and IS3 signal function. | |
| | | | | | | | | | 0 | F | | 1 | ŌF | The cutter output by the OT3 is output at only the (OFF=>ON) change of the IO3, IR3 and IS3 signal | |
| | | | | | | | | | - | | | 1 | | photo switch. | |
| | Turn OT3 output ON/OFF CTR. | 0 | OF | _ | - | Ľ | ٢ | r. | 0 | n | | 1 | ON | When the IO3, IR3 and IS3 signals are ON, the virtual output OT3 is turned ON/OFF per set No. of | _ |
| | per set No. of stitches | | | | | - | | | 0 | F | | 1 | OF | stitches.(When this is turned ON, the cutter specifications by the sensor will be invalidated.) | |
| | when I*3 signal is ON | | | | | | | | | | | i. | | The set No. of stitches can be set with the cutter specifications No. of stitches A (non-stitching chain | |
| | - | | | | | | | | | | | 1 | | ON delay) setting COA function, cutter specifications No. of stitches B (non-stitching chain ON | |
| | | | | | | | | | | | | i. | | delay) setting COB function and the cutter specifications No. of stitches C (non-stitching chain ON | |
| | | | | | | | | | | | | 1 | | delay) setting COC function. | |
| | | | | | | | | | | | | 1 | | Refer to the section [21. Input/output function for signal on C mode setting] for details on the IO3.IR3 | |
| | | | | | | | | | | | | 1 | | and IS3 signal function. | |

Note) For the details of each function, refer to 19. CUTTER OUTPUT.

| Mode name | Function name | | Oper ability | Factory setting | Unit | Setting range | F | unctic name Dię | on e gital | L I disp | s splay | Setting | g I | Specification | Ref. page |
|--------------|--|------|-----------------|-----------------|----------|------------------|-------|-----------------------|------------------|-------------|------------|---------|------------------|--|--------------|
| | Automatic cutter output prohibit during sensor ON | CSC. | 0 | OF | - | _ | 2 | 5 | ε. | 0 0 | n F | 1 | ON OF | The output of the automatic cutter output is prohibited while the sensor is ON. | - |
| | Automatic cutter output prohibit during sensor OFF | CEC. | 0 | OF | - | _ | 2 | Ε | ٤. | 0 0 | n F | 1 | ON OF | The output of the automatic cutter output is prohibited while the sensor is OFF. | - |
| F | Cutter output prohibit when sensor is ON while stopped | CTS. | 0 | OF | - | _ | 2 | ٢ | 5. | 0 0 | n F | 1 | ON OF | The output of the automatic cutter output is prohibited when the sensor input is ON while the sewing machine is stopped. | - |
| ↓ + | Automatic thread trim setting after cutter sensor is turned off | CAT. | 0 | OF | - | _ | [| R | ٢. | 0 0 | n F | 1 | ON OF | Automatic stop and trim setting, after the cutter sensor is turned off and then the number of stitch "C" set by "COC" function is run. | - |
| + 8 SL | Set I*1 input, NOP output to cutter BT specifications input/output | CTL. | 0 | OF | - | _ | ٤ | ſ | L. | 0 | n F | | ON OF | The IO1,IR1 and IS1 signals and the run output OP1 are set to the cutter BT specifications input/ output signals. Refer to the section [21. Input/output function for signal on C mode setting] for details on the IO3, IR3 and IS3 signal function. | - |
| | Preset stitching operation after operation signal OFF | NMD. | 0 | OF | - | _ | n | Π | ď. | 0 0 | n F | 1 | ON OF | Only the preset No. of stitches is stitched after the operation signal (S1) is turned OFF. | - |
| | ROL output mode | RLM. | 0 | OF | - | _ | r | L | N. | 0 0 | n F | 1 | ON OF | The roller lift output ROL will turn ON when presser foot lifting output FU, backtacking output B, virtual output OT2 are ON, and during tacking and thread trimming. | - |
| | No. of stitches setting for auxiliary feeding rear roller | RLN. | 0 | 0 | Stitches | 0 to 99 | r | ٤ | n. | ** | | 1 | ** | The roller lower No. of stitches is set for the auxiliary feeding rear roller. | - |

| Mode name | Function name | | Oper ability | Factory setting | Unit | Setting range | F | unction name Digit | tal d | displa | Setti ay | ing ¬ | Specification | Ref. page |
|--------------|----------------------------------|------|-----------------|-----------------|--------|------------------|-------|--------------------------|------------|----------|-------------------------------|-----------------------|--|--------------|
| | Thread trimming mode | TR. | 0 | M1 | _ | _ | ſ | r. | ((| n ; r | ן ב | N to R | The thread trimming timing for each manufacturer's thread trimming sewing machine can be set. Same function as the P mode thread trimming mode [TR]. When [PRG] is set, the sewing machine operation and thread trimming timing can be set when combined with the functions [TRM], [LTM] or [LLM]. | - |
| | Motor operation T mode during | FRM. | 0 | LK | - | _ | ٢ | r I | 7. | | | | The motor operation mode during thread trimming can be set when thread trimming mode TR is set to [PRG]. | - |
| | thread trimming | | | | | | | | | L r | <u></u> <u></u> <u></u> | + - L | The motor will run for the lockstitch thread trimming sewing machine. The motor will run for reverse thread trimming. | |
| | | | | | | | | | E | E . | R – | i k | A The motor will run (A mode) for the chain stitch thread trimming sewing machine. | |
| | | | | | | | | | E | <u>E</u> | Ь | ī K | The motor will run (B mode) for the chain stitch thread trimming sewing machine. | |
| G | | | | | | | | | L | y – | ρ | ¦ U | P The motor will run with special functions for the lockstitch thread trimming sewing machine. The | - |
| mode | | | | | | | | | | | | | motor stop time TD before thread trimming will be the needle UP position reference. | |
| | | | | | | | | | C | ď | n | ¦ D | The motor will run with special functions for the lockstitch thread trimming sewing machine. The | - |
| + | | | | | | | | | | | | 1 | motor stop time TD before thread trimming will be the needle DOWN position reference. | |
| (\uparrow) | Thread trimming L | _TM. | 0 | T2 | - | - | Ł | ſ | <u>n l</u> | [| <u>-</u> ! | · + _] | Thread trimming mode TR becomes effective when [PRG] is set. | - |
| | output (T) output mode | | | | | | | | 1 | | <u>द</u> | <u> </u> | 2_ The output timing mode of the thread trimming output (T) can be selected. | |
| + | | | | | | | | | Ľ | | <u>-</u> | · + _] | B For the details of the selection of the output timing of thread trimming output (T), refer to [12.1) Thread | |
| ° | | | | | | | | | Ľ | | <u>4</u> | <u>+</u> | trimming timing when thread trimming mode TR setting is PRG]. | |
| | | | | | | | | | ľ | <u>-</u> | <u></u> | + - <u>-</u> | | |
| | | | | | | | | | ļ | r | | <u> </u> | | |
| | Thursday Indexes | | 0 | 1.0 | | | , | , | 1 n 1 | i 1 | 1 | | | |
| | Inread release | | 0 | LZ | - | - | L | ני | ". L | L | | · <u> </u> _ <u> </u> | The substitut timing mode of the thread release substit (1) can be selected | - |
| | oulput (L) oulput mode | | | | | | | | ļ, | , | <u> </u> | · + | $\frac{1}{2}$ The output unning mode of the infreductions of the output (L) can be selected. | |
| | | | | | | | | | ļ | <u> </u> | ב | | - trimming timing when thread trimming mode TP setting is PPG1 | |
| | | | | | | | | | | Ļ ! | | · + | | |
| | | | | | | | | | ļ | L ! | ς | · <u>-</u> | | |
| | | | | | | | | | 1 | | | · + - = | 7 | |
| | Thread trimming | TS. | 0 | 24 | Degree | 0 to 360 | 1 | 5 | * | *** | • | * | When the thread trimming mode TR is set to [PRG], the output start angle of the thread trimming | |
| | output start angle | | | | | | | | | | | 1 | output (T) can be set. | |
| | | | | | | | | | | | | I I | Set according to the thread trimming output (T) timing chart. | |

| Mode name | Function name | | Oper ability | Factory setting | Unit | Setting range | | unction name | Settin | g 1 | Specification | Ref. page |
|--------------|----------------------------|------------|-----------------|-----------------|--------|------------------|-----------|-----------------|----------------|---------------|--|--------------|
| | Thread trimming | TE. | 0 | 30 | Degree | 0 to 360 | ſ | Digital | display *** | ** | * When the thread trimming mode TR is set to [PRG], the output end angle of the thread trimming | |
| | output angle | | | | Ũ | | | | | | output (T) can be set. | |
| | | | | | | | | | | l | Set according to the thread trimming output (T) timing chart. | |
| | Thread release | LS. | 0 | 188 | Degree | 0 to 360 | L | 5. | *** | | * When the thread trimming mode TR is set to [PRG], the output start angle of the thread release | - |
| | output start angle | | | | | | | | | 1 | output (L) can be set. | |
| | | | | | | | | | | | Set according to the thread release output (L) timing chart. | |
| | Thread release | LE. | 0 | 134 | Degree | 0 to 360 | L | E . | *** | ** | * When the thread trimming mode TR is set to [PRG], the output end angle of the thread release | - |
| | output angle | | | | | | | | | | output (L) can be set. | |
| | | | | | | | | | | I | Set according to the thread release output (L) timing chart. | |
| | Thread trimming | T1. | 0 | 20 | msec | 0 to 998 | | I. | *** | ** | * The output start time of the thread trimming output (T) for chain stitch sewing machine can be set. | - |
| | output start time | | | | | | | | | 1 | When the thread trimming mode TR is set to [PRG], the output start time of the thread trimming | |
| G | | | | | | | | | | | output (T) for lock stitch sewing machine can be set. Set according to the thread trimming output (T) | |
| mode | | | | | | | <u> </u> | | | | timing chart. | |
| | Thread trimming | T2. | 0 | 90 | msec | 0 to 998 | | 2. | *** | ** | * The output time of the thread trimming output (T) for chain stitch sewing machine can be set. | - |
| \bigcirc | output time | | | | | | | | | 1 | When the thread trimming mode TR is set to [PRG], the output time of the thread trimming output (T) | |
| + | | | | | | | | | | | for lock stitch sewing machine can be set. Set according to the thread trimming output (T) timing | |
| (\uparrow) | | | | | | | | | | 1 | chart. | |
| + | Thread release | L1. | 0 | 150 | msec | 0 to 998 | L | I. | *** | ** | * The output start time of the thread release output (L) for chain stitch sewing machine can be set. The | - |
| c | output start time | | | | | | | | | 1 | output start time of the thread release output (L) during chain stitching thread trimming timing A can | |
| | | | | | | | | | | 1 | be set. | |
| | | | | | | | | | | 1 | The chain stitching thread trimming timing B is invalid at this time. | |
| | | | | | | | | | | 1 | When the thread trimming mode TR is set to [PRG], the output start time of the thread release output | |
| | | | | | | | | | | 1 | (L) for lock stitch sewing machine can be set. Set according to the thread release output (L) timing | |
| | | | - | | | | | _ | | , | chart. | <u> </u> |
| | Thread release output time | L2. | 0 | 70 | msec | 0 to 998 | Ł | ć . | *** | *" | * The output time of the thread release output (L) for chain stitch sewing machine can be set. The | - |
| | | | | | | | | | | i i | output time of the thread release output (L) during chain stitching thread trimming timing A can be | |
| | | | | | | | | | | 1 | set. | |
| | | | | | | | | | | i i | The chain stitching thread trimming timing B is invalid at this time. | |
| | | | | | | | | | | | When the thread trimming mode TR is set to [PRG], the output time of the thread release output (L) | |
| | Thus a due la secondation | D 4 | 0 | 10 | | 0.1- 500 | - | , | *** | ' | tor lock stitch sewing machine can be set. Set according to the thread release output (L) timing chart. | |
| | i nread release outpu | K1. | U | 40 | msec | U TO 508 | ^ | I. | | ^{**} | I ne output start time of the thread release output (L) during chain stitching thread trimming timing B | - |
| | start time | | | | | | | | | I | can be set. The chain stitching thread trimming timing A is invalid at this time. The output start time | 1 |
| | | | | | | | | | | | or the output (1F) can be set. | |
| | | | | | | | 1 | | | I | Set according to teach output's timing chart. | 1 |

| Mode name | Function name | Op abi | er Fa lity se | actory setting | Unit | Setting range | - F | Function name Digita | l displ | Setting | | Specification | Ref. page |
|--------------|--|-----------|------------------|-------------------|-------------|------------------|-----|--------------------------------|------------|----------------|--------|--|--------------|
| | Thread release output R time (TF output time) | 2. C |) (| 66 | msec | 0 to 508 | ſ | 2. | *** | | *** | The output time of the thread release output (L) during chain stitching thread trimming timing B can be set. The chain stitching thread trimming timing A is invalid at this time. The output time of the output (TF) can be set. Set according to teach output's timing chart. | - |
| G | Condensed stitching R start time (Stop time before thread trimming) | 3. C |) ! | 50 | msec | 0 to 508 | ſ | З. | *** | | *** | The time of when the sewing machine begins condensed stitching after the condensed stitching (CH) turn ON during start/end condensed stitching can be set. However, during the end condensed stitching in the chain stitching thread trimming timing B, this time [R3] will be the time for end condensed stitching after the thread release output (L) turns OFF. (If end condensed stitching is not set, the time will be that for the needle to rise from the DOWN to UP position after the thread release output (L) is turned OFF.) | - |
| mode | Wiper output start time W | 1. C | , . | 10 | msec | 0 to 998 | y | I. | *** | | *** | When the thread trimming mode TR is set to [PRG], the output start time of the wiper output (W) can be set. Set according to the wiper output (W) timing chart. | - |
| · (| Wiper output time W | 2. C |) | 8 | x10 msec | 0 to 999 | 8 | 2. | *** | | *** | When the thread trimming mode TR is set to [PRG], the output time of the wiper output (W) can be set. Set according to the wiper output (W) timing chart. | - |
| | Wiper output WM operation mode | D. C |) | W | _ | _ | y | Πd. | ! | | | The output timing mode of the wiper outputÅiWÅjcan be set. The timing that the wiper output W is turned OFF can be set with the thread trimming signal S2. Refer to [12 . 1)]. Thread trimming timing when thread trimming mode TR setting is [PRG] for details on setting the OFF timing. | - |
| | | | | | | | | | B _ | | W | If the S2 signal turns OFF within the wiper output W set time, the W output will turn OFF after the set time has passed. If the S2 signal turns OFF after the wiper output W set time has passed, the W output will turn OFF after the set time has passed. | |
| | | | | | | | | | 0 | | OR | If the S2 signal turns OFF within the wiper output W set time, the W output will turn OFF after the set time has passed. If the S2 signal turns OFF after the wiper output W set time has passed, the W output will turn OFF when the S2 signal turns OFF. | |
| | | | | | | | | | R | <u> </u> | AN | If the S2 signal turns OFF without the wiper output W set time, the W output will turn OFF when the S2 signal turns OFF. If the S2 signal turns OFF after the wiper output W set time passes, the W output will turn OFF after the set time has passed. | |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | Function name Digital | L I displ |) Jay | Setting | | Specification | Ref. page |
|--------------------------|---------------|-----------------|-----------------|------|------------------|---------------------------------|--------------|-------------|---------|----------|--|--------------|
| G mode ↓ + ↑ | | | | | | | C | U H H | | RU CH | This setting is valid when the reverse run needle setting after thread trimming RU is ON. When the reverse run needle lifting is completed after the thread is trimmed, the W output will turn ON. If the S2 signal turns OFF within the wiper output W set time, the W output will turn OFF after the set time has passed. If the S2 signal turns OFF after the wiper output W set time has passed, the W output will turn OFF after the set time has passed. This setting is valid when the thread trimming motor operation mode TRM is set to KB. The W output will start before the short stitch. If the S2 signal turns OFF within the wiper output W set time, the W output will turn OFF after the set time has passed. If the S2 signal turns OFF after the wiper output W set time, the W output will turn OFF after the set time has passed. If the S2 signal turns OFF after the wiper output W set time, the W output will turn OFF after the set time has passed. If the S2 signal turns OFF after the wiper output W set time, the W output will turn OFF after the set time has passed. If the S2 signal turns OFF after the wiper output W set time has passed, the W output will turn OFF after the set time has passed. If the S2 signal turns OFF after the wiper output W set time has passed, the W output will turn OFF after the set time has passed. | |
| | | | | | | | | | | | will start before the sort stitch. The W output will turn OFF when the set time has passed after the thread trimming operation is completed. | |

| Mode name | Function name | | Oper ability | Factory setting | Unit | Setting range | F | unction name Digita | | Setting isplay | 9 | Specification | Ref. page |
|---|--|------|-----------------|-----------------|------|------------------|-------|---------------------------|-----------------|------------------------------|----------|---|--------------|
| | Presser foot lifting output start time | F1. | 0 | 140 | msec | 0 to 998 | F | I. | ** | ** | *** | When the thread trimming mode TR is set to [PRG], the output start time for the presser foot lifting output (FU) is set. | _ |
| | Time to motor drive after presser foot lifter bring down | FD. | 0 | 176 | msec | 0 to 998 | F | ď. | ** | ** | *** | The time for the motor to start driving after the presser foot output FU is turned OFF when pedal toe down or external run signal (S0,S1) ON during presser foot lifting can be set in 2 millisecond units. | _ |
| | Interlock time during thread trimming | IL. | 0 | 140 | msec | 0 to 998 | , | L. | ** | ** | *** | The interlock time that prohibits operation during thread trimming can be set. Manual calculation will be used during the [P] mode thread trimming (TR) timing [PRG] ,[KA3], [KA4], [KB3], [KB4], so the setting is valid. [KA1], [KA2], [KB1], [KB2] are for automatic calculation and cannot be set. | _ |
| | Interlock time during no thread trimming | IT. | 0 | 0 | msec | 0 to 510 | , | ٢. | ** | ** | *** | The interlock time during the no thread trimming timing can be set. This is valid when the [P] mode thread trimming timing [NO] or thread trimming release signal (TL) is turned ON. | _ |
| G mode | Motor rotation after motor stop before thread trimming | TDS. | 0 | OF | - | _ | ſ | d <u>9</u> | 5. 0 0 | 5 F | ON OF | After the motor stops, it will start rotating after the thread trimming output T turns ON and the delay time has passed. The delay time can be set by the [TD] function. | _ |
| + ↑ + | Motor stop time during lockstitch and R output time during chain stitch | TD. | 0 | 50 | msec | 0 to 508 | ſ | ď. | ** | ** | *** | The motor stop time before thread trimming during lock stitch can be set in 2 msec intervals. The output R output time during chain stitch can be set in 2 msec. When the chain stitch mode is set, it is possible to set to the delay time of the motor "R3". Please refer to "12 .1) Thread trimming timing when thread trimming mode TR setting is PRG" about the delay time setting. | _ |
| | Delay setting before reverse run during RU setting | RUS. | 0 | OF | _ | _ | r | US | 5. 0 0 | 5 F | ON OF | Delay time before reverse run (RU operation) after thread trimming is completed can be set with RT when the thread trimming reverse needle lift RU is set to ON. | - |
| | Delay setting before reverse run during RU setting | RT. | 0 | 76 | msec | 0 to 508 | r | Г. | 0 | | ON OF | When reverse needle lift after thread trimming RU is ON and RUS is ON, the delay time before the motor reverse run after thread trimming can be set in 2 msec intervals. | _ |
| | Reverse run needle lifting [RU] after output T,L and W | RUM. | 0 | OF | - | _ | r | U f. | <u>,</u> 0 | | ON OF | Cannot be used. | - |
| | Wiper output OFF trimming with (S1) signal | WS1. | 0 | OF | - | - | 8 | 5 | <u>;</u> 0 0 | , r | ON OF | If the pedal is toed down or external output signal (S2) is turned ON during the wiper output time [W2] (after thread trimming interlock time),the wiper output time [W] will turn OFF. The presser foot lifting output (FU) will also turn OFF simultaneously, and the sewing machine will run after the [FD] time. Use this for the air type wiper. This is effective for standing operation (automatic machine operation). | - |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | unction name Digita | al dis | isplay | Settin | g I | Specification | Ref. page |
|----------------|---|-----------------|-----------------|---------------|-------------------|-------------|---------------------------|-----------------------|-------------------|--------|----------------|---|--------------|
| | Operation mode with S2T. thread trimming signal to shift the needle stop position and return to the original needle stop position before the thread trimming signal | 0 | OF | _ | - | 5 | 2 (| Г. О | | | | If the sewing machine pulley is rotated by hand and set to 1 position while the sewing machine is stopped before thread trimming, if the needle UP position is 2 position, the needle DOWN position will shift. To return to the original stop position after that, fully heel the pedal, or set the operation mode by turning thread trimming signal (S2) ON. The same operation as then next [S2P] setting value ([NO], [TR], [PS]) is executed. | |
| G mode → + ↑ + | Operation mode with S2P. thread trimming signal when shifting the needle stop position before the thread trimming signal | 0 | TR | _ | _ | 5 | 2 F | 2. | | | TR PS NO | The thread mode started with the full pedal heeling or thread trimming signal (S2) ON when rotating the sewing machine pulley, etc., manually, and leaving the UP position when in 1 position, and leaving the DOWN position when in 2 position. When [KA1] to [KA4] of the thread trimming mode [TR] are set, the thread trimming operation will be performed according to the settings after the needle is lifted. When [KB1] to [KB4] are set, the thread trimming operation will be performed according to the settings after the needle is lifted. When [KB1] to [KB4] are set, the thread trimming operation will be performed according to the settings after the needle is lifted. The presser foot lifting operation will be executed after the needle is lifted. The thread trimming operation will not be executed. The sewing machine does not rotate or perform thread trimming, and only the presser foot lifting operation is executed. | |
| | Solenoid output OT1 MAN. manual/automatic change Setting of no. of stitches HOF. during MAN [OFF]setting Weak brake ON WB. | 0 | ON 7 OF | - Stitches | - 0 to 99 - | П Н В | Я r о ł ь. | n. 0 0 5. ** | 5 n 5 F * | | ON 05 | The sewing of the solenoid output [OT1] manual/automatic output is selected. The solenoid output [OT1] will be set to manual. The solenoid input signal IO1 is validated. The solenoid output [OT1] will be set to manual. The solenoid input signal IO1 is validated. This is valid when the solenoid output [OT1] manual/automatic output change is set to automatic. If the pedal is toed down or the external run signal (S00, S1, SH) is turned ON while the solenoid output [OT1] is ON, the OT1 output will turn OFF after the set No. of stitches. The weak brake will turn ON when the wiper output (W) turns ON. | |
| | simultaneously with wiper output (W) Motor rotation operation TDT. when LTM function is set to T1,T2 or T3 | 0 | OF | _ | _ | ſ | d / | 0 - 0 | 0 r 0 n 0 f | | OF ON OF | When the thread trimming output T mode LTM for lockstitch is set to [T1], [T2] or [T3], after the motor stops, it will start again after the thread trimming output T turns ON and the delay time has passed. Set time can be set by the [TD] function. | _ |

| Mode name | Function name | | Oper ability | Factory setting | Unit | Setting range | F | uncti nam D | on e igital | display | Setting | | Specification | Ref. page |
|--------------|---|------------|-----------------|-----------------|---------------|------------------|-------|-------------------|-------------------|---------|----------------|----|--|--------------|
| | Upper limit of maximum speed [H] | LHH. | 0 | 90 | x100 r/min | 0 to 99 | L | Н | H. | ** | | ** | The upper limit value of the maximum speed [H] in P mode is set. A value that exceeds the value set in this limiter cannot be set for the maximum speed [H]. The factory setting [90] refers to [90x100=9000] r/min. | - |
| | Lower limit of maximum speed [H] | LHL. | 0 | 0 | x100 r/min | 0 to 99 | ٤ | Н | L. | ** | | ** | The lower limit value of the maximum speed [H] in P mode is set. A value that is lower than the value set in this limiter cannot be set for the maximum speed [H]. | - |
| н | Upper limit of low speed [L] | LLH. | 0 | 5 | x100 r/min | 0 to 99 | L | L | H. | ** | | ** | The upper limit value of the maximum speed [L] in P mode is set. A value that exceeds the value set in this limiter cannot be set for the low speed [L]. The factory setting [5] refers to [5x100=500] r/min. | - |
| mode | Lower limit of low speed [L] | LLL. | 0 | 0 | x100 r/min | 0 to 99 | ٤ | L | L. | ** | | ** | The lower limit value of the low speed [L] in P mode is set. A value that is lower than the value set in this limiter cannot be set for the low speed [L]. | - |
| + | Upper limit of thread trimming speed [T] | LTH. | 0 | 5 | x100 r/min | 0 to 99 | ٤ | ٢ | H. | ** | | ** | The upper limit value of the thread trimming speed [T] in P mode is set. A value that exceeds the value set in this limiter cannot be set for the thread trimming speed [T]. The factory setting [5] refers to[5x100=500] r/min. | - |
| | Lower limit of thread trimming speed [T] | LTL. | 0 | 0 | x100 r/min | 0 to 99 | ٤ | ſ | L. | ** | | ** | The lower limit value of the thread trimming speed [T] in P mode is set. A value that is lower than the value set this limiter cannot be set for the thread trimming speed [T]. | - |
| | Upper limit of start/end tacking (condensed stitching) speed | LNH. | 0 | 30 | x100 r/min | 0 to 99 | L | n | H. | ** | | ** | The upper limit value of the start/end tacking (condensed stitching) speed in P mode is set. A value that exceeds the value set in this limiter cannot be set for the start/end tacking (condensed stitching) speed. The factory setting [30] refers to [30x100=3000] r/min. | - |
| | Lower limit of start/end tacking (condensed stitching) spe | LNL. ed | 0 | 0 | x100 r/min | 0 to 99 | ٤ | n | L. | ** | | ** | The lower limit value of the start/end tacking (condensed stitching) speed in P mode is set. A value that is lower than the value set in this limiter cannot be set for the start/end tacking (condensed stitching) speed. | - |
| | Upper limit of medium speed [M] | LMH. | 0 | 90 | x100 r/min | 0 to 99 | ٤ | Π | H. | ** | | ** | The upper limit value of the medium speed [M] in P mode is set. A value that exceeds the value set in this limiter cannot be set for the medium speed [M]. The factory setting [90] refers to [90x100=9000] r/min. | - |

| Mode name | Function name | | Oper ability | Factory setting | Unit | Setting range | F | unctior name Digi | n ital o | Settin display | g I | | Specification | Ref. page |
|--------------|----------------------|------|-----------------|-----------------|-------|------------------|-------|-------------------------|-----------------|-----------------------|--------|----|--|--------------|
| н | Lower limit of | LML. | 0 | 0 | x100 | 0 to 99 | L | n | L. | ** | | ** | The lower limit value of the medium speed [M] in P mode is set. | - |
| mode | medium speed [M] | | | | r/min | | | | | I | | | A value that is lower than the value set in this limiter cannot be set for the medium speed [M]. | |
| | Upper limit of | LSH. | 0 | 30 | x100 | 0 to 99 | L | 5 | H. | ** | | ** | The upper limit value of the medium speed [M] in P mode is set. | - |
| + | slow start speed [S] | | | | r/min | | | | | 1 | l | | A value that exceeds the value set in this limiter cannot be set for the medium speed [M]. | |
| (\uparrow) | | | | | | | | | | | | | The factory setting [30] refers to [30x100=3000] f/min. | |
| + | Lower limit of | LSL. | 0 | 0 | x100 | 0 to 99 | ٤ | 5 | L. | ** | | ** | The lower limit value of the medium speed [S] in P mode is set. | - |
| ₽ | slow start speed [S] | | | | r/min | | | | | | | | A value that is lower than the value set in this limiter cannot be set for the medium speed [S]. | |
| | | | | | | | | | | | | | | |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | unctio name | n | | S | ettin | g I | | Specification | Ref. page |
|--------------|---|-----------------|-----------------|------|------------------|---|----------------|------------|--------|--------|-------|---------------------|----------|---|--------------|
| | Simple setting mode for MAC. Mitsubishi thread trimming sewing machine prohibit | 0 | ON | _ | _ | n | <i>R</i> | £ . | 0 0 | n F | | | ON OF | The simple setting mode (program mode [1] for Mitsubishi thread trimming sewing machine) cannot be entered. ([]+[A]+[B] key operation will not be possible.) | - |
| | [P], [G] mode thread TRC. trimmer mode TR prohibit | 0 | OF | _ | - | ſ | r | ٤. | 0 0 | n F | | | ON OF | The [P] mode thread trimmer mode, TR cannot be entered.([]+[] key operation (program mode P) will be possible.) The thread trimmer mode [G] cannot be entered. ([]+[]+[C] key operation will not be possible.) | _ |
| | Rotation direction CWC. changeover prohibit | 0 | ON | - | - | נ | y | ٤. | 0 0 | n F | | | ON OF | Rotation direction changeover ([]+[M] key operationÅjduring the normal mode will not be possible. | _ |
| J mode | 1-2 position changeover 12C prohibit | 0 | OF | _ | _ | 1 | 2 | [. | 0 0 | n F | | | ON OF | 1-2 position changeover ([A] key operation) during the normal mode will not be possible. | _ |
| + | Slow start changeover SLC. prohibit | 0 | OF | - | _ | 5 | ٤ | [. | 0 0 | n F | | | ON OF | Slow start validity changeover ([B] key operation) during the normal mode will not be possible. | - |
| (↑) + | Speed setting key SPC. changeover prohibit | 0 | OF | _ | - | 5 | ρ | ٢. | 0 0 | n F | | | ON OF | Speed setting operation of normal mode ([C] key and [D] key operation) jwill not be possible. | - |
| + | JKC. | 0 | OF | _ | - | J | ٤ | C . | 0 0 | n F | | | ON OF | Not used. | - |
| B SL | Start tacking validity SBC. changeover prohibit | 0 | OF | _ | _ | 5 | Ь | ٤. | 0 0 | n F | | | ON OF | Start tacking validity changeover ([A] key operation) during the tacking mode will not be possible. | _ |
| | No. of start tacking SNC. stitches changeover prohibit | 0 | OF | _ | - | 5 | n | C . | 0 0 | n F | | | ON OF | The No. of start tacking stitches setting ([A], [B] key operations) during the tacking mode will not be possible. | _ |
| | End tacking validity EBC. changeover prohibit | 0 | OF | - | - | 8 | ь | ٤. | 0 0 | n F | | | ON OF | End tacking validity changeover ([C] key operation) during the tacking mode will not be possible. | - |
| | No. of end tacking ENC. stitches changeover prohibit | 0 | OF | _ | - | E | n | £ . | 0 0 | n F | | | ON OF | The No. of end tacking validity changeover ([C], [D] key operations) during the tacking mode will not be possible. | - |
| | Start tacking type SKC. changeover prohibit | 0 | OF | - | - | 5 | Ł | ٤. | 0 0 | n F | | | ON OF | Start tacking type setting ([B] key operation) during the tacking mode will not be possible. | _ |
| | End tacking type EKC. changeover prohibit | 0 | OF | - | - | ε | Ł | ٤. | 0 0 | n F | | | ON OF | End tacking type setting ([D] key operation) during the tacking mode will not be possible. | - |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | _ F | Functio name Dię | on e gital | disp | Settin | ng T | | Specification | Ref. page |
|---|--|-----------------|-----------------|------|------------------|-----|------------------------|------------------|--------|------------|---------|----------|---|--------------|
| J mode | Pattern stitching TSC. validity changeover prohibit | 0 | OF | - | - | ٢ | 5 | L . | 0 0 | n F | | ON OF | Preset stitching validity and backtacking validity changeover operation ([M] key operation) in the pattern mode will not be possible. | - |
| ↓ + ↑ | Pattern stitching No. TNC. of stitches and times changeover prohibit | 0 | OF | _ | - | ٢ | n | ٤. | 0 0 | n F | (| ON OF | No of preset stitching stitches and No. of backtacking times setting operation ([C], [D] key operations) in the pattern mode will not be possible. | - |
| + | Pattern mode pattern MDC. changeover prohibit | 0 | OF | _ | _ | n | ď | ٤. | 0 0 | n F | (| ON OF | Preset stitching, backtacking and control switch panel data play mode changeover ([D] key operation) in the pattern mode will not be possible. | - |
| + SL | Panel switch PSW. operation prohibit | 0 | OF | - | _ | ρ | 5 | В. | 0 0 | n F | | ON OF | Panel switch operation ([M], [A], [B], [C], [D] key operations) during the normal mode, tacking mode and pattern mode will not be possible. However, changeover into each mode will be possible. | - |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | Function name Die | on e igital | disp | Se play | ettin | g 1 1 | Specification | Ref. page |
|--------------------|---|-----------------|-----------------|------|------------------|-------|-------------------------|-------------------|---|-----------------------|-------|------------------|---|--------------|
| | Virtual S1 operation VCS with VC1 levels | × | OF | - | - | U | ٢ | 5. | 0 0 | n F | | ON OF | The virtual operation signal S1 is turned ON when the variable speed voltage VC1 and VC2 exceeded the set voltage level. | - |
| | Setting of VC1 and VC2 VCL where virtual S1 turns ON | × | 24 | - | 1 to 99 | U | ٢ | L. | ** | | | ** | The voltage level of the variable speed voltage VC1 and VC2 where virtual run signal S1 turns ON. | - |
| | Input voltage hysteresis VCD during virtual S1 signal ON/OFF by VC1 and VC2 level | × | 4 | _ | 0 to 99 | U | [| ď. | ** | | | ** | The voltage level hysteresis width for judging the ON/OFF of the virtual S1 signal when VCS turns ON can be set. | _ |
| Q | VC1 curve V1R reversal mode | × | OF | - | - | U | 1 | r. | 0 0 | n F | | ON OF | The voltage curve of the variable speed voltage VC1 is reversed. | - |
| mode ↓ | VC1 input 5 V/12 V V15 changeover mode | × | OF | _ | - | U | 1 | 5. | 0 0 | n F | | | The VC1 input range is set to 0 to 5 V. VC1 maximum input voltage is set to 5 V. VC1 maximum input voltage is set to 12 V. | |
| ⊤ 1.2 + ℃ | VC2 operation mode VC2 | × | LM | - | - | U | 5 | 2. | _ | Γ 5 Γ 0 σ | | | The external analog input VC2 function is set. Speed command input The virtual S1 signal turns on with the input voltage, and the sewing machine runs. This also acts as the speed command input. The VC2 input acts as the variable resistor on the control box panel, and the variable resistor is invalidated. During operation with the BC and BCR input, the speed set with the program P mode C8 is invalidated, and the speed is controlled with the VC2 input. The speed control input for reciprocal stroke change. The value set in the program P mode M is invalidated, and the middle speed is controlled with the VC2 input voltage. Virtual input IO1 is selected. | |
| | VC2 curve V2R reversal mode | × | OF | - | - | U | 2 | r. | 0 0 | n F | | ON OF | The external analog input VC2 curve is reversed. | - |
| | VC2 input 5 V/12 V V25 changeover mode | × | OF | - | - | U | 2 | 5. | 0 | <u>n</u> F | | | The VC2 input rang is set to 0 to 5 V. VC2 maximum input voltage is set to 5 V. VC2 maximum input voltage is set to 12 V. | |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | ⁻ unctio name Dię | on e gital | display | Setting | | Specification | Ref. page |
|--------------|--|-----------------|-----------------|------|------------------|-------|------------------------------------|------------------|------------|----------------------------|----------|---|--------------|
| | Speed limiter curve VL1. inflection point 1 percentage | 0 | 56 | % | 1 to 99 | U | L | l. | ** | | ** | The inflection point is set when using the reciprocal stroke change specification speed limiter process (VC2=LM.) | _ |
| mode | Speed limiter curve VP1. inflection point 1 point | 0 | 39 | _ | 1 to 99 | U | ρ | l. | ** | | ** | Setting inflection point 1 | - |
| + 1-2 | Speed limiter curve VP2. inflection point 2 point | 0 | 42 | - | 1 to 99 | U | ρ | 2. | ** | | ** | Setting inflection point 2 | - |
| + | Operation speed limit FLM. specification mode 1 | 0 | OF | - | - | F | L | n. | 0 n 0 F | | ON OF | The speed limit is valid only if the presser foot is rising when the VC2 operation mode is set to LM or the medium speed limit function LIM. Is set to ON during OT1 output ON. | - |
| | Operation speed limit 2LM. specification mode 2 | 0 | OF | - | _ | 2 | L | n. | on of |) - | ON OF | The speed limit is valid only if the virtual output OT2 is ON when the VC2 operation mode is set to LM or the medium speed limit function LIM. Is set to ON during OT1 output ON. | - |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | unctio name Dig | pn jital c | | Settin | g | Specification | Ref. page |
|--------------|---|-----------------|-----------------|----------|------------------|------------|-----------------------|---------------|--------|--------|----------|---|--------------|
| | Speed command value LMD. correctly by middle speed digital during speed limit process. | 0 | OF | _ | _ | L | n | d . ' | 0 | n F | ON OF | The middle speed during the speed limit process is read into the speed command value (speed high speed signal SPH, speed end tacking signal SPB, speed medium speed signal SPM, high speed run signal S4, end tacking speed run signal S5 V, medium speed run signal S5) other than the low speed from an external source by the digit. | _ |
| | Speed limit with digital HMD. speed setting on operation panel | 0 | OF | - | _ | K | n | d . | 0 0 | n F | ON OF | The speed during stitching other than tacking is limited by the digital speed setting (LED C and D) on operation panel. | - |
| Q | Ignore detector error E8C. | 0 | OF | - | _ | 8 | 8 | ί. | 0 | n | | The sewing machine detector error E8 will be ignored. If a signal is not received from the sewing machine detector within a set time during operation, the detector error E8 will not be displayed. | |
| mode [↓] | | | | | | | | | 0 | F | OF | If a signal is not received from the sewing machine detector within a set time during operation, the detector error E8 will be displayed and the sewing machine will stop. | _ |
| + | Thread break sensor valid TH. | 0 | OF | - | - | ſ | H. | | 0 0 | n F | ON OF | The thread break detector is validated. | - |
| 1-2 + | Operation after thread TST. break sensor detection | 0 | TR | - | - | ſ | 5 | ſ. | n | 0 | NO | The operation after the thread break is detected (thread break sensor detection) is set. The operation continues, and the thread break sensor output THO turns ON. | |
| C | | | | | | | | | ſ | r | TR | The sewing machine stops after the thread trimming, and then the thread break sensor output THO turns ON. | - |
| | | | | | | | | | 5 | ٢ | ST | The sewing machine stops normally, and then the thread break sensor output THO turns ON. | |
| | Speed to ignore B. thread break sensor | 0 | 600 | r/min | 0 to 8999 | b . | | | | **** | **** | The speed to ignore the thread break sensor can be set. | - |
| | No. of stitches to THS. ignore thread break sensor after starting stitching | 0 | 7 | Stitches | 0 to F | ٢ | Н | 5. | | ** | ** | Setting the number of stitch that the sensor of thread break detector becomes valid from first stitch. | - |
| | Number of stitches THF. for judgment of thread break. | 0 | 0 | Stitches | 0 to F | ſ | Н | F. | | ** | ** | The No. of stitches to judge the thread break detection when the thread break sensor input continues for a certain number of stitches can be set. | - |

| Mode name | Function name | | Oper ability | Factory setting | Unit | Setting range | F | unctio name Die | on e gital | displa | Settir ay | ig 1 1 | Specification | Ref. page |
|---------------|--|------|-----------------|-----------------|------|------------------|-------|-----------------------|------------------|--------|------------------|--|--|--------------|
| Q | Operation mode with F input during sewing | RFU. | 0 | OF | - | - | r | F | U. | 0 0 | n F | ON OF | The presser foot lifting output will turn ON by turning ON the presser foot lifting signal F during sewing machine operation. | - |
| mode | Machine operation Output of backtacking output (B) during OT1 output ON inhibited | S7C. | 0 | OF | _ | _ | 5 | 7 | ξ. | 0 0 | n F | ON 000000000000000000000000000000000000 | Note that the presser foot lifting signal S3 is invalid during sewing machine operation. The output of the backstitching output (B) with input S7 is inhibited while the virtual output (OT1) is ON. | - |
| ▲ 1-2 + | Medium speed (M) limit mode during OT1 output ON | LIM. | 0 | ON | _ | - | ٤ | , | N. | 0 0 | n F | ON OF | The speed will be limited to that set in medium speed M while virtual output (OT1) is ON. | _ |
| C | Simultaneously ON of OP1 output during OT1 output ON | O1P. | 0 | OF | - | - | 0 | 1 | Р. | 0 0 | n F | ON OF | OP1 output will turn ON simultaneously when virtual output (OT1) is ON. | _ |
| | Disregard of S3 signal of Lever Unit | LVB. | 0 | ON | - | - | ٤ | U | b . | 0 0 | n F | ON OF | When the lever unit run signal S1 is ON, the presser foot lift signal S3 will be ignored even when received. | - |

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| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | Function name – – – – – Digital | l displ | Se | etting | Specification | Ref. page |
|---------------------|---------------|-----------------|-----------------|------|------------------|--|---------|--------|------------|---|--------------|
| R mode ↓ + | Reset RESET | x | _ | _ | _ | r E 5 | 5 E | ר | • | EEPROM data is returned to EEPROM back-up state. This function can be used when returning the function setting to the factory setting. Every time [D,==>] key is pressed for two seconds or more, the mode returns to the normal mode after copying (factory setting data) to (existing data). | - |
| ₽ + | | | | | | | | | | | |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | unction name Digit | n tal di | | Setti ay | ng ר | Specification | Ref. page |
|------------------|--|-----------------|-----------------|------|------------------|-------|--------------------------|-------------|----------|-----------------|--|--|--------------|
| | KS1,KS2 output run KSM. mode | 0 | OF | _ | _ | Ł | 5 1 | N. 0 | ס | n F | | This is the virtual output KS1 and KS2 run mode. During the one needle stitching, half-stitching (one needle stitching signal S01, needle lift signal U, half-stitching signal UD, backstitching during run signal US, backstitching during run signal UDS,etc.),The outputs KS1 and KS2 will turn ON. The KS1 and KS2 output swill turn ON only during normal operation. | |
| S mode | Simple sequence SQS. start conditions | 0 | NO | _ | - | 5 | 9 | | | | $\begin{array}{c} \downarrow & - & - \\ - & - & NC \\ T & - & - \\ - & - & - \\ - & - & - \\ + & - & - \\ + & - & - \\ + & - & - \\ + & - & - \\ + & - & - \\ + & - & - \\ - & - & - \\ + & - & - \\ - & - & - \\ - & - & - \\ - & - &$ | The simple sequence start conditions are set. The simple sequence will not start. When the input signal 14 (IN4) is ON. When the thread trimming is completed. When run starts. When the motor starts. (This includes while stopped during the one needle stitching run.) When stitching starts after thread trimming. When start tacking is completed. (If the start tacking setting is OFF, the operation will be identical to [TR].) Normal starting. | |
| + * * * | When the motor stops SQE . (This includes while stopped during the one needle stitching run.) Simple seuence end conditions | 0 | NO | - | - | 5 | 9 | ε. | | | \downarrow $\downarrow -$ \downarrow \downarrow $\downarrow -$ \downarrow \downarrow $\downarrow -$ $\downarrow -$ | The simple sequence end conditions are set. The simple sequence is not compulsorily ended. When the input signal (15) is ON. When the thread trimming is completed. When run starts. When the motor stops. (This includes while stopped during the one needle stitching run.) When stitching starts after thread trimming. When start tacking is completed. (When the start tacking setting is [OF], the operation will be identical to [TR] setting. The use is prohibited. | |
| | This is the simple NS1. sequence output KS1 output start time/output start No. of stitches setting changeover function. | 0 | OF | _ | - | n | 5 | l. 0 | | n F | | [Time] / [No. of Stitches] selection for start of KS1 output. The [Time] / No. of Stitches] can be set with the KS1 output start [Time] / [No. of Stitches] setting K11. I The KS1 output start time can be set with a No. of stitches. The KS1 output start time can be set with a No. of stitches. The KS1 output start time can be set as a time. (10 msec unit) | |
| | [Time]/[No. of Stitches] NE1. selection for KS1 output | 0 | OF | _ | - | n | ε | l. 0 | | n F | | This is the simple sequence output KS1 output time/output No. of stitches setting changeover function. The [Time] / [No. of Stitches] can be set with the KS1 output [Time] / [No. of Stitches] setting K12. I The KS1 output time can be set with a No. of stitches. The KS1 output time can be set as a time. (10 msec unit) | |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | unctior name Digi | n | displa | Settin | ng 1 1 | Specification | Ref. page |
|--------------|---|-----------------|-----------------|------|------------------|-------|-------------------------|------------|----------|------------|--------------------|---|--------------|
| | KS1 output start S1S. reference setting. | 0 | OF | - | - | 5 | 1 | 5. | | | I I I | The simple sequence output KS1 output start reference is set. The setting time can be set with the KS1 output start [Time]/[No. of stitches] setting K11. | _ |
| | | | | | | | | 4 | 0 1 | ר - ר | | Using the input signal 12 ON as a reference after the start conditions are established, the KS1 output will turn ON after the set time has passed. | |
| | | | | | | | | - | 0 1 | 5 | OF | Using the start conditions establishment as a reference, the KS1 output will turn ON after the set time has passed. | - |
| | KS1 output end S1E. | 0 | OF | - | - | 5 | 1 | E . | | | | The simple sequence output KS1 output end reference is set. The setting time can be set with the KS1 output ITimel/INo. of Stitches] setting K12. | - |
| | | | | | | | | 1 | 0 1 | ר ר | - ON | Using the input signal 12 OFF as a reference after the KS1 output turns ON, the KS1 output will turn OFF after the set time has passed. | - |
| S | | | | | | | | | 0 1 | F | OF | Using the KS1 output ON as a reference, the KS1 output will turn OFF after the set time has passed. | |
| mode | KS2 : Selection of NS2. Stitch amount and time till ON | 0 | OF | - | - | n | 5 | 2. | | | | Selection stitch amount and time till ON for simple sequence output "KS2" (Amount have to be set at "K21") | - |
| | | | | | | | | | 0 1 | n | + | Stitch amount is counted till ON | |
| | | | | | | | | | 0 1 | F | OF | Time is counted till ON (10 mill-second per each) | |
| SL | KS2 : Selection of NE2. | 0 | OF | - | - | | | | | | | Selection stitch amount and time till OFF for simple sequence output "KS2" (Amount have to be set at "K22") | _ |
| | | | | | | | | | | י | + | Stitch amount is counted till OFF | |
| ~ | | | | | | | | E | | F | - <u> </u> | Time is counted till OFF (10 mill-second pre each) | |
| | KS2 : Setting of count S2S. | 0 | OF | - | - | 5 | 2 | <u>ح</u> | <u> </u> | | | Setting start condition of counting till ON for simple sequence output "KS2". | - |
| | condition till ON | | | | | - | • | - | 0 7 | י – י | - | When Input signal "I7" become ON after the count start condition was established, counting will start. | |
| | | | | | | | | t | 0 1 | F | + OF | When the count start condition is established, counting will start. | |
| | KS2 : Setting of count S2E. | 0 | OF | - | - | 5 | ح | F | - | | 1 | Setting start condition of counting till ON for simple sequence output "KS2". | _ |
| | condition till OFF | | | | | - | - | | 0 1 | ר - ר | + | When Input signal "17" become OFF after the count start condition was established, counting will | |
| | | | | | | | | | | | 1 | start. | |
| | | | | | | | | | 0 1 | <u> </u> | + | When the count start condition is established, counting will start. | |
| | KS3 : Selection of Stitch NS3. | 0 | OF | - | - | n | 5 | 3. | | | I | Selection stitch amount and time till ON for simple sequence output "KS3" (Amount have to be set at | |
| | amount and time till ON | | | | | | | | | | · | "K21") | L |
| | | | | | | | | | 0_1 | י | ON | Stitch amount is counted till ON. | |
| | | | | | | | | | o 1 | - | OF | Time is counted till ON (10 mill-second per each) | - |
| | | | | | | | | | 0 1 | 5 | OF | When the count start condition is established, counting will start. | |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | iunctio name Di | on e gita | l disp | play | Settir | ng T | | Specification | Ref. page |
|--------------|----------------------------------|-----------------|-----------------|--------|------------------|-------|-----------------------|-----------------|--|------|------------|--|----|--|--------------|
| | KS3 : Selection of NE3. | 0 | OF | - | - | n | ε | З. | | | | 1 | | Selection stitch amount and time till OFF for simple sequence output "KS3" (Amount have to be set | - |
| | Stitch amount and time till OFF | | | | | | | | L_ | | | <u> </u> | | at "K22") | |
| | | | | | | | | | 0 | | ۱ <u> </u> | L_(| ON | Stitch amount is counted till OFF | |
| | | | | | | | | | 0 | F | | 1 | OF | Time is counted till OFF (10 mill-second per each) | - |
| | KS3 : Setting of count S3S. | 0 | OF | - | - | 5 | 3 | 5. | | | | 1 | | Setting start condition of counting till ON for simple sequence output "KS3". | - |
| | condition till ON | | | | | | | | 0 | n | | i (| ON | When Input signal "16" become ON after the count start condition was established, counting will start. | _ |
| S . | | | | | | | | | 0 | F | | T | OF | When the count start condition is established, counting will start. | _ |
| mode | KS3 : Setting of count S3E. | 0 | OF | - | - | 5 | 3 | Ε. | $\begin{bmatrix} \mathbf{o} & \mathbf{r} & \mathbf{O} \\ \mathbf{c} & \mathbf{n} \end{bmatrix} = \begin{bmatrix} \mathbf{o} & \mathbf{r} \\ \mathbf{c} & \mathbf{n} \end{bmatrix}$ | | | Setting start condition of counting till OFF for simple sequence output "K3". | - | | |
| | condition till OFF | | | | | - | - | | | | ON | When Input signal "I6" become OFF after the count start condition was established, counting will | | | |
| + | | | | | | | | | | | | i i | | start. | |
| в | | | | | | | | | o n ON Wh i sta o F OF Wh | | OF | When the count start condition is established, counting will start. | | | |
| SL | KS1 output start K11. | 0 | 7 | x10 | 0 to 99 | Ł | 1 | 1. | ** | | | 1 | ** | The output start time/output start No. of stitches for the simple sequence output KS1 can be set. | - |
| + | [Time]/[No. of stitches] setting | | | msec | | | | | | | | 1 | | When using time, the setting value will be (7) x10=70 msec. When using No. of stitches, the setting | |
| D Z | | | | stitch | | | | | | | | i | | value will be (7) x1=7 stitches. | |
| | KS1 output K12. | 0 | 7 | x10 | 0 to 99 | Ł | 1 | 2. | ** | | | 1 | ** | The output time/output start No. of stitches for the simple sequence output KS1 can be set. When | - |
| | [Time]/[No. of stitches] setting | | | msec | | | | | | | | i | | using time, the setting value will be (7) x10=70 msec. When using No. of stitches, the setting value | |
| | | | | stitch | | | | | | | | 1 | | will be (7) x1=7 stitches. | |
| | KS2 output start K21. | 0 | 7 | x10 | 0 to 99 | E | 2 | 1 | ** | | | 1 | ** | The output start time/output start No. of stitches for the simple sequence output KS2 can be set. | - |
| | [Time]/[No. of stitches] setting | | | msec | | - | - | | | | | 1 | | When using time, the setting value will be (7) x10=70 msec. When using No. of stitches, the setting | |
| | | | | stitch | | | | | | | | 1 | | value will be (7) x1=7 stitches. | |
| | KS2 output K22. | 0 | 7 | x10 | 0 to 99 | E | 2 | 2 | ** | | | 1 | ** | The output time/output start No. of stitches for the simple sequence output KS2 can be et. When | - |
| | [Time]/[No. of stitches] setting | | | msec | | | - | 2. | | | | i i | | using time, the setting value will be (7) x10=70 msec. When using No. of stitches, the setting value | |
| | | | | stitch | | | | | | | | l I | | will be (7) x1=7 stitches. | |

| Mode name | Function name | Oper ability | Factory setting | Unit | Setting range | F | unctic name Dię | on e gital | displ | Settir lay | ng T | Specification | Ref. page |
|--------------|----------------------------------|-----------------|-----------------|-------|------------------|----------|-----------------------|------------------|-------|-------------------|----------|--|--------------|
| | KS3 output start K31. | 0 | 7 | x10 | 0 to 99 | Ł | 3 | I. | ** | | ** | The output start time/output start No. of stitches for the simple sequence output KS3 can be et. | - |
| | [Time]/[No. of Stitches] setting | | | msec | | | | | | | 1 | When using time, the setting value will be $(7) \times 10=70$ msec. When using No. of stitches, the setting | |
| | KS2 output K22 | 0 | 7 | suich | 0 to 00 | | | - | ** | | + ** | Value will be (7) X1=7 suiches. | |
| | KSS output KS2. | | 1 | X10 | 0 10 99 | 5 | 3 | <i>C</i> . | | | 1 | The output time/output start no. of stitches for the simple sequence output nos can be et. when | - |
| | | | | nisec | | | | | | | 1 | using time, the setting value will be $(7) \times 10=70$ msec. When using No. of studies, the setting value will be $(7) \times 10=70$ msec. | |
| | KS1 output rup mode K1M | | | Suich | | L | , | _ | | | <u> </u> | Will be (7) X1=7 suiches. | |
| | KST output run mode KTIVI. | | ON | _ | - | C | i | 11. | | | | This is the output KST run mode for when the simple sequence start conditions [SQS] are set to NO. | |
| S | | | | | | | | - | 0 | | | The KST output is output each time the start conditions are established. | |
| mode | | | | | | . | | _ | 0 | <u>r</u> | | The KST output is output each time the start conditions are established after thread trimming. | - |
| | Run prohibit during K1D. | 0 | OF | - | - | E | i | Ø. | 0 | יי ר | | Running is prohibited while the output KS1 is ON. (This is valid only when the simple sequence start | - |
| + | KS1 output ON | | | | | | | | 0 | r | I OF | conditions [SQS] are set to NO.) | |
| В | K11,K12 time clear K1C. | 0 | OF | _ | _ | E | 1 | ٤. | 0 | n | I ON | The K11 and K12 timers will be cleared and the KS1 output will be turned OFF when the sewing | _ |
| <u> </u> | during KS1 output ON | | | | | | | | 0 | F | ¦ OF | machine stop (motor turns OFF) even when the output KS1 timer is continuing. (This is valid only | |
| + | | | | | | | | | | | i i | when the simple sequence start conditions [SQS] are set to NO.) | |
| | K21,K22 time clear K2C. | 0 | OF | - | - | Ł | 2 | ٤. | 0 | n | ON | The K21 and K22 timers will be cleared and the KS1 output will be turned OFF when the sewing | _ |
| | during KS1 output ON | | | | | | | | 0 | F | i OF | machine stop (motor turns OFF) even when the output KS2 timer is continuing. (This is valid only | |
| | | | | | | | | | | | 1 | when the simple sequence start conditions [SQS] are set to NO.) | |
| | K31,K32 time clear K3C. | 0 | OF | _ | - | Ł | 3 | ٤. | 0 | n | i ON | The K31 and K32 timers will be cleared and the KS1 output will be turned OFF when the sewing | |
| | during KS1 output ON | | | | | | | | 0 | F | OF | machine stop (motor turns OFF) even when the output KS3 timer is continuing. (This is valid only | |
| | | | | | | | | | | | i i | when the simple sequence start conditions [SQS] are set to NO.) | |
| | Increase the number KSL. | 0 | OF | - | - | Ł | 5 | Ł. | 0 | n | ON | Increase the number of K11 through K33 by ten. (ex. 10 mS=>100 mS, note: Stitch number is not | |
| | of K11 through K33 by ten | | | | | | | | 0 | F | i OF | changed.) | |
| | | | | | | | | | | | 1 | | |

| | | Note 2 | | | | | | | | | Note 1 | | | -7 |] | 1. C mode i |
|--|---|--|---|--|---|---|--|---|---|---|--|--|---|------------------|---|----------------------|
| 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | o | J | 4 | ω | 2 | <u> </u> | l o | | ndu |
| Constant angle reverse run signal | Constant angle [reverse run/forward run] signal | Constant angle [reverse run/forward run] signal | Half-stitch signal | Needle lift signal | 1 stitch signal | Thread trimmer signal | Correction stitching signal | Stop position random run signal | High speed run signal | Medium speed run signal | Variable speed run signal | Low speed run signal | Nothing signal | Setting name | | t signal setting tal |
| USR | BCR | BC | UD | U | S01 | S2 | COR | RND | S4 | S2 | S1 | SO | NO | S | | ole |
| C: | a | a | с: | U | S | S | L) | ٢ | S | S | ა | S | 2 | Dig | | |
| S | ب | ب | o' | | 0 | ν | 0 | Э | r | ഗ | ~~ | 0 | 0 | j valu ital d | | |
| ٢ | ٢ | | | | | | ٢ | ¢. | | | | | | ue lisplay | | |
| Reverse run needle lift will be performed to the set angle. The set angle can be adjusted from the DOWN position to UP position with reverse run angle K8 in the [P] mode. This is effective for blind stitch sewing machine. | The needle is stopped just above the fabric to confirm the fabric puncture position. Each time the signal is turned ON, the operation will alternate between forward-reverse-forward run. If the pedal is toed down or the external run signal (S1) turns ON after stopping at a forward run position, forward run will start after reverse run. If stopped at a reverse run position, the sewing machine will forward run form that position. The needle position stop angle C8 in the [P] mode. | The needle is stopped just above the fabric to confirm the fabric puncture position. Each time the signal turns ON, the operation will alternate between forward-reverse-forward run. If the pedal is toed down or the external run signal (S1) turns ON after that, forward run will start form that position. The needle position stop angle C8 in the [P] mode. | If input UD is turned ON, half-stitch operation will start. | If input U is turned ON, the needle lift operation will start. | If input S01 is turned ON, 1 stitch operation will start. | This signal is equivalent to full heeling when using the pedal. When S2 is ON and thread trimming or needle UP position stop has been competed, the wiper will operate. After that, the automatic presser foot lifting will function while the signal is ON. | If input COR is turned ON, correction stitching will be preformed at the speed set in low speed L. | If input RND is turned ON, the sewing machine will run at the speed set in low speed L, and when stopping the sewing machine will stop at random regardless of the needle position. | If input S4 is turned ON, the sewing machine will rum at the speed set in high speed H. | If input S5 is turned ON, the sewing machine will run at the speed set in medium speed M. | This signal is equivalent to full toe down when using the pedal. It is operated at the speed which was set with the [C, <= =][D, = =>] key of operation panel when the automatic operation AT is ON input S1 at the time of ON. | If input S0 is turned ON, the sewing machine will run at the speed set in low speed L. | The sewing machine will do nothing even if input NO is turned ON. | Specification | | Example I A. P S U |

21. INPUT/OUTPUT FUNCTION FOR SIGNAL ON C MODE SETTING

200

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9 2. The setting name will display in the ascending order with each press of the [C] key.

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| cending order with each | / in the de | lisplay | name will c | operation | ÷. | Note) |
|---|----------------------------|---------|--------------|--|-----|--------|
| If input IR2 is sewing machir | ר ת | 12 | t to | Signal outpu | 43 | |
| If input IR1 is sewing mach | ۲ | 21 | t to | Signal output virtual output operation | 42 | |
| If input I03 is | r S | 03 | t to virtual | Signal output output 3 | 41 | |
| If input I02 is | ہ ک | 02 | t to virtual | Signal output output 2 | 40 | |
| If input I01 is | 0 | 2 | t to virtual | Signal output output 1 | 39 | Note 2 |
| lf input UBI backstitchir 1 stitch ope UBR is turr | C 0 1 | IBR | ng signal L | Backstitchir when runnin | 38 | |
| If input UC backstitch 1 stitch op sewing ma | 2 (1 | | ng signal L | Backstitchir when runnin | 37 | |
| If input BS stopped, t | υ ν ~ | Š. | ng signal E | Backstitchir [when runni stopped.] | 36 | |
| If input L backstitcl Half-stitc sewing m | ر د | ى م | ng during L | Backstitchin run signal | 35 | - |
| If input L backstitc Half-stitc sewing n | 5 P 1 | | ng during L | Backstitchin run signal | 34 | |
| If input S backstitc Nothing machine | ر. د | 7 | ng during s | Backstitchin run signal | 33 | |
| If input E signal is When B time, ney | ς. Γ | | g cancel E | End tacking signal | 32 | Note 1 |
| If input S signal is When B time, ney | 6 | ŭ | g cancel S | Start tackin signal | 31 | |
| Ilf input E while the When B time, ne | ט יח רי | ٦ | cel signal E | Tacking can | 30 | |
| | ing value Digital displ | Sett | hame | Setting r | No. | |

The setting name will display in the descending order with each press of the [D] key.
 The setting name will display in the ascending order with each press of the [C] key.

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| 61 | 60 | 59 | 58 | 57 | Note 2 56 | 55 | 54 | 53 | > 52 | 51 | ◀ 50 | 49 | 48 | Note 1 | 46 | 5 | 44 | No. |
|---|---|---|---|--|--|---|---|--|--------------------------------------|--|----------------------------------|---|--|---|---|---|---|---------------------|
| Needle thread break detector input signal | Count-DOWN clear signal | Count-UP clear signal | End tacking speed run signal | Non-stitching feed | Continuous tack stitching forced [ON] signal | Preset stitching forced [ON] signal | Slow start signal | Wiper output cancel signal | Sensor input signal | Weak brake [ON] signal | 1 position priority signal | Needle cooler output during rotation forced [OFF] signal | Thread trimmer output confirmation signal | Signal output to virtual output 3 when stopped | Signal output to virtual output 2 when stopped | Signal output to virtual output 1 when stopped | Signal output to virtual output 3 during operation | Setting name |
| ΤH | CCD | CCU | S5V | FWD | CBT | z | <u>к</u> | WL | SEN | 묒 | P12 | NCL | TON | IS3 | IS2 | IS1 | IR3 | Se |
| ر | 5 | 5 | с С | ٦ ر | 5 | د | ς Γ | В | 35 | 8 | م | 2 | רי ס | ، د | , ک | د | י ר | tting v Digita |
| т - | <i>d</i> ' | רי ע | ب ب | d 0 | ر. م | | | | 5 | 17 | ح | ب م | 5 | ŝ | ĉ | | ι. | /alue al display |
| It can be used as the input signal of needle thread break detector. | If input CCD is turned ON, it clears the DOWN counter only. | If input CCU is turned ON, it clears the UP counter only. | If input S5V is turned ON, the sewing machine will run at the speed set in end tacking speed V. | If input FWD is turned ON, output OT3, output NCL and output FU will be turned ON forcibly. Output ROL and output PUL will be turned OFF forcibly. | If input CBT is turned ON, continuous backstitching will start forcibly from that point. | If input N is turned ON,preset stitching will start forcibly from that point. | If the SL signal is ON, the slow start operation will be valid. Use this with the normal mode [B,SL] key set to [OF]. | If input WL is turned ON, the wiper output W will not be output. | This is the cloth edge sensor input. | If input BK is turned ON, the weak brake will turn ON. Use this with the BK of the [D] mode set to [OF]. | 1 position will be set forcibly. | If input NCL is turned ON, the needle cooler output NCL during sewing machine rotation will forcibly by turned OFF. | The thread trimmer output T can be turned ON or OFF only when the sewing machine is stopped. ÅiThread trimmer solenoid confirmation signalÅj | If input IR3 is turned ON, output OT3 turns ON only when the sewing machine is stopped. | If input IR2 is turned ON, output OT2 turns ON only when the sewing machine is stopped. | If input IR1 is turned ON, output OT1 turns ON only when the sewing machine is stopped. | If input IR3 is turned ON, output OT3 turns ON only when the sewing machine is running. | Specification |

Note) 1. The setting name will display in the descending order with each press of the [D] key. 2. The setting name will display in the ascending order with each press of the [C] key.

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| C mode (| output | t signal setting tab | le | | < | | |
|----------|---------------|---|---------|------------|-----------|---------|---|
| | No. | Setting name | Š | | y val | ue | Specification |
| | • | • | ? | י <u>ק</u> | . jital o | display | |
| | - | Output for slow start | SL | ა | ~ | | During the no. of the setting needles, SL output is turned ON. The setting no. of needles can select SLN on [P] mode of H0Fon [G] mode by setting SLH on [F] mode |
| | 2 | Run output 1 | OP | 0 | σ | | OP output is turned ON while the sewing machine is running. (not including needle lifting during thread trimming). |
| | ω | Run output 2 | OP1 | 0 | ס | | OP1 output is turned ON while the sewing machine is running. (not including needle lifting during thread trimming). OP1 output will turn ON during needle lifting when directly heeling. |
| Note 1 | 4 | Run output 3 | OP2 | 0 | סי | ი | OP1 output is turned ON while the pedal is toed dawn, the external operation signal (S0, S1, SH), full pedal heelimg or thread trimming signal (S2) is ON. |
| | σı | Output for run signal | S1 | S | | | S1 output is turned ON when the run signal is ON except during on 1 stitch sewing. |
| | 6 | Output for blower | VAC | C | 30 | ں | VAC output is turned ON during pedal full heeling or while thread trimmer signal S2 is ON. |
| | 7 | Output for needle cooler | NCL | د | U | ~ | NCL output is turned ON while the sewing machine is running (including needle lifting). |
| - | 8 | Output for vacuum signal | VCM | C | L) | 5 | VCM output is turned ON during pedal full heeling or while thread trimmer signal S2 is ON while the sewing machine is stopped. |
| | 9 | Output for signal during tacking | BT | o | ٦ | | BT output is turned ON during tacking. |
| | 10 | Roller lift output | ROL | ٢ | 0 | ~ | ROL output is turned ON when presser foot lifter output FU is ON, backstitching output B is ON, or when input IO2 signal is ON. ROL output is turned ON while tacking and while thread trimming if RLM of [F] mode is ON. |
| | 11 | Thread trimmer output | Η | ٦ | | | Thread trimming starts. |
| | 12 | Thread release output | Г | ~ | | | Thread release operation starts. |
| | 13 | Wiper output | X | α | | | Wiper operation starts. |
| | 14 | Backstitch output (Condensed stitch) | B | ç | | | Backstitching (reverse feed) starts. (Condensed stitch) |
| Z ADN | 15 | [CH2] output | сн | L) | x | | CH2 Output for chain stitches. |
| | 16 | [TF] output | Τ̈́ | ٦ | 'n | | TF output for chain stirches. Refer to "Output TB, TF timings". |
| | 17 | [KS1] output | KS1 | Ŷ | ა | | Behind operation signal ON, KS1 output is turned ON after the setting delay time. Refer to "Output KS1,KS2,KS3 timings". |
| | 18 | [KS2] output | KS2 | ŝ | S | \sim | After the motor stopped, KS1 output is turned ON after the setting delay time. Refer to "Output KS1, KS2, KS3 timings". |
| | 19 | [KS3] output | KS3 | ĥ | S | Ś | After trimming and stopped up position, KS3 output is turned ON after setting delay time. Refer to "Output KS1,KS2,KS3 timings". |
| | 20 | [TB] output | TB | ٦ | S | | TB Output for chain stitches. Refer to "Output TB, TF timings". |
| Note) | .` | The setting name will | l displ | ay i | n th | e desc | ending order with each press of the [D] key. |

2. The setting name will display in the ascending order with each press of the [C] key.

| 39 | 38 | 37 | 36 | 35 | Note 2 34 | 33 | 32 | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 Note 1 | 22 | 21 | No. |
|---|---|--------------------|--|---|---|---|--|--------------|--------------|--|--|---|---|---|--|--|---|--|----------------------|
| [CDE] output | [CUE] output | [NO] output | Always ON output | Vacuum output for holding thread | Thread break detector output | Count up output | Puller output | [A02] output | [A01] output | Output for power [OFF] confirmation | Output for error occurrence confirmation | Virtual output3 | Virtual output2 | Virtual output 1 | Needle DOWN position output | Needle UP position output | Output for UP position when stopped | Presser foot lifter output | Setting name |
| CDE | CUE | NO | H | FUW | THO | CUP | PUL | AO2 | AO1 | IPE | ERR | OT3 | OT2 | OT1 | DNW | UPW | UC | FU | Se |
| L) | L) | د | x | ٦ | ٦ | L) | ď | Ю | Ю | | Ĵ | 0 | 0 | 0 | Ø, | C: | C: | ٦ |)tting Digi |
| e G | υE | 0 | • | U B | н 0 | U P | <i>ט</i> נ | 。 へ | 0 / | مر ر | ר ר | E J | ר ג | | 2 Q | 9 2 | L) | c | value tal display |
| This output becomes ON when Down-counter becomes end. This output becomes OFF when "CCL" input is turned on. | This output becomes ON when Up-counter becomes end. This output becomes OFF when "CCL" input is turned on. | Nothing is output. | In case of the power on, [HI] output is always ON. | FUW output is turned ON during the presser foot lifter operation or during wiper operation. | When detecting thread break detector, THO output is turned ON (When re-operation, the signal is turned off) | When +1 up counter does, the [CUP] output is turned on. | PUL output is turned ON during the presser foot lifter operation, during the IO2 output is ON. | Not used | Not used | When power is turned OFF, IPF output is turned ON. (Not used) | This is output when an error occurs. (Note that this is not output when error code E9 occurs.) | OT3 output is turned ON according to each input specifications while inputs IO3,IR3 and IS1 are ON. | OT2 output is turned ON according to each input specifications while inputs IO2,IR2 and IS1 are ON. | OT1 output is turned ON according to each input specifications while inputs IO1,IR1 and IS1 are ON. | DNW output is turned ON if at the DOWN position when the, sewing machine is stopped, and while moving from the DOWN position to the UP position when the sewing, machine is running. | UPW output is turned ON if at the UP position when the, sewing machine is stopped, and while moving from the UP position to the DOWN position when the sewing, machine is running. | UC output is turned ON if at the needle UP position when the sewing machine is stopped. | Presser foot lifter operation starts. The operation mode set in the [P] mode FUM function and FU function will be entered. | Specification |

2. The setting name will display in the ascending order with each press of the [C] key.

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1. Input and output customization



22. THE COMPOSITION FIGURE OF INPUT AND OUTPUT CUSTOMIZATION

2. Input/output direct coupling port (inside connecting port)



* The factory settings of the input function settings [IJ], [IK], [IO] and [IL], [IM], [IN] are all [NO].

* The factory settings of the output function settings [OJ], [OK], [OIO] are all [NO].

* The input function settings [IL], [IM], [IN] must not be used with the default setting [NO].

3. Connector input/output common port



* The CP output is enabled with the CPK [OF] setting in the C mode.

 * The division rate can be with the division rate setting [CP] in the [C] mode.

(When the setting has been changed, turn the power OFF and ON once.)

Note) Option B connector input/output common port

When changing the input/output, set the output side to [NO] to use the port for inputs and set the input side to [NO] to use the port for outputs. The default settings are all [NO].

(For example, if the option B connector No.2 pin is to be set to input, set the OUT4, or [O4] function to [NO], and set the required input function in IN4, or [I4] function.) The above input/output common port is connected internally, so if a function other than [NO] is set on both the input side and output side, the output side setting will affect the input side.

23. HOW TO USE THE OPTION CONNECTOR

switch for minute current. Variable operation are possible by adding external signals to the option connector. A current of approximately 1.5mA flows through the switches used for the input signal, so please use

1) Connector layout





Foot lifter

Lever connector (white)









Operation panel/Communication

<u>No</u>.

Signal name

Remarks

RXD

ດ ຫ 4 ω

+12V

TXD 2

| Physics input port name Setting function I IG 0V 1 IG Run signal S1 IH Thread trimming signal S2 II Presser foot lifter signal S3 VC Variable speed signal VC +12V +12V I | 6 | ъ | 4 | ω | Ν | <u> </u> | No. |
|---|------|-----------------------|----------------------------|------------------------|------------|----------|-------------------------|
| Setting function I OV S1 Run signal S1 Thread trimming signal S2 Presser foot lifter signal S3 Variable speed signal VC +12V Variable signal | | VC | = | Ŧ | IG | | Physics input port name |
| <pre><</pre> < S | +12V | Variable speed signal | Presser foot lifter signal | Thread trimming signal | Run signal | VO | Setting function |
| | | КС | S3 | S2 | S1 | | |
| Remarks | | | | | | | Remarks |

Encoder

| | | 1 | | ი |
|---------|----|------------------|-------------------------|-----|
| | | Ground | | თ |
| | | +12V | | 4 |
| | EB | Phase B signal | | ω |
| | ΕA | Phase A signal | | 2 |
| | | VO | | - |
| Remarks | | Setting function | Physics input port name | No. |

Detector

| No. | Physics input port name | Setting function | | Remarks |
|----------|-------------------------|-------------------------|----|---------|
| 1 | | VO | | |
| 2 | | - | | |
| ω | | Ground | | |
| 4 | | UP position detection | UP | |
| თ | | DOWN position detection | DN | |
| о | | +12V | | |

Presser foot lifter

| 2 | - | No. | |
|----------------------------|----------------------------|-------------------------|--|
| OF | OF | Physics input port name | |
| Presser foot lifter output | Presser foot lifter output | Setting function | |
| FU+ | FŪ- | | |
| | | Remarks | |

Sewing machine

| 14 | 13 | 12 | 11 | 10 | 9 | 8 | | 7 | | 6 | | 5 | | 4 | | ω | 2 | | - | | No. |
|------|------|----|----|--------|------|------|---------------|-----------------|--------|----------------|---------------|----------------|--------|---------------------|-------------------|----------------|--------------|--------|----------------|-----------------------------|----------------------|
| | | | | | | | | 0D | | ос С | | E | | ΙF | | D | OB | | OA | port name | Physics input |
| +24V | +24V | OV | OV | Ground | +24V | +24V | | Sub-back output | output | Backstitching | signal | Backstitching | signal | Presser foot lifter | cancel signal | Thread trimmer | Wiper output | output | Thread trimmer | (A, C, D, E, F, G, H, I, J, | Setting function |
| | | | | | | | | Г | | Φ | | S2 | | ч | | Ħ | ≲ | | Ч | 0 | |
| +24V | +24V | OV | VO | Ground | +24V | +24V | | Sub-back output | output | Backstitching | signal | Backstitching | signal | Presser foot lifter | cancel signal | Thread trimmer | Wiper output | output | Thread trimmer | | Setting function (E |
| | | | | | | | | Г | | Φ | | S7 | | F | | \subset | ≶ | | Ч | | ື |
| +24V | +24V | OV | OV | Ground | +24V | +24V | remove output | Lower thread | output | Needle cooler | cancel signal | Thread trimmer | signal | Presser foot lifter | protection signal | Thread trimmer | Wiper output | output | Thread trimmer | | Setting function (K, |
| | | | | | | | | SL | | p | | Ч | | F | | 9S | ≲ | | ⊣ | | ₹ |
| +24V | +24V | OV | VO | Ground | +24V | +24V | output | Thread trimmer | output | .Needle cooler | cancel signal | Thread trimmer | signal | Presser foot lifter | protection signal | Thread trimmer | Wiper output | output | Thread trimmer | | Setting function (|
| | | | | | | | | ч | | ğ | | Ę | | ч | | SS | ≶ | | ч | | 디 |
| +24V | +24V | VO | VO | Ground | +24V | +24V | output | Thread release | output | Needle cooler | cancel signal | Thread trimmer | signal | Presser foot lifter | protection signal | Thread trimmer | Wiper output | output | Thread trimmer | | Setting function (N |
| | | | | | | | | г | | p | | Ę | | п | | S | ≶ | | Ч | | _ |
| | | | | | | | | | | | | | | | | | | | | | Remarks |

under the setting functions.) (Make sure of the simple selecting table for the sewing machine heads, 9-3) Program modes [1] and [2], and the marks described Functions set to the sewing machine connectors vary in accordance with the sewing machine heads selected.

| 1 | VO | | VO | | VO | | VO | | VO | |
|-----------------------------|--------------------------------|-----|---------------------------------|--------------|---------------------------------|------|---------------------------------|-----|----------|-----------------------------|
| 2 IA | Needle UP position priority | PSU | 105 input siganl | 1 <u>0</u> 5 | Thread trimmer safe signal | 3S | Emergency stop signal | ES | Z | leedle UP position priority |
| | stop signal | | | | | | | | Ś | top signal |
| ω | +12V | | +12V | | +12V | | +12V | | + | 12V |
| 4 IB | Needle DOWN position | PSD | Needle DOWN position | PSE | Needle DOWN position | PSD | Needle DOWN position | PSD | z | eedle DOWN position |
| | priority stop signal | | priority stop signal | | priority stop signal | | priority stop signal | | σ | riority stop position |
| J | Needle UP position output | CKU | Needle UP position output | CKC | Needle UP position output | CKU | Needle UP position output | CKU | z | eedle UP position output |
| 6 IC | Low speed run signal | SO | Low speed run signal | so | Low speed run signal | so | Low speed run signal | so | ≌. ⊣ | hread trimmer protection |
| Connector G (Option B) | | | | | | | | | | |
| No. Physics input port name | e Setting function (A) | | Setting function (B) | | Setting function (C) | | Setting function (D) | | | Setting function (E) |
| 1 | VO | | A0 | | VO | | VO | | ٨0 | |
| 2 O4/I4 | 1 | | — | | Medium speed signal | SPM | Medium speed signal | SPM | р | 1 output |
| 3 01 | OT1 output | OT1 | OT1 output | OT1 | OT1 output | OT1 | OT1 output | OT1 | 9 | 5 output |
| 4 VC2 | Variable speed command | б | Variable speed command | Ś | Variable speed command | Ś | Variable speed command | Ś | Va | riable speed command |
| 5 O5/I5 | 1 | | - | | End tacking speed signal | SPB | End tacking speed signal | SPB | Thr | ead trimmer output |
| 6 11 | I01 input signal | ō | 101 input signal | ō | I01 input signal | ō | 101 input signal | ō | <u>0</u> | input signal |
| 7 | +12V | | +12V | | +12V | | +12V | | + | 2V |
| 8 | +24V | | +24V | | +24V | | +24V | | +24 | N |
| 9 12 | Needle lift signal | C | Needle lift signal | C | I01 input signal | ō | Needle lift signal | C | Nee | edle lift signal |
| 10 | OV | | OV | | VO | | VO | | VO | |
| 11 | +24V | | +24V | | +24V | | +24V | | +24\ | |
| 12 02 | Needle cooler output | NCL | Needle cooler output | NCL | Needle cooler output | NCL | Needle cooler output | NCL | OT4 | output |
| 13 O7/I7 | I | | Start/end tacking cancel signal | BTL | Start/end tacking cancel signal | BTL | I | | KS1 | output |
| 14 CP/O6/I6 | Presser foot lifter signal | т | Presser foot lifter signal | п | Presser foot lifter signal | п | Presser foot lifter signal | п | 1 | |
| 15 03 | TF output | Ŧ | TF output | Ŧ | TF output | Ŧ | TF output | Ŧ | OTO | 3 output |
| No. Physics input port name | e Setting function (F, H, I, C | 9 | Setting function (G) | | Setting function (J) | | Setting function (K, L, N | ٢ | | Setting function (M) |
| 1 | VO | | VO | | VO | | VO | | 70 | |
| 2 04/14 | 1 | | OT1 output | OT1 | Constant angle signal | BC | Needle cooler prohibit signal | NCL | Nee | dle cooler prohibit signal |
| 3 01 | OT1 output | OT1 | OT1 output | OT1 | KS1 output | KS1 | OT1 output | OT1 | 9 | 1 output (Folder) |
| 4 VC2 | Variable speed command | న | Variable speed command | S | Variable speed command | న | Variable speed command | 6 | Vari | able speed command |
| 5 O5/I5 | I | | I | | 1 | | Reset signal | KS3 | Res | et signal |
| 6 11 | I01 input signal | ō | I01 input signal | ō | I01 input signal | ō | Short stitch cancel signal | B | Sho | rt stitch cancel signal |
| 7 | +12V | | +12V | | +12V | | +12V | | +12 | < |
| 8 | +24V | | +24V | | +24V | | +24V | | +24 | × |
| 9 12 | Needle lift signal | C | Needle lift signal | C | Needle lift signal | C | Folder input signal | 101 | Folc | der input signal |
| 10 | VO | | A0 | | VO | | VO | | ۸O | |
| 11 | +24V | | +24V | | +24V | | +24V | | +24\ | |
| 12 02 | Needle cooler output | NCL | OT3 output | OT3 | Needle cooler output | NOL | Roller lift output | ROL | Shor | t stitch output |
| 13 O7/I7 | 1 | | I | | 1 | | Thread trimmer knife out signal | TON | Threa | d trimmer knife out signal |
| 14 CP/O6/I6 | 1 | | — | | 1 | | Non-stitching feed signal | FWD | NIN | -stitching feed signal |
| 5U 21 | TF output | ΤF | OT2 output | OT2 | | I TE | Non otitobing food output | DT3 | N. | n-stitching feed output |

Connector E (Option A : Black) No. Physics input port name Setting function (A, B, C, D, F, I, O) 0V

Setting function (E)

Setting function (G, H)

Setting function (J)

Setting function (K, L, M, N)

Remarks

2)The explanation of the input/output signal

| Presser foot lif | ter | | | | Sev | wing | g m | ach | ine o | conn | ecto | or | | | | | | | | | | | | | | Lev | er c | onn | ecto | or | | | | | | | | | Coni | nect | or |
|--|--|--|--------------------|------------------------------------|---|---|--|----------------------------------|---------------------|--|---|---|--|---|---|-------------------------|-------------------------|-----------------------------------|---|---|--|--|------------------------------|--|---|------------|---|---------------------------------------|---|--|--|--------|--|-----|--|--|--|---|--------|-------------------|----------------------------|
| - | 2 | 4 | c | מ | | | ъ | 7 | | | | | | c | . در | <u> </u> | 2 | | 9 | | | ъ | | | 4 | | | | | | | | ω | | | | | N | | | Pin number |
| | Presser foot lifter output | Presser foot lifter signal | (Condensed stitch) | Dackstitching output | , | run signal | Backstitching durin | Thread release output | | | | | | rancel signal | Thread trimmer | Thread trimmer output | Wiper output | power supply +12 V | Constant voltage | | command voltage | Variable speed | | | Presser foot lifter signal | | | | | | | | Thread trimmer signal | | | | | Variable speed run signal | | (Factory setting) | The innut/output signal na |
| Ę | FU+ | П | τ | a | | | S7 | Г | | | | | | ŗ | ⊒ . | | × | | | | | S | | | S3 | | | | | | | | S2 | | | | | S | | | me |
| | OF | Ŧī | 0 | 3 | | | IE | OD | | | | | | ā | <u></u> | OA | OB | | | | | ŚĊ | | | = | | | | | | | | Ŧ | | | | | Ð | - | port name | Physics input |
| | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | SC-380 | name | Model |
| set in the [P] mode FUM function and FU function will be entered. | Presser foot lifter operation starts. The operation mode | If input F is turned ON, the presser foot lifter operation will start. | (Condensed stitch) | Backetitching (rayang fand) starts | will happen if input S7 is turned ON while the sewing | running, backstitching (reverse feed) will start. Nothing | If input S7 is turned ON while the sewing machine is | Thread release operation starts. | prohibited at once. | and TLS setting is ON, next thread trimming is | When TL of [D] mode signal is turned ON a little time | presser foot lifting operation will start | After the thread trimmer interlock time passes the | N while input TI is ON the thread will not be trimmed | If nedal fill beeling or thread trimmer signal S2 is turned | Thread trimming starts. | Wiper operation starts. | A DC12 V (max. 40 mA) is out put. | This is the power for the variable speed command. | which is proportional to the voltage is gotten. | variable speed command voltage (0-11 V), the speed | It is speed regulation input from outside. By giving | the [P] mode of the 74 page. | will lift after delay time. The delay time is set by S3D | If input S3 is turned ON before triming, the presser foot | will lift. | If input S3 is turned ON after trimming, the presser foot | will function while the signal is ON. | operate. After that, the automatic presser foot lifting | position stop has been completed, the wiper will | When S2 is ON and thread trimming or needle UP | pedal. | This signal is equivalent to full heeling when using the | ON. | automatic operation AT is ON input S1 at the time of | with the [C][D]key of operation panel when the | the pedal. It is operated at the speed which was set | This signal is equivalent to full the down when using | | | The snecification |

| | | | | Opti | on B conn | ector | | | | | | | C | ption A connecto | r | | Connector |
|---|---|---|---|--|--|---|---|--|---|--|---|---|--|---|--|---|---|
| 15 | 14 | 13 | 12 | 9 | 7 | 6 | СЛ | 4 | ы | N | ა | o | თ | 4 | ω | Ν | Pin number |
| [TF] output | The signal which does nothing | The signal which does nothing | Output for needle cooler | Needle lift signal | Rated voltage poser | Signal output to virtual output 1 | The signal which does nothing | Virtual speed command | Virtual output 1 | I ne signal which does nothing | The signal which | Low speed run signal | Needle UP position output | Needle DOWN position priority stop signal | Constant voltage power supply | Needle UP position priority stop signal | The input/output signal na (Factory setting) |
| | т | R | NCL | C | +12 V | ō | R | VC2 | OT1 | Z | 5 | SO | CKU | PSD | +12 V | PSU | ame |
| 03 | 16/06/CP | 17/07 | 02 | 12 | | - | 15/05 | VC2 | 01 | O4/14 | | IC/CKD | | Ξ | | A | Physics input port name |
| | | | | | | | | | | | | | | | | | Model name SC-380 |
| TF output for chain stitches. Refer to pages 55 and 109 for the output timing. | If input F is turned ON, the presser foot lifter operation will start. * Same function as that of No. 4 pin of sewing machine connector. | It is an also input/output serving port. When using as the input, make O7 NO setting, and when using as the output, make I7 NO setting. | NCL output is turned ON while the sewing machine is running (including needle lifting). | If input U is turned ON, the needle lift operation will start. | A DC 12 V is output (max.50 mA). This can be used as the power source for the photoelectric switches in the amplifier. | If input IO1 is turned ON, output OT1 will always be turned ON. | It is an also input/output serving port. When using as the input, make O5 NO setting, and when using as the output, make I5 NO setting. | This is the input for external speed command. By applying the variable speed command voltage, the speed that is relative to the voltage is obtained. | OT1 output is turned ON according to each input specifications while inputs IO1,IR1 and IS1 are ON. | It is also input/output serving port. When using as the input, make O4 NO setting, and when using as the output, make I4 NO setting. | this also input/output sopping port Whop using as the | If input S0 is turned ON, the sewing machine will run at the speed set in low speed L. (CKD is DOWN position signal output It changes by the CKK setting of 92 page C mode by S0 and CKD.) | The UP position is output. This can be used as the signal for the stitch count, etc. The output voltage is DC 12 V/5 V (max. 40 mA). The factory setting is 5 V. | If input PSD is turned ON while the sewing machine is running, the needle will stop at the DOWN position after swing PSD stitches and thread trimming. The no. of stitches after PSD input is set by PSU the [P] mode of 73 page. | The constant voltage power supply. DC +12 V (max. 40 mA) | If input PSU is turned ON while the sewing machine is running, the needle will stop at the UP position after swing PSU stitches and thread trimming. The no. of stitches after PSU input is set by PSU the [P] mode of 73 page. | The specification |

3) To use as a standing work type sewing machine.

possible. using the lever connector. However, take special care to the intrusion of noise, and use the shortest wiring The sewing machine can be used as a standing work type sewing machine with the four connections below

For the standing work, it is recommended to use JUKI PK75

- (1) When operating with an external variable resistor
- (Control panel auto and AT in [P] mode is OFF) Lever (white connector)

| | | - |
|-----------|---|---|
| V 0 | 1 | |
| Operation | ς | |

| | | c | |
|-----------------------------------|------|----------|---------------------|
| | | ת | V 21+ |
| $^{\rm J}$ resistor 10 K Ω | | | command |
|] External variable | | ъ | Variable speed |
| _ | KC v | 4 | Presser foot lifter |
| | S S | ω | Thread trimmer |
| | | 2 | Operation |
| | 2 | | |

(2) For operating with a high speed

(Control panel auto and AT in [P] mode is ON)

Lever (white connector)

| | | 6 | +12 V |
|--------------------|------------------|----|---------------------|
| | | | command |
| | | Сı | Variable speed |
| | | 4 | Presser foot lifter |
| - Run (High speed) | | ы | Thread trimmer |
| • | S S S S | 2 | Operation |
| | | - | ν 0 |

(3) When operation with high speed and inching (Control panel auto and AT in [P] mode is OFF)

(a) When using the lever connector Lever (white connector)

| Operation Thread trimmer Presser foot lifter Variable speed |
|--|
| V U V |
| |

+12 V ი

Variable speed command

сл

R

D : Equivalent to 1S953 (NEC) (VR R : 1 k\Omega 1/2W higher 30 V, IF 30 mA)

(b) When using the lever connector and option connector Option A (black connector)

Lever (white connector)

|] | σ | V 7L+ |
|----------------|----|---------------------|
| | > | |
| | | command |
| | , | |
| S3 | IJ | Variable speed |
| 0 | 4 | Presser foot lifter |
| 5 | | |
| / ⁽ | C. | Inread trimmer |
| 202 | 0 | |
| , . | Z | Operation |
| J J | ა | Opportion |
| 2 | _ | |
| | ٢ | |
| - | | |

| 6 | ი | Operation (low speed) |
|---|---|-----------------------|
| / | | |
| 0 | ы | |
| | 4 | |
| | ω | |
| | 2 | |
| | 1 | VO |

(High speed)
24. ERROR DISPLAY

When the control box detects an error, the error code is flickered on the operation panel display. Confirm the error code, and investigate with the following table.

| Error | Drnhahla nai iea | Inenantion |
|--|---|--|
| ס א ה ה גר ה ה ה | 8 A fuse in control box broken. | Replace the 8A fuse. |
| | Is the power voltage too low ? | Check the power voltage. |
| | Is the power supply capacity too small ? | Check the power supply |
| | Note) It does this display when power supply is turned OFF, but | capacity. |
| <u> </u> | Is the wire to the motor short-circuited ? | Check the motor wiring. |
| | Is the sewing machine load torque too high ? | Check the sewing machine. |
| E2 | Is the power voltage too high ? | Check the power voltage. |
| | Is the sewing machine inertia too high ? | Lengthen the deceleration time. (Refer to DC in [A] mode) |
| E3 | Is the connector to the motor encoder securely inserted ? | Check the connector insertion. |
| | Are the signals from the motor encoder correct ? | Check the encoder signals. |
| | Is the serving machine locked ? | (Refer [E] mode) Check the sewing machine |
| | Is the motor locked ? | Check the motor. |
| E4 | Is the motor connector securely inserted ? | Check the motor connector |
| | Are the signals from the motor connector correct ? | insertion. Check the motor connector |
| E6 | Is an extraordinary signal inputted ? (The signal as it repeats ON/OFF | Check the input signal. |
| | at the high frequency) Does the noise from outside enter an input signal | Removes a noise source |
| E8 | Is the position detector connector securely inserted ? | Check the detector connector |
| | | insertion. |
| | Are the signals from the detector correct ? | Check the detector UP/ |
| | | mode.) |
| E9 | Is the solenoid wiring short-circuited ? | Check the solenoid wiring. |
| | Solenoid defect (coil defect) | Replace the solenoid. |
| M5 | A error of the copy mode using the control panel. Is the control panel connector securely inserted ? | Check the connector insertion. |
| | The voltage or the type of control panel is difference. | Check the voltage and the type |
| Others | | are right. |
| The sewing does not run when | Is the lever unit connector securely inserted ? | Check the lever unit connector |
| the pedal pressed. | Are the operation signals (S1) from the lever unit broken ? | insertion. Check the lever unit signal. |
| | | (Refer S1 signal, [E] mode) |
| The sewing machine does not run at the high speed. | Is does not displayed 99 in normal mode. | Change 99 using control box [D] key. |
| | Is the variable speed voltage with the pedal toe down low ? | Check the variable speed |
| | Is the motor pulley diameter too small ? | Check the motor pulley |
| | | diameter. (Refer item 4.3) |
| The thread is not trimmed | Is the thread trimming signal (S2) from the lever unit broken? | Check signal S2, (Refer [E] |
| even with neeling. | Is the cancel thread trimmer operation S2L ON ? | mode) Set S2L to OFF. (Refer [P] |
| | | mode) |
| The presser toot litter output | is the light heeling signal (S3) or thread trimming signal (S2) from the lever unit broken ? | Check signals S2 and S3. (Refer IFI mode) |
| | Is the presser foot lift signal (F) broken ? | Check signal F |
| | | (Refer [E] mode) |
| | is the presser foot lift signal (FU) broken ? | (Refer IFI mode) |

25. SPECIFICATIONS

| | | | | | | S | C-38 | 80 | | | | | | | | Mc | otor | | | Specifi | |
|--------------------|--------------------|---------------|---------------|---------------|-----------------|----------------|---------|------------------|---------------|---------------------|----------------------------|-------------|--------------------------|-----------------|----------------|-----------------|----------------|--------------|-----------------------------------|----------|--------------------------------------|
| Weight (kg) | Altitude | Storage tempe | Ambient humic | Ambient tempe | Range of rating | Solenoid volta | | | range | Speed control | Voltage (V) | | | Model name | Rate torque (N | Rate speed (r/i | Rate output (M | Voltage (V) | Model name | cations | |
| | | rature | lity | erature | g Voltage | je | (r/min) | With motor shaft | shaft (S/min) | With sewing machine | | trimmer (V) | automatic thread | General purpose | .m) | nin) | 5 | | | | oltage and Frequency |
| Motor 8.0 kg/Cor | Under 1000 m abo | -25 °C t | 30 % tc | 5 °C to | ±10 | DC 24 | | 50 to 3,6 | | 70 to 4,000 (MA | XC-EJK : 100-110/110-120 V | | | XC-EJK-10-05 | 1.76 Nm ((| 3,000 | 550 | 100 to 120 V | XL-554-10Y | 50/60 Hz | 110 V signal phase |
| ntrol Box : 5.5 kg | ove mean sea level | to 55 °C | 0 95 % | 0.40 °C | 0% | V/30 V | | 300 r/min | | 4X 8,999) S/min | XC-EJK : 200-220/220-240 V | | JE type (XC-EJKCE-20-05) | XC-EJK-20-05 | 0.18 Kgm) |) r/min | WC | 200 to 240 V | XL-554-20Y, JE type (XL-554-20CE) | | 230 V single phase, 3-phase 50/60 Hz |

| | XC-CL-2 | Lever unit |
|-------------------|---------|---------------|
| XC-KE-01PJ | | Specification |
| Position detector | | Model |

(DC 24 V Setting)

| | Impedance | Specifications | Solenoid | | Impedance | Specifications | Solenoid |
|---------------------|-----------|------------------------|----------|--------------------------|-----------|---------------------------------|----------|
| (short time rating) | 4 or more | (back stitch output B) | 0C | (continuous time rating) | 8 or more | (Presser foot lifter output FU) | OF |
| (short time rating) | 4 or more | (Virtual output1) | 01 | (short time rating) | 4 or more | (Thread trimming output T) | OA |
| (short time rating) | 4 or more | (needle cooler output) | 02 | (short time rating) | 4 or more | (Wiper output W) | OB |
| (short time rating) | 4 or moer | (TF output TF) | 03 | (short time rating) | 4 or more | (Thread release L) | OD |

(DC 30 V Setting)

| Solenoid | OF | OA | OB | OD |
|----------------|---------------------------------|----------------------------|------------------------|---------------------|
| Specifications | (Presser foot lifter output FU) | (Thread trimming output T) | (Wiper output W) | (Thread release L) |
| Impedance | 10 or more | 5 or more | 5 or more | 5 or more |
| | (continuous time rating) | (short time rating) | (short time rating) | (short time rating) |
| Solenoid | 000 | Q | 02 | ß |
| Specifications | (back stitch output B) | (Virtual output1) | (needle cooler output) | (TF output TF) |
| Impedance | 5 or more | 5 or more | 5 or more | 5 or moer |
| | (short time rating) | (short time rating) | (short time rating) | (short time rating) |

Note)

In the brackets, it is a factory setting. The continuous time rating of "OF" output is 50 percentage of chopping duty.

<REFERENCE> TABLE OF DIGITAL DISPLAY

Table of digital display

| | | | | ••• | | | | C | C: | Digital display |
|----|---|---|------------|-----|----|---|----|---|----|-----------------|
| | | | | N | ~ | × | Ş | < | C | Numeral |
| | | | J. | | 0 | 3 | | 1 | | Digital display |
| н | S | ת | Q | Ρ | 0 | z | Σ | | × | Numeral |
| C_ | | X | C 7 | | | 0 | 11 | 0 | | Digital display |
| د | _ | т | G | п | ш | D | ဂ | ω | A | Numeral |
| | | | | | J. | | | | C) | Digital display |
| 9 | 8 | 7 | 6 | ъ | 4 | ω | 2 | - | 0 | Numeral |

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JUKI CORPORATION

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